

Certification of Confluence Proofs using **CeTA***

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1 Introduction

CeTA was originally developed as a tool for certifying termination proofs [5], which have to be provided as certificates in the CPF-format. Given a certificate **CeTA** will either answer **CERTIFIED**, or return a detailed error message why the proof was **REJECTED**. Its correctness is formally proven as part of **IsaFoR**, the **Isabelle Formalization of Rewriting**: **IsaFoR** contains executable “check”-functions for each formalized proof technique together with formal proofs that whenever such a check is accepted, the technique is applied correctly. Isabelle’s code-generator is then used to obtain **CeTA**.¹ By now, **CeTA** can also be used for certifying confluence and non-confluence proofs. In this system description, we give an overview on what kind of proofs are supported, and what information has to be given in the certificates. As we will see, only little information is required and so we hope that **CSI** [8] will not stay the only confluence tool that can produce certificates.

2 Terminating Term Rewrite Systems (TRSs)

It is well known that confluence of terminating TRSs is decidable by checking joinability of all critical pairs. The latter can be decided by reducing both terms of a critical pair to arbitrary normal forms and then checking if these are equal. This technique is also supported in **CeTA**, where in the certificate one just has to provide the termination proof and **CeTA** automatically constructs all critical pairs and checks their joinability by rewriting to normal forms. Alternatively one can also specify to check joinability by an automatic breadth-first search. Finally one can completely provide the joining sequences for all critical pairs in the certificate. Although the latter results in more verbose certificates, which are harder to produce, they are faster to check as no search is required for certification. For example, for $\mathcal{R} = \mathcal{R}_{\text{ack}} \cup \{f(x) \rightarrow x, a \rightarrow \text{ack}(1000, 1000), a \rightarrow f(\text{ack}(1000, 1000))\}$, where \mathcal{R}_{ack} is a convergent TRS for the Ackermann-function, all critical pairs are joinable, but rewriting to normal form won’t work.

3 Certificates for Confluence

IsaFoR contains formalizations of two techniques that ensure confluence and do not demand termination: strongly closed and linear TRSs as well as weakly orthogonal TRSs are confluent.

For the latter, the certificate only consists of the statement that the TRS is weakly orthogonal, which is a syntactic criterion that can easily be checked by **CeTA**. For the former criterion, the interesting part is to ensure that a given TRS \mathcal{R} is strongly closed, i.e., for every critical pair (s, t) there are terms u and v such that $s \rightarrow_{\mathcal{R}}^* u \overleftarrow{\mathcal{R}} t$ and $s \rightarrow_{\mathcal{R}}^* v \overleftarrow{\mathcal{R}} t$. Clearly, rewriting to normal forms is of little use here, so we just offer a breadth-first search in **CeTA**. In the certificate one just has to provide a bound on the length of the joining derivations. The reason for requiring the explicit bound is that in Isabelle all functions have to be total. In contrast to

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¹At <http://c1-informatik.uibk.ac.at/software/ceta/> one can access **CeTA**, **IsaFoR**, and the CPF-format.

Section 2, here \mathcal{R} is not necessarily terminating, and thus an unbounded breadth-first search might be non-terminating, whereas an explicit bound on the depth easily ensures totality.

At this point, let us recall our notions of TRSs and critical pairs: as usual a TRS \mathcal{R} is just a set of rewrite rules. However we do not assume the following standard variable conditions:

$$VC_{lhs}(\mathcal{R}) = \forall \ell \rightarrow r \in \mathcal{R}. \ell \notin \mathcal{V} \qquad VC_{\supseteq}(\mathcal{R}) = \forall \ell \rightarrow r \in \mathcal{R}. \mathcal{V}(\ell) \supseteq \mathcal{V}(r)$$

The critical pairs of a TRS \mathcal{R} are defined as

$$CP(\mathcal{R}) = \{(r\sigma, C[r']\sigma) \mid \ell \rightarrow r \in \mathcal{R}, \ell' \rightarrow r' \in \mathcal{R}, \ell = C[u], u \notin \mathcal{V}, mgu(u, \ell') = \sigma\}$$

where it is assumed that the variables in $\ell \rightarrow r$ and $\ell' \rightarrow r'$ have been renamed apart. We do not exclude root overlaps of a rule with itself, which gives rise to trivial critical pairs of the form $(r\sigma, r\sigma)$. Therefore, most techniques in $\mathcal{I}\mathcal{s}\mathcal{a}\mathcal{F}\mathcal{o}\mathcal{R}$ that rely on critical pairs immediately try to remove all trivial critical pairs, i.e., they consider $\{(s, t) \in CP(\mathcal{R}) \mid s \neq t\}$ instead of $CP(\mathcal{R})$. So, in practice these additional critical pairs do not play a role. However, for TRSs that do not satisfy the variable conditions they are essential. For example, for the TRS $\mathcal{R}_1 = \{\mathbf{a} \rightarrow y\}$ over signature $\{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$ we have $CP(\mathcal{R}) = \{(x, y)\}$, whereas without root-overlaps with the same rule there would be no critical pair and we might wrongly conclude confluence via orthogonality.

The confluence criterion of weak orthogonality not only implicitly demands $VC_{\supseteq}(\mathcal{R})$, but explicitly demands $VC_{lhs}(\mathcal{R})$. In contrast, none of the variable conditions is required for strongly closed and linear TRSs. Hence, the following two TRSs are confluent via this criterion: $\mathcal{R}_2 = \{x \rightarrow f(x), y \rightarrow g(y)\}$ is strongly closed as there are no critical pairs, and $\mathcal{R}_3 = \{\mathbf{a} \rightarrow f(x), f(x) \rightarrow \mathbf{b}\}$ is strongly closed as the only non-trivial critical pair is $(f(x), f(y))$, which is obviously joinable in one step to \mathbf{b} . Also $\mathcal{R}_4 = \{\mathbf{a} \rightarrow f(x), f(x) \rightarrow \mathbf{b}, x \rightarrow f(g(x))\}$ —which satisfies neither of the variable conditions—is strongly closed and linear, and thus confluent. Similarly as for weak orthogonality, the addition of root overlaps w.r.t. the same rule is essential, as otherwise the non-confluent and linear TRS \mathcal{R}_1 would be strongly closed.

4 Disproving Confluence via Non-Joinable Forks

One way to disprove confluence of an arbitrary, possibly non-terminating TRS \mathcal{R} is to provide a non-joinable fork, i.e., $s \rightarrow_{\mathcal{R}}^* t_1$ and $s \rightarrow_{\mathcal{R}}^* t_2$ such that t_1 and t_2 have no common reduct. To certify these proofs, in $\mathcal{C}\mathcal{e}\mathcal{A}$ we demand the concrete derivations from s to t_1 and t_2 and additionally a certificate that t_1 and t_2 are not joinable, which is clearly the more interesting part. To this end, we generalize the notion of non-joinability to two TRSs, which allows us to conveniently and modularly formalize several existing techniques for non-joinability. Initially, $\mathcal{R}_1 = \mathcal{R}_2 = \mathcal{R}$ and any change on one of the TRSs is currently internally computed by $\mathcal{C}\mathcal{e}\mathcal{A}$.

$$NJ_{\mathcal{R}_1, \mathcal{R}_2}(t_1, t_2) = (\neg \exists u. t_1 \rightarrow_{\mathcal{R}_1}^* u \wedge t_2 \rightarrow_{\mathcal{R}_2}^* u)$$

4.1 Grounding

Clearly, $NJ_{\mathcal{R}_1, \mathcal{R}_2}(t_1\sigma, t_2\sigma)$ implies $NJ_{\mathcal{R}_1, \mathcal{R}_2}(t_1, t_2)$ for some arbitrary substitution σ . This substitution has to be provided in the certificate and can be used to replace each variable in t_1 and t_2 by some fresh constant. Grounding can be beneficial for other non-joinability techniques.

4.2 Tcap and Unification

The function $tcap_{\mathcal{R}}$ can approximate an upper part of a term where no rewriting with \mathcal{R} is possible, and thus, remains unchanged by rewriting. Hence, it suffices to check that $tcap_{\mathcal{R}_1}(t_1)$

is not unifiable with $tcap_{\mathcal{R}_2}(t_2)$ to ensure $NJ_{\mathcal{R}_1, \mathcal{R}_2}(t_1, t_2)$.

Since $tcap_{\mathcal{R}_i}$ replaces variables by fresh ones, it is beneficial to apply grounding beforehand [8]. To this end, **CeTA** computes a suitable grounding substitution, if some t_i is not a ground term. Because of grounding, this criterion fully subsumes the criterion, that two different normal forms are not joinable. Nevertheless one can also refer to the latter criterion in certificates.

4.3 Usable Rules for Reachability

In [1] the usable rules for reachability \mathcal{U}_r have been defined (via some inductive definition of auxiliary usable rules \mathcal{U}_0). They have the crucial property that $t \rightarrow_{\mathcal{R}}^* s$ implies $t \rightarrow_{\mathcal{U}_r(\mathcal{R}, t)}^* s$. This property immediately shows the following theorem.

Theorem 1. $NJ_{\mathcal{U}_r(\mathcal{R}_1, t_1), \mathcal{U}_r(\mathcal{R}_2, t_2)}(t_1, t_2)$ implies $NJ_{\mathcal{R}_1, \mathcal{R}_2}(t_1, t_2)$.

Whereas the crucial property was easily formalized within **IsaFoR** following the original proof, it was actually more complicated to provide an implementation of usable rules that turns the inductive definition of \mathcal{U}_0 into executable code. Note that we did not have this problem in previous work on usable rules [3] where we explicitly demand that the set of usable rules is provided in the certificate. However, due to our implementation of usable rules, we no longer require the set of usable rules in the certificate.

4.4 Discrimination Pairs

In [1] term orders are utilized to prove non-joinability. To be precise, (\succsim, \succ) is a discrimination pair iff \succsim is a rewrite order, \succ is irreflexive, and $\succsim \circ \succ \subseteq \succ$.² We formalized the following theorem, which in combination with Theorem 1 completely simulates [1, Theorem 12].

Theorem 2. If (\succsim, \succ) is a discrimination pair, $\mathcal{R}_1^{-1} \cup \mathcal{R}_2 \subseteq \succsim$, and $t_1 \succ t_2$ then $NJ_{\mathcal{R}_1, \mathcal{R}_2}(t_1, t_2)$.

Proof. We perform a proof by contradiction, so assume $t_1 \rightarrow_{\mathcal{R}_1}^* u$ and $t_2 \rightarrow_{\mathcal{R}_2}^* u$ and hence $t_2 \rightarrow_{\mathcal{R}_1^{-1} \cup \mathcal{R}_2}^* t_1$. Then by the preconditions we obtain $t_2 \succsim^* t_1 \succ t_2$. Iteratively applying $\succsim \circ \succ \subseteq \succ$ yields $t_2 \succ t_2$ in contradiction to irreflexivity of \succ . \square

We have also proven within **IsaFoR** that every reduction pair is a discrimination pair, and thus one can use all reduction pairs that are available in **CeTA** in the certificate.

4.5 Argument Filters

In [1] it is shown that argument filters π are useful for non-confluence proofs. The essence is

Observation 3. $NJ_{\pi(\mathcal{R}_1), \pi(\mathcal{R}_2)}(\pi(t_1), \pi(t_2))$ implies $NJ_{\mathcal{R}_1, \mathcal{R}_2}(t_1, t_2)$.

Consequently, one may show non-joinability by applying an argument filter and then continue on the filtered problem. At this point we can completely simulate [1, Theorem 14]: apply usable rules, apply argument filter, apply usable rules, apply discrimination pair.

4.6 Interpretations

Let \mathcal{F} be some signature. Let \mathcal{A} be a weakly monotone \mathcal{F} -algebra $(A, (f^A)_{f \in \mathcal{F}}, \geq)$, i.e., $f^A : A^n \rightarrow A$ for each n -ary symbol $f \in \mathcal{F}$, \geq is a partial order, and for all a, b, f , $a \geq b$ implies

²Note, that unlike what is said in [1], one does not require $\succ \circ \succ \subseteq \succ$.

$f^{\mathcal{A}}(\dots, a, \dots) \geq f^{\mathcal{A}}(\dots, b, \dots)$. \mathcal{A} is a quasi-model for \mathcal{R} iff $\llbracket \ell \rrbracket_{\mathcal{A}, \alpha} \geq \llbracket r \rrbracket_{\mathcal{A}, \alpha}$ for all $\ell \rightarrow r \in \mathcal{R}$ and every valuation $\alpha : \mathcal{V} \rightarrow A$. Let α_d be some default valuation.

Theorem 4. *If \mathcal{A} is a quasi-model of $\mathcal{R}_1^{-1} \cup \mathcal{R}_2$ and $\llbracket t_2 \rrbracket_{\mathcal{A}, \alpha_d} \not\geq \llbracket t_1 \rrbracket_{\mathcal{A}, \alpha_d}$ then $NJ_{\mathcal{R}_1, \mathcal{R}_2}(t_1, t_2)$.*

Proof. Similar as for Theorem 2. Given $t_2 \xrightarrow{\mathcal{R}_1^{-1} \cup \mathcal{R}_2}^* t_1$ and the quasi-model condition we conclude $\llbracket t_2 \rrbracket_{\mathcal{A}, \alpha_d} \geq \llbracket t_1 \rrbracket_{\mathcal{A}, \alpha_d}$. This is an immediate contradiction to $\llbracket t_2 \rrbracket_{\mathcal{A}, \alpha_d} \not\geq \llbracket t_1 \rrbracket_{\mathcal{A}, \alpha_d}$. \square

This proof was easy to formalize as it could reuse the formalization of semantic labeling [4], which also includes algorithms to check the quasi-model conditions as well as a format for models in the certificate. Here, **CeTA** is currently restricted to algebras over finite domains. Moreover, the valuation α_d cannot be specified in the certificate. However, by previously applying grounding, the choice of α_d does not matter any longer.

Note that in contrast to [1, Theorem 10], we only require $\llbracket t_2 \rrbracket_{\mathcal{A}, \alpha_d} \not\geq \llbracket t_1 \rrbracket_{\mathcal{A}, \alpha_d}$ instead of $\llbracket t_2 \rrbracket_{\mathcal{A}, \alpha_d} \not\geq \llbracket t_1 \rrbracket_{\mathcal{A}, \alpha_d} \wedge \llbracket t_1 \rrbracket_{\mathcal{A}, \alpha_d} \geq \llbracket t_2 \rrbracket_{\mathcal{A}, \alpha_d}$. This has an immediate advantage, namely that we can derive [1, Corollary 6] as a consequence: instantiate \geq by equality, then weak monotonicity is always guaranteed, the quasi-model condition becomes a model condition, and $\llbracket t_2 \rrbracket_{\mathcal{A}, \alpha_d} \not\geq \llbracket t_1 \rrbracket_{\mathcal{A}, \alpha_d}$ is equivalent to $\llbracket t_1 \rrbracket_{\mathcal{A}, \alpha_d} \neq \llbracket t_2 \rrbracket_{\mathcal{A}, \alpha_d}$. Moreover, the usable rules can easily be integrated as a preprocessing step in the same way as we did for discrimination pairs.

Further note that [1, Corollary 6] can also simulate [1, Theorem 5], by just taking the quotient algebra. Therefore, by Theorems 1, 2, and 4, and Observation 3 we can now simulate all non-joinability criteria of [1] and **CeTA** can also certify all example proofs of [1].

4.7 Tree Automata

A bottom-up tree automaton \mathcal{A} is a quadruple $(\mathcal{Q}, \mathcal{F}, \Delta, \mathcal{Q}_f)$ with states \mathcal{Q} , signature \mathcal{F} , transitions Δ , and final states \mathcal{Q}_f , and $\mathcal{L}(\mathcal{A}) \subseteq \mathcal{T}(\mathcal{F})$ denotes the accepted regular tree language. We say that \mathcal{A} is closed under \mathcal{R} if $\{t \mid s \in \mathcal{L}(\mathcal{A}), s \rightarrow_{\mathcal{R}} t\} \subseteq \mathcal{L}(\mathcal{A})$.

Observation 5. *Let \mathcal{A}_1 and \mathcal{A}_2 be tree automata. If $t_i \in \mathcal{L}(\mathcal{A}_i)$ and \mathcal{A}_i is closed under \mathcal{R}_i for $i = 1, 2$, and $\mathcal{L}(\mathcal{A}_1) \cap \mathcal{L}(\mathcal{A}_2) = \emptyset$ then $NJ_{\mathcal{R}_1, \mathcal{R}_2}(t_1, t_2)$.*

For checking these non-joinability certificates, **CeTA** implemented standard tree automata algorithms for membership, intersection, and emptiness. The most difficult part is checking whether \mathcal{A} is closed under \mathcal{R} for some \mathcal{A} and \mathcal{R} . Here, **CeTA** provides three alternatives. One can refer to Genet’s criterion of compatibility, or use the more liberal condition of state-compatibility [2], which requires an additional compatibility relation in the certificate, or one can just refer to the decision procedure [2], which currently requires a deterministic automaton as input. Since all of the conditions have been formalized under the condition $VC_{\supseteq}(\mathcal{R})$, Observation 5 can only be applied if both TRSs satisfy this variable condition. Moreover, grounding is an essential preprocessing step, since tree automata only accept ground terms.

Example 6. *Let $\mathcal{R}_5 = \{a \rightarrow b_1, a \rightarrow b_2, x \rightarrow f(x)\}$. Non-confluence can easily be shown since the critical pair (b_1, b_2) is not joinable: Take the automata $\mathcal{A}_i = (\{1\}, \mathcal{F}, \{f(1) \rightarrow 1, b_i \rightarrow 1\}, \{1\})$, which satisfy all conditions of Observation 5.*

5 Modularity of Confluence

In [6] it was proven that confluence is a modular property for disjoint unions of TRSs. Whereas a certificate for applying this proof technique is trivial by just providing the decomposition, we cannot certify these proofs, since currently a formalization of this modularity result is missing.

However, we at least formalized the easy direction of the modularity theorem that non-confluence of one of the TRSs implies non-confluence of the disjoint union, and we can thus certify non-confluence proofs in a modular way. We base our certifier on the following theorem. Here, we assume an infinite set of symbols³ and finite signatures $\mathcal{F}(\mathcal{R})$ and $\mathcal{F}(\mathcal{S})$ of the TRSs.

Theorem 7. *Let $\mathcal{F}(\mathcal{R}) \cap \mathcal{F}(\mathcal{S}) = \emptyset$, let $VC_{\supseteq}(\mathcal{R})$, let $VC_{lhs}(\mathcal{S})$. Then $\neg CR(\mathcal{R})$ implies $\neg CR(\mathcal{R} \cup \mathcal{S})$.*

Proof. By assuming $\neg CR(\mathcal{R})$ there are s, t, u such that $s \rightarrow_{\mathcal{R}}^* t$, $s \rightarrow_{\mathcal{R}}^* u$, and $NJ_{\mathcal{R}, \mathcal{R}}(t, u)$. Since $\mathcal{F}(\mathcal{R}) \cap \mathcal{F}(\mathcal{S}) = \emptyset$, w.l.o.g. we assume $\mathcal{F}(s) \cap \mathcal{F}(\mathcal{S}) = \emptyset$.⁴ By $VC_{\supseteq}(\mathcal{R})$ we conclude that also $(\mathcal{F}(t) \cup \mathcal{F}(u)) \cap \mathcal{F}(\mathcal{S}) = \emptyset$ must hold. Assume that t and u are joinable by $\mathcal{R} \cup \mathcal{S}$. By looking at the function symbols and using $VC_{lhs}(\mathcal{S})$ we conclude that the joining sequences cannot use any rule from \mathcal{S} . Hence, t and u are joinable by \mathcal{R} , a contradiction to $NJ_{\mathcal{R}, \mathcal{R}}(t, u)$. \square

There is an asymmetry in the modularity theorem, namely that \mathcal{R} and \mathcal{S} have to satisfy different variable conditions. Note that in general it is not possible to weaken these conditions as can be seen by the following two examples of [7, Example 20 and example in Section 5.3]. If $\mathcal{R} = \{a \rightarrow b, a \rightarrow c\}$ and $\mathcal{S} = \{x \rightarrow d\}$ (or if $\mathcal{R} = \{f(x, y) \rightarrow f(z, z), f(b, c) \rightarrow a, b \rightarrow d, c \rightarrow d\}$ and $\mathcal{S} = \{g(y, x, x) \rightarrow y, g(x, x, y) \rightarrow y\}$) then $\neg CR(\mathcal{R})$, but $CR(\mathcal{R} \cup \mathcal{S})$. Hence $VC_{lhs}(\mathcal{S})$ (or $VC_{\supseteq}(\mathcal{R})$) cannot be dropped from Theorem 7. The relaxation on the variable conditions sometimes is helpful:

Example 8. *Consider the non-confluent \mathcal{R}_5 of Example 6 and $\mathcal{S} = \{g(x) \rightarrow y\}$. By Theorem 7 and $\neg CR(\mathcal{R}_5)$ we immediately conclude $\neg CR(\mathcal{R}_5 \cup \mathcal{S})$. Note that the proof in Example 6 is not applicable to $\mathcal{R}_5 \cup \mathcal{S}$, since $VC_{\supseteq}(\mathcal{R}_5 \cup \mathcal{S})$ does not hold.*

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³Note that in *IsaFoR* function symbols do not come with a fixed arity.

⁴Here is exactly the point where in the formalization we use the assumptions of finite signatures and an infinite set of symbols. Then it is always possible to rename all symbols in $\mathcal{F}(s) \cap \mathcal{F}(\mathcal{S})$ into fresh ones.