

A New Order-theoretic Characterisation of the Polytime Computable Functions

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March 28, 2012



Implicit Computational Complexity (ICC)

characterise complexity classes

- external restriction of resources
- + restrict program structure

Motivation

- ▶ broaden understanding
- ▶ apply in programming language theory

Cobhams Definition of FP



Alan Cobham

The Intrinsic Computational Difficulty of Functions.

Proc. of the 1964 International Congress for Logic, Methodology, and the Philosophy of Science, pages 24–30, 1964

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Bounded Recursion on Notation

$$f(\varepsilon, \vec{y}) = g(\vec{y})$$

$$f(zi, \vec{y}) = h_i(z, \vec{y}, f(z, \vec{y})) \quad \text{for } i = 0, 1$$

- ▶ provided $f(z, \vec{y}) \leq p(z, \vec{y})$ for previously defined p and all z, \vec{y}
- ▶ requires smash function $x \# y := 2^{|\cdot| \cdot |\cdot|}$

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$$f(zi, \vec{y}) = h_i(z, \vec{y}, f(z, \vec{y})) \quad \text{for } i = 0, 1$$

- ▶ provided $|f(z, \vec{y})| \leq |p(z, \vec{y})|$ for previously defined p and all z, \vec{y}
- ▶ requires smash function $x \# y := 2^{|\times| \cdot |y|}$

Bellantoni & Cooks Definition of FP



Stephen Bellantoni and Stephen A. Cook

A New Recursion-Theoretic Characterization of the Polytime Functions.

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Predicative Recursion on Notation

$$f(\epsilon, \vec{x}; \vec{y}) = g(\vec{x}; \vec{y})$$

$$f(z_i, \vec{x}; \vec{y}) = h_i(z, \vec{x}; \vec{y}, f(z, \vec{x}; \vec{y})) \quad \text{for } i = 0, 1$$

- uses separation of arguments

$$f(\underbrace{n_1, \dots, n_l}_{\text{normal}}; \underbrace{n_{l+1}, \dots, n_{l+k}}_{\text{safe}})$$

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- ▶ uses separation of arguments

$$f(\underbrace{n_1, \dots, n_l}_{\text{normal}}; \underbrace{n_{l+1}, \dots, n_{l+k}}_{\text{safe}})$$

- ▶ “complexity depends only on normal arguments”

Runtime Complexity Analysis of TRSs

Computation

- ▶ conceive TRS \mathcal{R} as first order program over signature $\mathcal{D} \uplus \mathcal{C}$
- ▶ values \mathcal{Val} are terms built from constructors \mathcal{C}
- ▶ for each $f \in \mathcal{D}$, \mathcal{R} computes functions $f : \mathcal{Val}^n \rightarrow \mathcal{Val}$ such that

$$f(v_1, \dots, v_n) := u \quad \iff \quad f(v_1, \dots, v_n) \xrightarrow{!}_{\mathcal{R}} u$$

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Runtime Complexity

- ▶ runtime complexity function

$$rc_{\mathcal{R}}(n) := \max\{\text{dh}(t, \rightarrow_{\mathcal{R}}) \mid t \text{ is basic term of size up to } n\}$$

$$\text{where } \text{dh}(t, \rightarrow) := \max\{\ell \mid t \rightarrow t_1 \rightarrow t_2 \cdots \rightarrow t_\ell\}$$

- ▶ term $f(v_1, \dots, v_n)$ is **basic** if $f \in \mathcal{D}$ and all $v_i \in \mathcal{Val}$



Polynomial Path Order $>_{\text{pop}^*}$



M. Avanzini and G. Moser

Complexity Analysis by Rewriting.

Proc. of 9th International Symposium on Functional and Logic Programming, LNCS Vol. 4989, pages 130–146, 2008

- ▶ $\text{order } >_{\text{pop}^*}$ embodies predicative recursion on $>_{\text{mpo}}$

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Example

$$1: \quad +(0, y) \rightarrow y$$

$$3: \quad \times(0, y) \rightarrow 0$$

$$2: \quad +(s(x), y) \rightarrow s(+ (x, y))$$

$$4: \quad \times(s(x), y) \rightarrow + (y, \times(x, y))$$

$$5: \quad \text{sq}(x) \rightarrow \times(x, x)$$

- ▶ TRS is compatible with $>_{\text{mpo}}$ using precedence $\text{sq} \succ \times \succ + \succ s$

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Example

$$1: \quad +(\mathbf{0}; y) \rightarrow y$$

$$3: \quad \times(\mathbf{0}, y;) \rightarrow 0$$

$$2: \quad +(\mathbf{s}(x); y) \rightarrow s(+(\mathbf{x}; y))$$

$$4: \quad \times(\mathbf{s}(x), y;) \rightarrow +(\mathbf{y}; \times(\mathbf{x}, y;))$$

$$5: \quad \text{sq}(\mathbf{x};) \rightarrow \times(\mathbf{x}, \mathbf{x};)$$

- ▶ TRS is compatible with $>_{\text{pop}^*}$ using precedence $\text{sq} \succ \times \succ + \succ s$

Polynomial Path Order $>_{\text{pop}^*}$

Runtime Complexity Analysis

Let \mathcal{R} denote a **constructor** TRS. There exists $k \in \mathbb{N}$ such that

$$\mathcal{R} \subseteq >_{\text{pop}^*} \implies \text{rc}_{\mathcal{R}}^i \in O(n^k)$$

Polynomial Path Order $>_{\text{pop}^*}$

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Implicit Computational Complexity

① Soundness

Let \mathcal{R} be a constructor TRS that computes a function f .

If $\mathcal{R} \subseteq >_{\text{pop}^*}$ then f is polytime computable.

Polynomial Path Order $>_{\text{pop}^*}$

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② Completeness

Let f be a polytime computable function.

There exists a constructor TRS \mathcal{R}_f computing f with $\mathcal{R}_f \subseteq >_{\text{pop}^*}$.

Polynomial Path Order $>_{\text{pop}^*}$

Runtime Complexity Analysis

Let \mathcal{R} denote a constructor TRS. **There exists** $k \in \mathbb{N}$ such that

$$\mathcal{R} \subseteq >_{\text{pop}^*} \implies \text{rc}_{\mathcal{R}}^i \in O(n^k)$$

Implicit Computational Complexity

① Soundness

Let \mathcal{R} be a constructor TRS that computes a function f .
If $\mathcal{R} \subseteq >_{\text{pop}^*}$ then f is polytime computable.

② Completeness

Let f be a polytime computable function.

There exists a constructor TRS \mathcal{R}_f computing f with $\mathcal{R}_f \subseteq >_{\text{pop}^*}$.

Drawback

order $>_{\text{pop}^*}$ cannot precisely estimate degree of polynomial

Small Polynomial Path Order $>_{\text{spop}^*}$

- ▶ restriction of polynomial path order

$$>_{\text{spop}^*} \subseteq >_{\text{pop}^*}$$

- ▶ estimate degree of complexity certificate in “*depth of recursion*”

Small Polynomial Path Order $>_{\text{spop}^*}$

- ▶ restriction of polynomial path order

$$>_{\text{spop}^*} \subseteq >_{\text{pop}^*}$$

- ▶ estimate degree of complexity certificate in “*depth of recursion*”

- ① restrict composition to safe arguments

weak safe composition

$$f(\vec{x}; \vec{y}) = g(\vec{x}; h_1(\vec{x}; \vec{y}), \dots, h_k(\vec{x}; \vec{y}))$$

Small Polynomial Path Order $>_{\text{spop}^*}$

- ▶ restriction of polynomial path order

$$>_{\text{spop}^*} \subseteq >_{\text{pop}^*}$$

- ▶ estimate degree of complexity certificate in “*depth of recursion*”

- ① restrict composition to safe arguments weak safe composition

$$f(\vec{x}; \vec{y}) = g(\vec{x}; h_1(\vec{x}; \vec{y}), \dots, h_k(\vec{x}; \vec{y}))$$

- ② uses product-status

$$f_k(s(x_1), x_2, x_3, \dots, x_k;) \rightarrow f_k(x_1, x_2, x_3, \dots, x_k;)$$

$$f_k(0, s(x_2), x_3, \dots, x_k;) \rightarrow f_k(x_2, x_2, x_3, \dots, x_k;)$$

$$\vdots$$

$$f_k(0, \dots, 0, s(x_k);) \rightarrow f_k(x_k, \dots, x_k, x_k;)$$

- compatible with $>_{\text{pop}^*}$, admits runtime complexity in $\Theta(n^k)$

Small Polynomial Path Order $>_{\text{spop}^*}$

$f(s_1, \dots, s_k; s_{k+1}, \dots, s_{k+l}) >_{\text{spop}^*} t$ if

- 1 $s_i \geq_{\text{spop}^*} t$ for some argument s_i

Small Polynomial Path Order $>_{\text{spop}^*}$

$f(s_1, \dots, s_k; s_{k+1}, \dots, s_{k+l}) >_{\text{spop}^*} t$ if

- ① $s_i \geq_{\text{spop}^*} t$ for some argument s_i
- ② $t = g(t_1, \dots, t_m; t_{m+1}, \dots, t_{m+n})$ where $f \in \mathcal{D}$ and $f \succ g$
 - $f(s_1, \dots, s_k; s_{k+1}, \dots, s_{k+l}) \triangleright_n t_j$ for all normal arguments t_j
 - $f(s_1, \dots, s_k; s_{k+1}, \dots, s_{k+l}) >_{\text{spop}^*} t_j$ for all safe arguments t_j

$$f(\vec{x}; \vec{y}) = g(\vec{x}; h_1(\vec{x}; \vec{y}), \dots, h_k(\vec{x}; \vec{y}))$$

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$$f(s_1, \dots, s_k; \dots) \triangleright_n t \quad :\Leftrightarrow \quad s_i \underline{\triangleright} \cdot \sim t$$

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- ③ $t = g(t_1, \dots, t_k; t_{k+1}, \dots, t_{k+l})$ where $f \in \mathcal{D}$ and $f \sim g$
 - $\langle s_1, \dots, s_k \rangle >_{\text{spop}^*} \langle t_{\pi(1)}, \dots, t_{\pi(k)} \rangle$
 - $\langle s_{k+1}, \dots, s_{k+l} \rangle \geq_{\text{spop}^*} \langle t_{\tau(k+1)}, \dots, t_{\tau(k+l)} \rangle$

$$f(\varepsilon, \vec{x}; \vec{y}) = g(\vec{x}; \vec{y})$$
$$f(z_i, \vec{x}; \vec{y}) = h_i(z, \vec{x}; \vec{y}, f(z, \vec{x}; \vec{y})) \quad \text{for } i = 0, 1$$

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 - $f(s_1, \dots, s_k; s_{k+1}, \dots, s_{k+l}) >_{\text{spop}^*} t_j$ for all safe arguments t_j
 - t contains at most one defined symbol h with $h \succcurlyeq f$
- ③ $t = g(t_1, \dots, t_k; t_{k+1}, \dots, t_{k+l})$ where $f \in \mathcal{D}$ and $f \sim g$
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 - $\langle s_{k+1}, \dots, s_{k+l} \rangle \geq_{\text{spop}^*} \langle t_{\tau(k+1)}, \dots, t_{\tau(k+l)} \rangle$

$$f(s(x);) \not>_{\text{spop}^*} c(; f(x);, f(x;))$$

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- ③ $t = g(t_1, \dots, t_k; t_{k+1}, \dots, t_{k+l})$ where $f \in \mathcal{D}_{\text{rec}}$ and $f \sim g$
 - $\langle s_1, \dots, s_k \rangle >_{\text{spop}^*} \langle t_{\pi(1)}, \dots, t_{\pi(k)} \rangle$
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assume designated set of recursive symbols $\mathcal{D}_{\text{rec}} \subseteq \mathcal{D}$

Small Polynomial Path Order $>_{\text{spop}^*}$

$f(\mathbf{s}_1, \dots, \mathbf{s}_k; \mathbf{s}_{k+1}, \dots, \mathbf{s}_{k+l}) >_{\text{spop}^*} t$ if

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 - $f(\mathbf{s}_1, \dots, \mathbf{s}_k; \mathbf{s}_{k+1}, \dots, \mathbf{s}_{k+l}) >_{\text{spop}^*} \mathbf{t}_j$ for all safe arguments \mathbf{t}_j
 - t contains at most one defined symbol h with $h \not\asymp f$
- ③ $t = g(\mathbf{t}_1, \dots, \mathbf{t}_k; \mathbf{t}_{k+1}, \dots, \mathbf{t}_{k+l})$ where $f \in \mathcal{D}_{\text{rec}}$ and $f \sim g$
 - $\langle \mathbf{s}_1, \dots, \mathbf{s}_k \rangle >_{\text{spop}^*} \langle \mathbf{t}_{\pi(1)}, \dots, \mathbf{t}_{\pi(k)} \rangle$
 - $\langle \mathbf{s}_{k+1}, \dots, \mathbf{s}_{k+l} \rangle \geq_{\text{spop}^*} \langle \mathbf{t}_{\tau(k+1)}, \dots, \mathbf{t}_{\tau(k+l)} \rangle$

Small Polynomial Path Order $>_{\text{spop}^*}$

Main Result

- ▶ the **depth of recursion** $\text{rd}(f)$ is defined as follows:

$$\text{rd}(f) := \begin{cases} 1 + \max\{\text{rd}(g) \mid f \succ g\} & \text{if } f \in \mathcal{D}_{\text{rec}} \\ \max\{\text{rd}(g) \mid f \succ g\} & \text{otherwise} \end{cases}$$

Small Polynomial Path Order $>_{\text{spop}^*}$

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- ▶ constructor TRS \mathcal{R} is **predicative recursive of degree d** if
 - \mathcal{R} is compatible with $>_{\text{spop}^*}$
 - depth of recursion of symbol in \mathcal{R} is at most d

Small Polynomial Path Order $>_{\text{spop}^*}$

Main Result

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Theorem

- 1 if \mathcal{R} is a predicative recursive TRS of degree d , then $\text{rc}_{\mathcal{R}}^i \in O(n^d)$

Small Polynomial Path Order $>_{\text{sop}^*}$

Main Result

- ▶ the depth of recursion $\text{rd}(f)$ is defined as follows:

$$\text{rd}(f) := \begin{cases} 1 + \max\{\text{rd}(g) \mid f \succ g\} & \text{if } f \in \mathcal{D}_{\text{rec}} \\ \max\{\text{rd}(g) \mid f \succ g\} & \text{otherwise} \end{cases}$$

- ▶ constructor TRS \mathcal{R} is predicative recursive of degree d if
 - \mathcal{R} is compatible with $>_{\text{sop}^*}$
 - depth of recursion of symbol in \mathcal{R} is at most d

Theorem

- ① if \mathcal{R} is a predicative recursive TRS of degree d , then $\text{rc}_{\mathcal{R}}^i \in O(n^d)$
- ② for all d there exists a predicative recursive TRS of degree d such that $\text{rc}_{\mathcal{R}}^i \in \Theta(n^d)$

Small Polynomial Path Order $>_{\text{spop}^*}$

Example

$$1: \quad +(\mathbf{0}; y) \rightarrow y$$

$$3: \quad \times(\mathbf{0}, y;) \rightarrow 0$$

$$2: \quad +(\mathbf{s}(x); y) \rightarrow \mathbf{s}(+(x; y))$$

$$4: \quad \times(\mathbf{s}(x), y;) \rightarrow +(\mathbf{y}; \times(x, y;))$$

$$5: \quad \text{sq}(x;) \rightarrow \times(x, x;)$$

- ▶ TRS is compatible with $>_{\text{spop}^*}$ using precedence $\text{sq} \succ \times \succ + \succ \mathbf{s}$
- ▶ only \times and $+$ are recursive
- ▶ innermost runtime complexity is quadratic

Experimental Results

bound	MPO	POP*	sPOP*
yes	76 _{0.09}	43 _{0.05}	39 _{0.07}

Table: 757 constructor TRSs from TPDB 8.0

Experimental Results

bound	MPO	POP*	sPOP*
$O(1)$			$9 \setminus 0.06$
$O(n^1)$			$32 \setminus 0.07$
$O(n^2)$			$38 \setminus 0.09$
$O(n^3)$			$39 \setminus 0.20$
$O(n^k)$		$43 \setminus 0.05$	$39 \setminus 0.20$
yes	$76 \setminus 0.09$	$43 \setminus 0.05$	$39 \setminus 0.07$

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Experimental Results

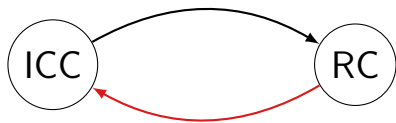
bound	MPO	POP*	sPOP*	POP* _{PS}	sPOP* _{PS}
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$O(n^1)$			32\0.07		46\0.09
$O(n^2)$			38\0.09		53\0.10
$O(n^3)$			39\0.20		54\0.22
$O(n^k)$		43\0.05	39\0.20	56\0.05	54\0.22
yes	76\0.09	43\0.05	39\0.07	56\0.05	54\0.08

Table: 757 constructor TRSs from TPDB 8.0

► **Parameter Substitution**

$$f(\varepsilon, \vec{x}; \vec{y}) = g(\vec{x}; \vec{y})$$

$$f(z_i, \vec{x}; \vec{y}) = h_i(z, \vec{x}; \vec{y}, f(z, \vec{x}; p_1(z, \vec{x}; \vec{y})), \dots, p_k(z, \vec{x}; \vec{y})) \quad \text{for } i = 0, 1$$



Applications in ICC

Main Results

Theorem

\succ_{spop^*} is sound and complete for polytime functions

Applications in ICC

Main Results

Theorem

\succ_{spop^*} is **sound** and complete for polytime functions

- ▶ innermost runtime complexity is an invariant cost model

Applications in ICC

The Class \mathcal{B}_{WSC}

class \mathcal{B}_{WSC} is smallest class of functions that

- ① contains a small set of initial functions successors, conditional, ...
- ② is closed under weak predicative composition

$$f(\vec{x}; \vec{y}) = g(\vec{x}; h_1(\vec{x}; \vec{y}), \dots, h_k(\vec{x}; \vec{y}))$$

- ③ is closed under safe recursion on notation

$$f(\varepsilon, \vec{x}; \vec{y}) = g(\vec{x}; \vec{y})$$

$$f(z_i, \vec{x}; \vec{y}) = h_i(z, \vec{x}; \vec{y}, f(z, \vec{x}; \vec{y})) \quad \text{for } i = 0, 1$$

Applications in ICC

The Class \mathcal{B}_{WSC}

class \mathcal{B}_{WSC} is smallest class of functions that

- 1 contains a small set of initial functions successors, conditional, ...
- 2 is closed under weak predicative composition

$$f(\vec{x}; \vec{y}) = g(\vec{x}; h_1(\vec{x}; \vec{y}), \dots, h_k(\vec{x}; \vec{y}))$$

- 3 is closed under safe recursion on notation

$$f(\varepsilon, \vec{x}; \vec{y}) = g(\vec{x}; \vec{y})$$

$$f(z_i, \vec{x}; \vec{y}) = h_i(z, \vec{x}; \vec{y}, f(z, \vec{x}; \vec{y})) \quad \text{for } i = 0, 1$$

Theorem

\mathcal{B}_{WSC} equals the polytime computable functions

Applications in ICC

Main Results

Theorem

\succ_{spop^*} is sound and **complete** for polytime functions

- ▶ innermost runtime complexity is an invariant cost model
- ▶ every $f \in \mathcal{B}_{\text{WSC}}$ can be formulated as predicative recursive TRS

Applications in ICC

More Precise...

Theorem

$RM \Rightarrow TRS$

Suppose R is **register machine** operating in time $O(n^d)$.

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Theorem

$TRS \Rightarrow RM$

Suppose predicative TRS \mathcal{R} of degree d computes functions on **strings**.

If f is computed by \mathcal{R} , then f is computable on a register machine R_f operating in time $O(n^d)$.

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$$g \in O(n^{d_g}), h \in O(n^{d_h}), i \in O(n^{d_i}) \quad \Rightarrow \quad f \in O(n^d)$$

where $d = \max\{\min\{1, d_g\} \cdot d_h, d_i\}$

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Conjecture

for any function f on strings, the following are equivalent

- ① f is defined in \mathcal{B}_{wsc} via at most d -fold nested application of SRN
- ② f is computed by **predicative recursive TRS** \mathcal{R}_f of degree d
- ③ f is computed by **register machine** R_f operating in time $O(n^d)$