

# Logic Programming

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# Outline of the Lecture

### Logic Programs

introduction, basic constructs, database and recursive programming, theory of logic programs

# The Prolog Language

programming in pure Prolog, arithmetic, structure inspection, meta-logical predicates, cuts, extra-logical predicates, how to program efficiently

# Advanced Prolog Programming Techniques

nondeterministic programming, incomplete data structures, definite clause grammars, meta-programming, constraint logic programming

#### ummary of Last Lecture

# Summary of Last Lecture

### Observation

the basic operations of relational algebras, namely:

- 1 union
- 2 difference
- 3 cartesian product
- 4 projection
- 5 selection
- 6 intersection

can easily be expressed within logic programming

### Definition

- a type is a (possible infinite) set of terms
- types are conveniently defined by unary relations

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#### Theory of Logic Programs

# Theory of Logic Programs

### Definitions

• goal clause

 $\leftarrow B_1, \ldots, B_n$ 

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consists of sequence  $B_1, \ldots, B_n$  of goals

- empty goal clause  $\leftarrow$  is denoted by  $\square$
- resolvent of goal clause  $\leftarrow B_1, \ldots, B_i, \ldots, B_m$  and rule  $A \leftarrow A_1, \ldots, A_n$  is goal clause

 $\leftarrow B_1\theta,\ldots,B_{i-1}\theta,A_1\theta,\ldots,A_n\theta,B_{i+1}\theta\ldots,B_m\theta$ 

provided  $B_i$  (selected goal) and A unify with mgu  $\theta$ 

# Selective Linear Definite Clause Resolution

### Definitions

- SLD-derivation of logic program P and goal clause G consists of
  - **1** maximal sequence  $G_0, G_1, G_2, \ldots$  of goal clauses
  - **2** sequence  $C_0, C_1, C_2, \ldots$  of variants of rules in *P*
  - **3** sequence  $\theta_0, \theta_1, \theta_2, \ldots$  of substitutions

such that

- $G_0 = G$
- $G_{i+1}$  is resolvent of  $G_i$  and  $C_i$  with mgu  $\theta_i$
- $C_i$  has no variables in common with  $G, C_0, \ldots, C_{i-1}$
- SLD-refutation is finite SLD-derivation ending in  $\square$
- computed answer substitution of SLD-refutation of P and G with substitutions  $\theta_0, \theta_1, \ldots, \theta_m$  is restriction of  $\theta_0 \theta_1 \cdots \theta_m$  to variables in G

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#### Theory of Logic Programs

Remark

selected goal in goal clause is determined by selection function

#### Theorem

 $\forall$  logic programs P and goal clause G

- $\forall$  computed answer substitutions  $\theta$
- $\forall$  selection functions  $\mathcal{S}$
- $\exists$  computed answer substitution  $\theta'$  using S
- such that  $\theta'$  is at least as general as  $\theta$  (with respect to variables in G)

# One Choice

	goal in sequence of goals			_	" $\forall$ selection functions $\mathcal{S}$ "
2	rule in logic pr	ogram			
	substitution	-	avoid	choice	by always taking mgu

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#### Example

 $\begin{array}{l} \text{plus}(0,X,X).\\ \text{plus}(s(X),Y,s(Z)) \leftarrow \text{plus}(X,Y,Z).\\ \text{times}(0,X,0).\\ \text{times}(s(X),Y,Z) \leftarrow \text{times}(X,Y,U), \text{plus}(U,Y,Z).\\ \leftarrow \text{times}(x,X,Y)\\ \\ \text{SLD-refutation}\\ G_{0}: \leftarrow \text{times}(X,X,Y)\\ C_{0}: \text{times}(s(X_{0}),Y_{0},Z_{0}) \leftarrow \text{times}(X_{0},Y_{0},U_{0}), \text{plus}(U_{0},Y_{0},Z_{0})\\ \theta_{0}: X \mapsto s(X_{0}), Y_{0} \mapsto s(X_{0}), Z_{0} \mapsto Y\\ G_{1}: \leftarrow \text{times}(X_{0},s(X_{0}),U_{0}), \text{plus}(U_{0},s(X_{0}),Y)\\ C_{1}: \text{times}(0,X_{1},0).\\ \theta_{1}: X_{0} \mapsto 0, X_{1} \mapsto s(0), U_{0} \mapsto 0\\ \\ G_{2}: \leftarrow \text{plus}(0,s(0),Y)\\ C_{2}: \text{plus}(0,X_{2},X_{2}).\\ \theta_{2}: X_{2} \mapsto s(0), Y \mapsto s(0) \end{array}$ 

 $G_3$ :  $\Box$  computed answer substitution:  $X \mapsto s(0), Y \mapsto s(0)$ 

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#### Theory of Logic Programs

### Definition

a SLD tree captures all SLD derivations wrt a given selection function



### Semantics

### Definitions

- the Herbrand universe for a program *P* is the set of all closed terms built from constants and function symbols appearing in the program
- the Herbrand base is the set of all ground goals formed from predicates in *P* and terms in the Herbrand universe
- an interpretation is a subset of the Herbrand base
- an interpretation *I* is a model if it is closed under rules:

$$\forall A \leftarrow B_1, \ldots, B_n \quad A \in I, \text{ if } B_1, \ldots, B_n \in I$$

• the minimal model of *P* is the intersection of all models; the minimal model is unique

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#### Semantics

# Correctness and Completeness

### Definition

the intended meaning of a logic program is a set of ground facts

### Definition

#### a program P is called

- correct with respect to the intended meaning M, if the meaning of P is a subset of M
- complete if the intended meaning M is a subset of the meaning of P

#### mantics

# Declarative, Operational, and Denotational Semantics

### Definition

- the declarative semantics of *P* (aka its meaning) is the minimal model of *P*
- we also say that the meaning of a logic program *P*, is the set of (ground unit) goals deducible from *P*

### Definitions

the operational semantics describes the meaning of a program procedurally

#### Definition

the denotational semantics assign meanings to programs based on associating with the program a function over the domain computed by the program

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#### Semantics

#### Example

```
natural_number(0).
natural_number(s(X)) \leftarrow natural_number(X).
```

#### Lemma

the program is complete wrt the set of facts

```
M := \{\texttt{natural\_number}(s^i(0)) \mid i \ge 0\}
```

### Proof of Completeness.

- 1 let *N* be a natural number
- 2 we show that natural\_number(s<sup>N</sup>(0)) is deducible by given a explicit SLD tree
- **3** case distinction on N = 0 and N > 0

#### Lemma

the program is correct wrt the set of facts

 $M := \{\texttt{natural\_number}(s^i(0)) \mid i \ge 0\}$ 

### Proof of Correctness.

- **1** suppose natural\_number( $s^m(0)$ ) is deducible in *n* deductions
- 2 we use induction on *n*
- 3 n = 0: then natural\_number( $s^m(0)$ ) implies m = 0
- **4** n > 0: the goal must be of form natural\_number(s(t))
- **5** thus natural\_number(t) is deducible with n-1 deductions

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- 6  $t = s^{m'}(0)$  for some  $m' \in \mathbb{N}$
- 7 natural\_number $(s^{m'1}(0)) \in M$  and m = m' + 1

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#### Semantics

### Example

```
natural_number(0).
natural_number(s(X)) \leftarrow natural_number(X).
```

```
plus(0,X,X) \leftarrow natural_number(X).
plus(s(X),Y,s(Z)) \leftarrow plus(X,Y,Z).
```

#### Lemma

the program is correct and complete wrt to the definition of addition

### Proof Sketch.

- completeness: suppose X + Y = Z; then we give an SLD tree of plus(X, Y, Z)
- **2** correctness: suppose plus(X, Y, Z) is deducible; then we prove by induction on the length of this deduction that X + Y = Z

#### Example

is the program is correct wrt the following set?

 $M := \{\texttt{natural\_number}(s^i(0)) \mid 0 \leqslant i \leqslant K\}$ 

#### Attempted Proof

- **1** suppose natural\_number( $s^m(0)$ ) is deducible in *n* deductions
- 2 we use induction on *n*
- 3 n = 0: then natural\_number $(s^m(0))$  implies m = 0
- 4 n > 0: the goal must be of form natural\_number(s(t))
- 5 thus natural\_number(t) is deducible with n-1 deductions
- 6  $t = s^{m'}(0)$  for some  $0 \leq m' \leq K$  and m = m' + 1
- 7 natural\_number $(s^m(0)) \in M$  iff  $m \leq K$
- 8 what happens for m > K?

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#### Proof Trees, SLD Trees, and all That

#### Definitions

- a proof tree for a program *P* and a goal *G* is a tree, whose nodes are goals and whose edges represent reduction of goals; the root is the query *G*
- a proof tree for a conjunction of goals  $G_1, \ldots, G_n$  is the set of all proof trees for  $G_i$

#### Definitions

- a search tree is the same as an SLD tree
- in a search tree  $\Box$  is called a success node
- leafs in the search tree  $\neq \Box$  are called failure node

#### Remark

a proof tree is a different representation of one successful solution represented by a search tree

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