

# Resources in $\lambda$ -calculus

(an introduction to the differential approach to computation)

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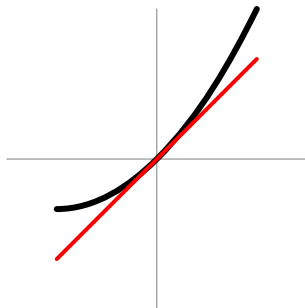
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Master Seminar 3 – May, 16 2012

1. Introduction (first slide contains maths!).
2. Resource calculus.
3. Differential  $\lambda$ -calculus.
4. Promoted resources.
5. Conclusion.

Differentials:

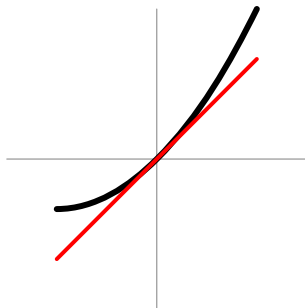
$f: \mathbb{R} \rightarrow \mathbb{R}$ , for example  $f(x) = x^2$ :



$Df: \mathbb{R} \rightarrow \mathcal{L}(\mathbb{R}, \mathbb{R})$ , here  $Df(x)(u) = 2x \cdot u = \frac{\partial}{\partial x} f(x) \cdot u$ .

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- ▶  $\lambda$ -terms are functions, can we get linear approximations for them?

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$$\begin{aligned} & \langle \lambda x \langle x \rangle xx \rangle abc \\ \longrightarrow & \langle a \rangle bc + \langle a \rangle cb + \langle b \rangle ac + \langle b \rangle ca + \langle c \rangle ab + \langle c \rangle ba \end{aligned}$$

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$$\longrightarrow 0 + 0 + 4 \langle \lambda xx \rangle \lambda xx$$

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1. Resource calculus.

## Definition

Resource calculus:

$$t ::= \begin{array}{l} x \mid \lambda x t \mid \langle t \rangle T \\ 0 \mid t + t \end{array} \quad T ::= \begin{array}{l} 1 \mid TT \mid t \\ 0 \mid T + T \end{array}$$

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$$t_1 \cdots t_n$$

- ▶ Quotient by (bi-)linearity of all constructions:

$$\lambda x 0 = 0 \quad \lambda x (t_1 + t_2) = \lambda x t_1 + \lambda x t_2$$

## Linear substitution

$$t = \langle x \rangle_{xx} \quad \frac{\partial}{\partial x} t \cdot u = \langle u \rangle_{xx} + \langle x \rangle_{ux} + \langle x \rangle_{xu}$$



## Linear substitution

$$t = \langle x \rangle x \quad \frac{\partial}{\partial x} t \cdot u = \langle u \rangle x x + \langle x \rangle u x + \langle x \rangle x u$$

### Definition

We use  $\frac{\partial}{\partial z} \square \cdot u$  to denote linear substitution of  $z$  by  $u$  in a term:

$$\frac{\partial}{\partial z} x \cdot u = 0 \quad \frac{\partial}{\partial z} z \cdot u = u$$

$$\frac{\partial}{\partial z} (\lambda x s) \cdot u = \lambda x \frac{\partial}{\partial z} s \cdot u$$

$$\frac{\partial}{\partial z} (\langle r \rangle R) \cdot u = \left\langle \frac{\partial}{\partial z} r \cdot u \right\rangle R + \langle r \rangle \frac{\partial}{\partial z} R \cdot u$$

$$t = \langle x \rangle xx \quad \frac{\partial}{\partial x} t \cdot u = \langle u \rangle xx + \langle x \rangle ux + \langle x \rangle xu$$

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$$\frac{\partial}{\partial z} (\langle r \rangle R) \cdot u = \left\langle \frac{\partial}{\partial z} r \cdot u \right\rangle R + \langle r \rangle \frac{\partial}{\partial z} R \cdot u$$

or in bags:

$$\frac{\partial}{\partial z} 1 \cdot u = 0 \quad \frac{\partial}{\partial z} ST \cdot u = \left( \frac{\partial}{\partial z} S \cdot u \right) T + S \left( \frac{\partial}{\partial z} T \cdot u \right)$$

## Property

Operators  $\frac{\partial}{\partial x}$  and  $\frac{\partial}{\partial y}$  commute, *Schwarz/Clairaut* property:

$$\frac{\partial}{\partial y} \left( \frac{\partial}{\partial x} t \cdot u \right) \cdot v = \frac{\partial}{\partial x} \left( \frac{\partial}{\partial y} t \cdot v \right) \cdot u$$

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$$\begin{aligned} \frac{\partial}{\partial y} \left( \frac{\partial}{\partial x} t \cdot u \right) \cdot v + \frac{\partial}{\partial y} t \cdot \left( \frac{\partial}{\partial x} v \cdot u \right) \\ = \frac{\partial}{\partial x} t \cdot \left( \frac{\partial}{\partial y} u \cdot v \right) + \frac{\partial}{\partial x} \left( \frac{\partial}{\partial y} t \cdot v \right) \cdot u \end{aligned}$$

In the usual case when  $x \notin v$  and  $y \notin u$ :

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Redexes are sub-terms of the form  $\langle \lambda x s \rangle R$ .

## Definition

Reduction is defined using linear substitution:

$$\langle \lambda x s \rangle rR \longrightarrow \left\langle \lambda x \frac{\partial}{\partial x} s \cdot r \right\rangle R$$

$$\langle \lambda x s \rangle 1 \longrightarrow s[0/x]$$

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- ▶ A sum is reduced by reducing any term it contains.
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- ▶ Normalization holds as long as sums are finite.
- ▶ [ER08] *Uniformity and the Taylor expansion of ordinary  $\lambda$ -terms.*

Decomposition is defined inductively on standard  $\lambda$ -terms:

$$\begin{aligned}(x)^* &= x \\ (\lambda x s)^* &= \lambda x s^* \\ ((t) s)^* &= \sum_{n=0}^{+\infty} \langle t^* \rangle s^{*n} \\ &= \langle t^* \rangle 1 + \langle t^* \rangle s^* + \langle t^* \rangle s^* s^* + \dots\end{aligned}$$

Example.



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Example.

## 2. Differential $\lambda$ -calculus.

The differential of a function  $f: A \rightarrow B$  has type:

$$Df: A \rightarrow \mathcal{L}(A, B)$$

This suggests that we could add the following construct to the standard  $\lambda$ -calculus:

$$Df \cdot u: A \rightarrow B$$

We obtain Differential  $\lambda$ -calculus ([Vau07]):

$$t ::= x \mid \lambda x t \mid (t) t \mid Dt \cdot u \mid 0 \mid t + t$$

Warning: application is only left-linear.

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The differential of a function  $f: A \rightarrow B$  has type:

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$$\lambda z \frac{\partial}{\partial z} ((z) z) \cdot x$$



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$$\downarrow \partial$$

$$\lambda z \frac{\partial}{\partial z} ((z) z) \cdot x$$

$$=$$

$$\lambda z (x) z + \lambda z (Dz \cdot x) z$$

Nice analogy between:

$$(t) s \approx \sum_{n=0}^{+\infty} \frac{1}{n!} (D^n t \cdot \underbrace{(s, \dots, s)}_n) 0$$

and:

$$f(x) = \sum_{n=0}^{+\infty} \frac{1}{n!} f^{(n)}(0) x^n$$

or:

$$f(x) = \sum_{n=0}^{+\infty} \frac{1}{n!} D^n f(\underbrace{x, \dots, x}_n)(0)$$

3. Promoted resources.

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- ▶  $(s) t$  becomes  $\langle s \rangle t'$ .
- ▶  $(D(D(Df \cdot u) \cdot v) \cdot w) t$  becomes  $\langle f \rangle uvwt'$

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Here *promotion* is not linear:

$$(u + v)' \neq u' + v'$$

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Here *promotion* is not linear:

$$(u + v)' = u'v'$$

$$0' = 1$$



Linear substitution is extended to promoted resources:

$$\frac{\partial}{\partial z} t' \cdot u = \left( \frac{\partial}{\partial z} t \cdot u \right) t'$$

A new reduction rule:

$$\langle \lambda x s \rangle 1 \xrightarrow{a} s[0/x] \quad \langle \lambda x s \rangle rR \xrightarrow{a} \left\langle \lambda x \frac{\partial}{\partial x} s \cdot r \right\rangle R$$

$$\langle \lambda x s \rangle r'R \xrightarrow{a} \langle \lambda x s \rangle R + \left\langle \lambda x \frac{\partial}{\partial x} s \cdot r \right\rangle r'R$$

We introduced:

- ▶ A notion of (non-duplicable and non-erasable) resource.
- ▶ A reduction based on linear substitution.
- ▶ A notion of “vector space” over terms to control non-determinism.
- ▶ Analogies with differential analysis (in math).

What we have not talked about:

- ▶ Differential Linear Logic.
- ▶ Links with Process algebras.

Open perspectives:

- ▶ Links with Implicit Complexity?
- ▶ Links with Quantum computation?
- ▶ Find a better syntax!