



SAT/SMT Solving and Applications in Rewriting

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Outline

- 1. Overview**
- 2. Propositional Logic**
- 3. SAT Application: Search for Lexicographic Path Orders**
- 4. Applying SAT Solvers**
- 5. SAT Solving: DPLL and CDCL**
- 6. Further Reading**

Schedule

session 1	Monday	background: SAT solving, propositional logic, DPLL and CDCL application: search for lexicographic path orders
session 2	Tuesday	background: SMT solving, arithmetic theories, lazy approach application: search for Knuth–Bendix orders
session 3	Wednesday	background: eager approach, certification application: polynomial interpretations, max-poly certification
session 4	Friday	SAT/SMT for infeasibility and confluence, logically constraint TRSs

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Definition (Propositional Logic: Syntax)

- propositional **formulas** are built from
 - atoms** p, q, r, p_1, p_2, \dots propositional variables
 - top, bottom** \top, \perp “true” and “false”
 - negation** \neg $\neg p$ “not p ”
 - conjunction** \wedge $p \wedge q$ “ p and q ”
 - disjunction** \vee $p \vee q$ “ p or q ”
 - implication** \rightarrow $p \rightarrow q$ “if p then q ”
 - equivalence** \leftrightarrow $p \leftrightarrow q$ “ p if and only if q ”

according to **BNF grammar** $\varphi ::= p \mid \perp \mid \top \mid (\neg\varphi) \mid (\varphi \wedge \varphi) \mid (\varphi \vee \varphi) \mid (\varphi \rightarrow \varphi) \mid (\varphi \leftrightarrow \varphi)$

- notational conventions:
 - binding precedence** $\neg > \wedge > \vee > \rightarrow, \leftrightarrow$ omit outer parentheses
 - $\rightarrow, \wedge, \vee$ are **right-associative**: $p \rightarrow q \rightarrow r$ denotes $p \rightarrow (q \rightarrow r)$

Definition (Propositional Logic: Semantics)

- **valuation** (truth **assignment**) is mapping $v: \{p \mid p \text{ is atom}\} \rightarrow \{T, F\}$
- extension to formulas: **truth values**

- $v(\top) = T$

- $v(\perp) = F$

- $v(\neg\varphi) = \begin{cases} T & \text{if } v(\varphi) = F \\ F & \text{otherwise} \end{cases}$

- $v(\varphi \wedge \psi) = \begin{cases} T & \text{if } v(\varphi) = v(\psi) = T \\ F & \text{otherwise} \end{cases}$

- $v(\varphi \vee \psi) = \begin{cases} F & \text{if } v(\varphi) = v(\psi) = F \\ T & \text{otherwise} \end{cases}$

- $v(\varphi \rightarrow \psi) = \begin{cases} F & \text{if } v(\varphi) = T \text{ and } v(\psi) = F \\ T & \text{otherwise} \end{cases}$

- $v(\varphi \leftrightarrow \psi) = \begin{cases} T & \text{if } v(\varphi) = v(\psi) \\ F & \text{otherwise} \end{cases}$

Definitions

- **semantic entailment**

$$\varphi_1, \varphi_2, \dots, \varphi_n \models \psi$$

if $v(\psi) = T$ whenever $v(\varphi_1) = v(\varphi_2) = \dots = v(\varphi_n) = T$, for every valuation v

- formula φ is **valid** if $v(\varphi) = T$ for every valuation v
- formula φ is **satisfiable** if $v(\varphi) = T$ for some valuation v

Theorem

- formula φ is valid $\iff \neg\varphi$ is unsatisfiable
- validity and satisfiability are **decidable**

Satisfiability (SAT)

instance: (propositional) formula φ

question: is φ satisfiable?

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Applications of SAT

- Encode logic puzzles
- Cryptanalysis
- Bounded model checking
- ...
- Component of reasoning in more complex logics (sessions 2 and 3)
- Encode non-deterministic computations (SAT is NP complete)
- Encode problems in proof search, e.g., in context of term rewriting

Application: SAT for LPO Parameter Search

Definition (Lexicographic Path Order (LPO))

- Let \mathcal{F} be some first-order signature
- Let $p : \mathcal{F} \rightarrow \mathbb{N}$ be some precedence
- LPO is a relation on terms \succ_{LPO} (\succ for short), defined by these inference rules

$$\frac{s_i \succ t \vee s_i = t}{s = f(s_1, \dots, s_n) \succ t} \quad (\text{sub})$$

$$\frac{p(f) > p(g) \quad \forall i \in \{1, \dots, m\}. s \succ t_i}{s = f(\dots) \succ g(t_1, \dots, t_m) = t} \quad (\text{prec})$$

$$\frac{\forall j \in \{1, \dots, i-1\}. s_j = t_j \quad s_i \succ t_i \quad \forall j \in \{i+1, \dots, n\}. s \succ t_j}{s = f(s_1, \dots, s_n) \succ f(t_1, \dots, t_n) = t} \quad (\text{lex})$$

Theorem

LPO is a reduction order (stable, monotone, strongly normalizing)

Example

Consider a TRS for the Ackermann function

$$\text{ack}(0, m) \rightarrow s(m)$$

$$\text{ack}(s(n), 0) \rightarrow \text{ack}(n, s(0))$$

$$\text{ack}(s(n), s(m)) \rightarrow \text{ack}(n, \text{ack}(s(n), m))$$

assuming $p(\text{ack}) > p(s)$, all rules are decreasing w.r.t. LPO;
witness for second rule

$$\frac{\frac{n = n \text{ (sub)}}{s(n) \succ n \text{ (sub)}} \quad \frac{p(\text{ack}) > p(s) \quad \frac{0 = 0}{\text{ack}(s(n), 0) \succ 0 \text{ (sub)}}}{\text{ack}(s(n), 0) \succ s(0) \text{ (prec)}}}{\text{ack}(s(n), 0) \succ \text{ack}(n, s(0)) \text{ (lex)}}$$

A Search Problem for Termination Proving

Theorem

The following “LPO-problem” is NP-complete.

Given some TRS \mathcal{R} , is there some precedence such that $\ell \succ_{LPO} r$ for all $\ell \rightarrow r \in \mathcal{R}$?

An opportunity

Since the LPO-problem is in NP, and SAT is NP-complete, we can encode the LPO-problem to SAT

- in early times, dedicated solvers have been implemented to search for precedences
- encoding to SAT is by far simpler and also quite flexible w.r.t. extensions
- experiments revealed: due to high efficiency of modern SAT solvers, the encoding approach is faster than existing dedicated solvers
- encoding problems to SAT: **bit-blasting**

Encoding of LPO

- first consider the search for an inference tree (postpone the precedence encoding)
- given two terms s and t we construct an encoding as formula $\varphi_{s \succ t}$
- since \succ only occurs positively, soundness suffices:

satisfiability of $\varphi_{s \succ t}$ implies $s \succ t$

- $\varphi_{s \succ t}$ is a large conjunction, each conjunct is called a **constraint**
- for every $s_i \trianglelefteq s$ and $t_j \trianglelefteq t$ we use one propositional variable $\lceil s_i \succ t_j \rceil$
- add constraint $\lceil s \succ t \rceil$ to $\varphi_{s \succ t}$
- add the following constraints to $\varphi_{s \succ t}$ for all subterm pairs of s and t
 - $\lceil x \succ t_j \rceil \rightarrow \perp$
 - $\lceil f(s_1, \dots, s_n) \succ y \rceil \rightarrow \bigvee_{i \in \{1, \dots, n\}} \lceil s_i \succ y \rceil$
 - $\lceil f(s_1, \dots, s_n) \succ g(t_1, \dots, t_m) \rceil \rightarrow$
 $\bigvee_{i \in \{1, \dots, n\}} \lceil s_i \succ g(t_1, \dots, t_m) \rceil \vee \lceil p(f) > p(g) \rceil \wedge \bigwedge_{j \in \{1, \dots, m\}} \lceil f(s_1, \dots, s_n) \succ t_j \rceil$ if $f \neq g$
 - $\lceil f(s_1, \dots, s_n) \succ f(t_1, \dots, t_n) \rceil$: similar, encode (sub) or (lex)
 - remark: $\lceil s_i \succ t_j \rceil := \top$, if $s_i = t_j$, and $\lceil s_i \succ t_j \rceil := \lceil s_i \succ t_j \rceil$, otherwise

Remarks

- encoding size: $\mathcal{O}(n^3)$ with $\mathcal{O}(n^2)$ variables
- optimizations
 - sharing: if same subterm pair occurs several times, only use one atom
 - static analysis: use knowledge about LPO to reduce encoding size
 - short cuts: $\lceil f(s_1, \dots, s_n) \succ y \rceil \rightarrow \begin{cases} \top, & \text{if } y \in \mathcal{V}(f(s_1, \dots, s_n)) \\ \perp, & \text{otherwise} \end{cases}$
 - early successes: $\lceil s_i \succ t_j \rceil \rightarrow \top$ if $s_i \triangleright t_j$
 - early failures: $\lceil s_i \succ t_j \rceil \rightarrow \perp$ if $\mathcal{V}(s_i) \not\supseteq \mathcal{V}(t_j)$ or $s_i \preceq t_j$
- example on $\text{ack}(s(n), 0) \succ \text{ack}(n, s(0))$
 - $\lceil \text{ack}(s(n), 0) \succ \text{ack}(n, s(0)) \rceil \rightarrow \lceil s(n) \succ \text{ack}(n, s(0)) \rceil \vee \lceil \text{ack}(s(n), 0) \succ s(0) \rceil$
 - $\lceil s(n) \succ \text{ack}(n, s(0)) \rceil \rightarrow \lceil p(s) > p(\text{ack}) \rceil \wedge \lceil s(n) \succ s(0) \rceil$
 - $\lceil \text{ack}(s(n), 0) \succ s(0) \rceil \rightarrow \lceil p(\text{ack}) > p(s) \rceil \vee \lceil s(n) \succ s(0) \rceil$
 - $\lceil s(n) \succ s(0) \rceil \rightarrow \perp$
 - bottom-up computation: $\lceil \text{ack}(s(n), 0) \succ \text{ack}(n, s(0)) \rceil \rightarrow \lceil p(\text{ack}) > p(s) \rceil$

Encoding of Precedence

- for signature \mathcal{F} with $|\mathcal{F}| = n$ it suffices to guess $p(f) \in \{0, \dots, n-1\}$ for each $f \in \mathcal{F}$
- several possibilities
 - encode $p(f)$ as **tally sequence** in $n-1$ atoms and $\lceil p(f) > p(g) \rceil$ uses **unary comparison**
 - example for $n = 8$ and $p(f) = 3$: 0000111
 - comparison: $f_6 f_5 f_4 f_3 f_2 f_1 f_0 > g_6 g_5 g_4 g_3 g_2 g_1 g_0$ becomes $\bigvee_{i \in \{0, \dots, 6\}} f_i \wedge \neg g_i$
 - invariant: $\bigwedge_{f \in \mathcal{F}} \bigwedge_{i \in \{1, \dots, 6\}} (f_i \rightarrow f_{i-1})$
 - advantage: good structure for SAT solvers
 - disadvantage: large size
 - encode $p(f)$ in $\log(n)$ atoms and $\lceil p(f) > p(g) \rceil$ uses **binary comparison**
 - example for $n = 8$ and $p(f) = 3$: 011
 - comparison: $f_2 f_1 f_0 > g_2 g_1 g_0$ becomes $f_2 \wedge \neg g_2 \vee (g_2 \rightarrow f_2) \wedge (f_1 \wedge \neg g_1 \vee (g_1 \rightarrow f_1) \wedge f_0 \wedge \neg g_0)$
 - advantage: small size
 - disadvantage: more complex structure for SAT solving
 - use stronger logic than SAT, e.g., SMT with **arithmetic primitives** (see next sessions)
- selecting suitable encoding is often done with help of **experiments**

Summary of LPO encoding

- the search for parameters of LPO and similar orders can be encoded to SAT
- this bit-blasting approach is usually faster than dedicated solvers
- fact: many tools for (termination | confluence) analysis use SAT or SMT solvers

Exercise

- LPO on its own is quite weak for termination proving
- preprocessing term order constraints by **argument filters** greatly improves power
- an AF is a function π that maps every n -ary function symbol to some argument position, or to a subset of argument positions
- $\pi(x) = x$
- $$\pi(f(t_1, \dots, t_n)) = \begin{cases} \pi(t_i), & \text{if } \pi(f) = i \\ f([\pi(t_i) \mid i \leftarrow [1..n], i \in \pi(f)]), & \text{if } \pi(f) \text{ is a set} \end{cases}$$
- given s and t , encode whether there is some π and LPO such that $\pi(s) \succ_{LPO} \pi(t)$
- hints: (1) ; (2)

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Remark

- many SAT solvers require conjunctive normal form (CNF) as input
- CNFs have the following structure
 - a **literal** is an atom or a negated atom: $x, \neg y, \dots$
 - a **clause** is disjunction of literals: $x \vee z \vee \neg y$ or short: $\{x, z, \neg y\}$
 - a **CNF** is a conjunction of clauses

DIMACS Input Format

```
c
c comments
c
p cnf 4 3          4 atoms and 3 clauses
1 -2 4 0           $x_1 \vee \neg x_2 \vee x_4$ 
-1 2 -3 -4 0       $\neg x_1 \vee x_2 \vee \neg x_3 \vee \neg x_4$ 
3 -2 0             $x_3 \vee \neg x_2$ 
```

Accessing SAT Solvers

- look at recent SAT competitions to find solver

`https://satcompetition.github.io`

- either use DIMACS and binary of arbitrary solver
- or search for language binding, e.g.,

`https://hackage.haskell.org/package/minisat-solver-0.1/candidate/docs/SAT-MiniSat.html`

- example

```
cd [USB-stick]/ISR24_sat_smt_isr_2024
cabal install miniTT
miniTT encoding lpo  examples/ack.ari    # see basic encoding
miniTT encoding lpo2 examples/ack.ari    # see optimized encoding
miniTT txt          lpo  examples/ack.ari    # textual proof output
# inspect miniTT/src/LP0.hs miniTT/src/LP02.hs
```

Remarks

- translation from arbitrary formula to equivalent CNF is expensive
- **Tseitin's transformation** is linear-time translation to **equisatisfiable** CNF
- here: only consider formulas without \rightarrow and \leftrightarrow

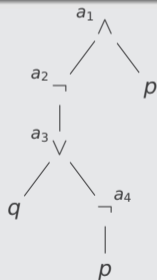
Example (Tseitin's Transformation)

- $\varphi = \neg(q \vee \neg p) \wedge p$
- introduce new variable for each propositional connective:

$$a_1 \quad \neg(q \vee \neg p) \wedge p \quad a_3 \quad q \vee \neg p$$

$$a_2 \quad \neg(q \vee \neg p) \quad a_4 \quad \neg p$$

- $\varphi \approx a_1 \wedge (a_1 \leftrightarrow a_2 \wedge p) \wedge (a_2 \leftrightarrow \neg a_3) \wedge (a_3 \leftrightarrow q \vee a_4) \wedge (a_4 \leftrightarrow \neg p)$



Lemma

- 1 $(\varphi \leftrightarrow \neg\psi) \equiv (\varphi \vee \psi) \wedge (\neg\varphi \vee \neg\psi)$
- 2 $(\varphi \leftrightarrow \psi \wedge \chi) \equiv (\neg\varphi \vee \psi) \wedge (\neg\varphi \vee \chi) \wedge (\varphi \vee \neg\psi \vee \neg\chi)$
- 3 $(\varphi \leftrightarrow \psi \vee \chi) \equiv (\varphi \vee \neg\psi) \wedge (\varphi \vee \neg\chi) \wedge (\neg\varphi \vee \psi \vee \chi)$

Example (cont'd)

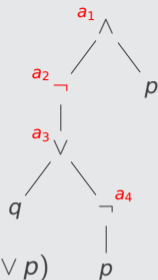
$$\begin{aligned}\varphi &\approx a_1 \wedge (a_1 \leftrightarrow a_2 \wedge p) \wedge (a_2 \leftrightarrow \neg a_3) \wedge (a_3 \leftrightarrow q \vee a_4) \wedge (a_4 \leftrightarrow \neg p) \\ &\equiv a_1 \wedge (\neg a_1 \vee a_2) \wedge (\neg a_1 \vee p) \wedge (a_1 \vee \neg a_2 \vee \neg p) \wedge (a_2 \vee a_3) \wedge (\neg a_2 \vee \neg a_3) \\ &\quad \wedge (a_3 \vee \neg q) \wedge (a_3 \vee \neg a_4) \wedge (\neg a_3 \vee q \vee a_4) \wedge (a_4 \vee p) \wedge (\neg a_4 \vee \neg p)\end{aligned}$$

Improvement (Plaisted & Greenbaum)

replace equivalence (\leftrightarrow) by implication (\rightarrow or \leftarrow) based on **polarity** of subformulas

Example (cont'd)

- $\varphi = \neg(q \vee \neg p) \wedge p$
- $\varphi \approx a_1 \wedge (a_1 \rightarrow a_2 \wedge p) \wedge (a_2 \rightarrow \neg a_3) \wedge (a_3 \leftarrow q \vee a_4) \wedge (a_4 \leftarrow \neg p)$
- $a_1 \rightarrow a_2 \wedge p \equiv (\neg a_1 \vee a_2) \wedge (\neg a_1 \vee p) \wedge (a_1 \vee \neg a_2 \vee \neg p)$
- $a_2 \rightarrow \neg a_3 \equiv (a_2 \vee a_3) \wedge (\neg a_2 \vee \neg a_3)$
- $a_3 \leftarrow q \vee a_4 \equiv (a_3 \vee \neg q) \wedge (a_3 \vee \neg a_4) \wedge (\neg a_3 \vee q \vee a_4)$
- $a_4 \leftarrow \neg p \equiv (a_4 \vee p) \wedge (\neg a_4 \vee \neg p)$
- $\varphi \approx a_1 \wedge (\neg a_1 \vee a_2) \wedge (\neg a_1 \vee p) \wedge (\neg a_2 \vee \neg a_3) \wedge (a_3 \vee \neg q) \wedge (a_3 \vee \neg a_4) \wedge (a_4 \vee p)$



replace $a \leftrightarrow \psi$ by $a \rightarrow \psi$ if ψ occurs only positively, and by $a \leftarrow \psi$ if ψ never occurs positively

Definition

subformula ψ occurs **positively** in formula φ if number of negations on path from root of φ to root of ψ in parse tree of φ is even

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Remarks

- most state-of-the-art SAT solvers are based on variations of **Davis–Putnam–Logemann–Loveland** (DPLL) procedure (1960, 1962)
- **abstract version** of DPLL described in JACM paper of Nieuwenhuis, Oliveras, Tinelli (2006)

Definition (Abstract DPLL)

- states $M \parallel F$ consist of
 - list M of (possibly annotated) non-complementary literals
 - CNF F
- transition rules

$$M \parallel F \implies M' \parallel F' \text{ or fail-state}$$

Example

$$\varphi = (\neg 1 \vee \neg 2) \wedge (2 \vee 3) \wedge (\neg 1 \vee \neg 3 \vee 4) \wedge (2 \vee \neg 3 \vee \neg 4) \wedge (1 \vee 4)$$

		\parallel	$\neg 1 \vee \neg 2, 2 \vee 3, \neg 1 \vee \neg 3 \vee 4, 2 \vee \neg 3 \vee \neg 4, 1 \vee 4$	
\Rightarrow	^d 1	\parallel	$\neg 1 \vee \neg 2, 2 \vee 3, \neg 1 \vee \neg 3 \vee 4, 2 \vee \neg 3 \vee \neg 4, 1 \vee 4$	decide
\Rightarrow	1 ^d $\neg 2$	\parallel	$\neg 1 \vee \neg 2, 2 \vee 3, \neg 1 \vee \neg 3 \vee 4, 2 \vee \neg 3 \vee \neg 4, 1 \vee 4$	unit propagate
\Rightarrow	1 ^d $\neg 2 3$	\parallel	$\neg 1 \vee \neg 2, 2 \vee 3, \neg 1 \vee \neg 3 \vee 4, 2 \vee \neg 3 \vee \neg 4, 1 \vee 4$	unit propagate
\Rightarrow	1 ^d $\neg 2 3 4$	\parallel	$\neg 1 \vee \neg 2, 2 \vee 3, \neg 1 \vee \neg 3 \vee 4, 2 \vee \neg 3 \vee \neg 4, 1 \vee 4$	unit propagate
\Rightarrow	$\neg 1$	\parallel	$\neg 1 \vee \neg 2, 2 \vee 3, \neg 1 \vee \neg 3 \vee 4, 2 \vee \neg 3 \vee \neg 4, 1 \vee 4$	backtrack
\Rightarrow	$\neg 1 4$	\parallel	$\neg 1 \vee \neg 2, 2 \vee 3, \neg 1 \vee \neg 3 \vee 4, 2 \vee \neg 3 \vee \neg 4, 1 \vee 4$	unit propagate
\Rightarrow	$\neg 1 4$ ^d $\neg 3$	\parallel	$\neg 1 \vee \neg 2, 2 \vee 3, \neg 1 \vee \neg 3 \vee 4, 2 \vee \neg 3 \vee \neg 4, 1 \vee 4$	decide
\Rightarrow	$\neg 1 4$ ^d $\neg 3 2$	\parallel	$\neg 1 \vee \neg 2, 2 \vee 3, \neg 1 \vee \neg 3 \vee 4, 2 \vee \neg 3 \vee \neg 4, 1 \vee 4$	unit propagate

Definition (Transition Rules)

- **unit propagate** $M \parallel F, C \vee I \implies M I \parallel F, C \vee I$
if $M \models \neg C$ and I is undefined in M **unit clause**
- **pure literal** $M \parallel F \implies M I \parallel F$
if I occurs in F and I^c (complement of I) does not occur in F and I is undefined in M
- **decide** $M \parallel F \implies M \overset{d}{I} \parallel F$
if I or I^c occurs in F and I is undefined in M
- **fail** $M \parallel F, C \implies \text{fail-state}$
if $M \models \neg C$ and M contains no decision literals
- **backtrack** $M \overset{d}{I} N \parallel F, C \implies M I^c \parallel F, C$
if $M \overset{d}{I} N \models \neg C$ and N contains no decision literals

Example

$$\varphi = (\neg 1 \vee 2) \wedge (\neg 3 \vee 4) \wedge (\neg 5 \vee \neg 6) \wedge (6 \vee \neg 5 \vee \neg 2)$$

		\parallel	$\neg 1 \vee 2, \neg 3 \vee 4, \neg 5 \vee \neg 6, 6 \vee \neg 5 \vee \neg 2$	
\Rightarrow	$\overset{d}{1}$	\parallel	$\neg 1 \vee 2, \neg 3 \vee 4, \neg 5 \vee \neg 6, 6 \vee \neg 5 \vee \neg 2$	decide
\Rightarrow	$\overset{d}{1} \overset{d}{2}$	\parallel	$\neg 1 \vee 2, \neg 3 \vee 4, \neg 5 \vee \neg 6, 6 \vee \neg 5 \vee \neg 2$	unit propagate
\Rightarrow	$\overset{d}{1} \overset{d}{2} \overset{d}{3}$	\parallel	$\neg 1 \vee 2, \neg 3 \vee 4, \neg 5 \vee \neg 6, 6 \vee \neg 5 \vee \neg 2$	decide
\Rightarrow	$\overset{d}{1} \overset{d}{2} \overset{d}{3} \overset{d}{4}$	\parallel	$\neg 1 \vee 2, \neg 3 \vee 4, \neg 5 \vee \neg 6, 6 \vee \neg 5 \vee \neg 2$	unit propagate
\Rightarrow	$\overset{d}{1} \overset{d}{2} \overset{d}{3} \overset{d}{4} \overset{d}{5}$	\parallel	$\neg 1 \vee 2, \neg 3 \vee 4, \neg 5 \vee \neg 6, 6 \vee \neg 5 \vee \neg 2$	decide
\Rightarrow	$\overset{d}{1} \overset{d}{2} \overset{d}{3} \overset{d}{4} \overset{d}{5} \neg 6$	\parallel	$\neg 1 \vee 2, \neg 3 \vee 4, \neg 5 \vee \neg 6, 6 \vee \neg 5 \vee \neg 2$	unit propagate
\Rightarrow	$\overset{d}{1} \overset{d}{2} \neg 5$	\parallel	$\neg 1 \vee 2, \neg 3 \vee 4, \neg 5 \vee \neg 6, 6 \vee \neg 5 \vee \neg 2$	backjump

conflict is due to $\overset{d}{1} \overset{d}{2}$ and $\overset{d}{5} \neg 6$ hence $\neg 1 \vee \neg 5$ can be inferred

Definitions

- **backtrack** $M \overset{d}{I} N \parallel F, C \implies M I^c \parallel F, C$
if $M \overset{d}{I} N \models \neg C$ and N contains no decision literals
- **backjump** $M \overset{d}{I} N \parallel F, C \implies M I' \parallel F, C$
if $M \overset{d}{I} N \models \neg C$ and \exists clause $C' \vee I'$ such that
 - $F, C \models C' \vee I'$ **backjump clause**
 - $M \models \neg C'$
 - I' is undefined in M
 - I' or I'^c occurs in F or in $M \overset{d}{I} N$

Example (cont'd)

$\neg 1 \vee \neg 5$ and $\neg 2 \vee \neg 5$ are backjump clauses with respect to $1 \overset{d}{2} 3 \overset{d}{4} 5 \overset{d}{6} \parallel \varphi$

Lemma

backjump can simulate backtrack

Terminology

backjump is also called **non-chronological backtracking** or **conflict-driven backtracking**

Question

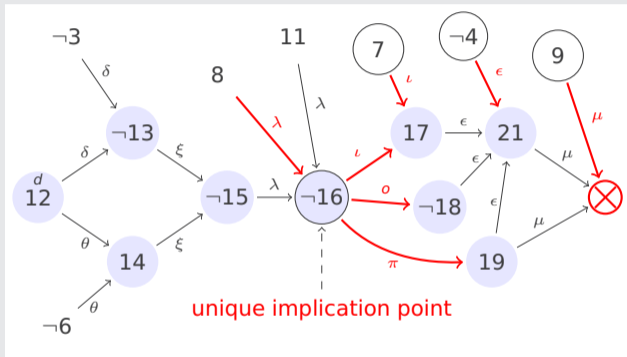
how to find good backjump clauses ?

Answer

use **conflict graph**

Example

α	1	1	$\neg 2$	$\neg 3$	$\neg 4$	5	$\neg 6$	7	8	9	$\neg 10$	11	$\neg 12$	$\neg 13$	14	$\neg 15$	$\neg 16$	17	$\neg 18$	19	20	21	
β			\vee																				
γ																							
δ																							
ϵ																							
ζ																							
η																							
θ																							
ι																							
κ																							
λ																							
μ																							
ν																							
ξ																							
\omicron																							
π																							
ρ																							



$\neg 9 \vee \neg 19 \vee \neg 21$ conflict clause (μ)

$4 \vee \neg 7 \vee \neg 9 \vee 16$ resolve with $\epsilon, \pi, \omicron, \iota$

backjump clause

Remarks

- computed clauses are clauses that correspond to **cut** in conflict graph, separating conflict node from current decision literal and literals at earlier decision levels
- not all cuts are computed in this way
- clauses corresponding to UIPs are **backjump clauses**
- UIPs always exist (last decision literal)
- backjumping with respect to last UIP amounts to backtracking
- most SAT solvers use backjump clause corresponding to 1st UIP

Observation

adding backjump clauses to clause database (**learning**) helps to prune search space

- **learn**

$$M \parallel F \implies M \parallel F, C$$

if $F \models C$ and each atom of C occurs in F or in M

Observation

restarts are useful to avoid wasting too much time in parts of search space without satisfying assignments

- restart

$$M \parallel F \implies \parallel F$$

Final Remarks

- restarts do not compromise completeness if number of steps between consecutive restarts strictly increases
- modern SAT solvers additionally incorporate
 - heuristics for selecting next decision literal
 - special data structures that allow for efficient unit propagation (two watched literals)

Outline

1. Overview
2. Propositional Logic
3. SAT Application: Search for Lexicographic Path Orders
4. Applying SAT Solvers
5. SAT Solving: DPLL and CDCL
- 6. Further Reading**

Further Reading

- David A. Plaisted and Steven Greenbaum
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- Michael Codish, Vitaly Lagoon, Peter J. Stuckey
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