## universität innsbruck



## SAT and SMT Solving

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lecture 5
SS 2019

## Outline

- Summary of Last Week
- Satisfiability Modulo Theories
- $\operatorname{DPLL}(\mathrm{T})$
- Equality and Uninterpreted Functions in Practice


## Definitions

for unsatisfiable CNF formula $\varphi$ given as set of clauses

- $\psi \subseteq \varphi$ such that $\bigwedge_{c \in \psi} C$ is unsatisfiable is unsatisfiable core (UC) of $\varphi$
- minimal unsatisfiable core $\psi$ is UC such that every subset of $\psi$ is satisfiable
- SUC (minimum unsatisfiable core) is UC such that $|\psi|$ is minimal


## Remark

SUC is always minimal unsatisfiable core

## Definition (Resolution Graph)

directed acyclic graph $G=(V, E)$ is resolution graph for set of clauses $\varphi$

1. $V=V_{i} \uplus V_{c}$ is set of clauses and $V_{i}=\varphi$,
2. $V_{i}$ nodes have no incoming edges,
3. there is exactly one node $\square$ without outgoing edges,
4. $\forall C \in V_{c} \exists$ edges $D \rightarrow C, D^{\prime} \rightarrow C$ such that $C$ is resolvent of $D$ and $D^{\prime}$, and
5. there are no other edges.

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## Definition (Resolution Graph)

directed acyclic graph $G=(V, E)$ is resolution graph for set of clauses $\varphi$ if

1. $V=V_{i} \uplus V_{c}$ is set of clauses and $V_{i}=\varphi$,
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4. $\forall C \in V_{c} \exists$ edges $D \rightarrow C, D^{\prime} \rightarrow C$ such that $C$ is resolvent of $D$ and $D^{\prime}$, and
5. there are no other edges.

## Algorithm minUnsatCore $(\varphi)$

| Input: | unsatisfiable formula $\varphi$ |
| :--- | :--- |
| Output: | minimal unsatisfiable core of $\varphi$ |

build resolution graph $G=\left(V_{i} \uplus V_{c}, E\right)$ for $\varphi$
while $\exists$ unmarked clause in $V_{i}$ do
$C \leftarrow$ unmarked clause in $V_{i}$
if SAT $\left(\operatorname{Reach}_{G}(C)\right)$ then mark $C$
$\triangleright$ subgraph without $C$ satisfiable?
$\triangleright C$ is UC member
else
build resolution graph $G^{\prime}=\left(V_{i}^{\prime} \uplus V_{c}^{\prime}, E^{\prime}\right)$ for $\overline{\operatorname{Reach}_{G}(C)}$
$V_{i} \leftarrow V_{i} \backslash\{C\}$ and $V_{c} \leftarrow V_{c}^{\prime} \cup\left(V_{c} \backslash \operatorname{Reach}_{G}(C)\right)$
$E \leftarrow E^{\prime} \cup\left(E \backslash \operatorname{Reach}_{G}^{E}(C)\right)$
$G \leftarrow\left(V_{i} \cup V_{c}, E\right)$
$\left.G \leftarrow G\right|_{B R e a c h} ^{G}(\square) \quad \triangleright$ restrict to nodes with path to $\square$
return $V_{i}$

## Theorem

if $\varphi$ unsatisfiable then minUnsatCore $(\varphi)$ is minimal unsatisfiable core of $\varphi$

## Definition (Partial minUNSAT)

pminUNSAT $(\chi, \varphi)$ is minimal $|\psi|$ such that $\psi \subseteq \varphi$ and $\chi \wedge \bigwedge_{C \in \psi} \neg C$ satisfiable

Lemma

$$
|\varphi|=|\operatorname{pmin} \operatorname{UNSAT}(\chi, \varphi)|+|\operatorname{pmaxSAT}(\chi, \varphi)|
$$

## Theorem

$\operatorname{FuMalik}(\chi, \varphi)=\operatorname{pminUNSAT}(\chi, \varphi)$

```
Algorithm FuMalik \((\chi, \varphi)\)
Input: clause set \(\varphi\) and satisfiable clause set \(\chi\)
Output: minUNSAT \((\chi, \varphi)\)
cost \(\leftarrow 0\)
while \(\neg \operatorname{SAT}(\chi \cup \varphi)\) do
        \(U C \leftarrow\) unsatCore \((\chi \cup \varphi)\)
        \(B \leftarrow \varnothing\)
        for \(C \in U C \cap \varphi\) do \(\quad \triangleright\) loop over soft clauses in core
            \(b \leftarrow\) new blocking variable
            \(\varphi \leftarrow \varphi \backslash\{C\} \cup\{C \vee b\}\)
            \(B \leftarrow B \cup\{b\}\)
    \(\chi \leftarrow \chi \cup \operatorname{CNF}\left(\sum_{b \in B} b=1\right) \quad \triangleright\) cardinality constraint is hard
    return cost
```


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input: $\quad$ formula $\varphi$ involving theory $T$ output:

SAT + valuation $v$ such that $v(\varphi)=T$ UNSAT
if $\varphi$ satisfiable otherwise


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## Example (Theories)

- arithmetic

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2 a+b \geqslant c \vee(a-b=c+3 \wedge p)
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- arithmetic
- uninterpreted functions

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\begin{array}{r}
2 a+b \geqslant c \vee(a-b=c+3 \wedge p) \\
\mathrm{f}(x, y) \neq \mathrm{f}(y, x) \wedge \mathrm{g}(\mathrm{a}) \rightarrow \mathrm{g}(\mathrm{f}(x, x))=\mathrm{g}(y)
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## Example (Theories)

- arithmetic
- uninterpreted functions
- bit vectors

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\left(\left(\text { zext }_{32} a_{8}\right)+b_{32}\right) \times c_{32}>_{u} 0_{32}
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## Definition (Theory of Equality)

theory of equality (EQ) uses binary predicate $\approx$ and consists of axioms
$\forall x .(x \approx x) \quad \forall x y .(x \approx y \rightarrow y \approx x) \quad \forall x y z .(x \approx y \wedge y \approx z \rightarrow x \approx z)$

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## Example

- $u \approx v \wedge \neg(v \approx w)$ is EQ-consistent


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- have $u \approx v \wedge \neg(v \approx w) \vDash_{\mathrm{EQ}} \neg(w \approx u)$ and $u \approx v \equiv_{\mathrm{EQ}} v \approx u$


## Definition (Theory of Equality With Uninterpreted Functions)

EUF over set of function symbols $\mathcal{F}$ consists of equality axioms:
$\forall x .(x \approx x) \quad \forall x y \cdot(x \approx y \rightarrow y \approx x) \quad \forall x y z .(x \approx y \wedge y \approx z \rightarrow x \approx z)$

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EUF ovprent of function cumbale $\mathcal{I}$ anncicte $\begin{aligned} & \text { and } \\ & \text { function symbol } f \text { takes } n>0 \text { arguments }\end{aligned}$
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\forall x_{1} y_{1} \ldots x_{n} y_{n}\left(x_{1} \approx y_{1} \wedge \ldots \wedge x_{n} \approx y_{n} \rightarrow f\left(x_{1}, \ldots, x_{n}\right) \approx f\left(y_{1}, \ldots, y_{n}\right)\right)
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## Uninterpreted Functions in Real Life



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plus for all $f \in \mathcal{F}$ with $n>0$ arguments the functional consistency axiom:

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## Example

EUF over $\mathcal{F}=\{\mathrm{a} / 0, \mathrm{~b} / 0, \mathrm{f} / 1$, add $/ 2\}$ consists of axioms

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- $\mathrm{a} \not \approx \mathrm{b} \wedge \mathrm{f}(\mathrm{a}) \approx \mathrm{f}(\mathrm{b})$ is EUF-consistent


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- $a \neq b \wedge f(a) \approx f(b)$ is EUF-consistent
- $\mathrm{a} \not \approx y \wedge \mathrm{f}(\mathrm{a}) \approx x$ is EUF-consistent


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\forall x_{1} y_{1} \ldots x_{n} y_{n} .\left(x_{1} \approx y_{1} \wedge \cdots \wedge x_{n} \approx y_{n} \rightarrow f\left(x_{1}, \ldots, x_{n}\right) \approx f\left(y_{1}, \ldots, y_{n}\right)\right)
$$

## Example

EUF over $\mathcal{F}=\{\mathrm{a} / 0, \mathrm{~b} / 0, \mathrm{f} / 1$, add $/ 2\}$ consists of axioms

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\forall x(x \approx x) \quad \forall x y(x \approx y \rightarrow y \approx x) \quad \forall x y z(x \approx y \wedge y \approx z \rightarrow x \approx z)
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$$
\begin{gathered}
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$$

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## Application: Verification of Microprocessors

- verify that 3-stage pipelined MIPS processor satisfies intended instruction set architecture


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- EUF ensures functional consistency:
same data results in same computation
( Miroslav N. Velev and Randal E. Bryant.
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## Theories of Interest in SMT Solvers

- equality + uninterpreted functions (EUF) $f(x, a) \approx g(y)$


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- over reals $\mathbb{R}$ (LRA)


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```
read(write(A,i,v),j)
((zext32 a a ) + b 32) × c c32 > }\mp@subsup{u}{u}{}\mp@subsup{0}{32}{
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- solvers: Yices, OpenSMT, MathSAT, Z3, CVC4, Barcelogic, ...


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- still dominant approach for bit-vector arithmetic (known as "bit blasting")
- advantage: use SAT solver off the shelf
- drawbacks:
- expensive translations: infeasible for large formulas
- even more complicated with multiple theories


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- if $\psi$ satisfiable by $v$, check $v$ with $T$-solver:
- if $v$ is $T$-consistent then also $\varphi$ is satisfiable
- otherwise $T$-solver generates $T$-consequence $C$ of $\varphi$ excluding $v$, repeat from 1 with $\varphi \wedge C$


## Example

$$
\mathrm{g}(\mathrm{a}) \approx \mathrm{c} \wedge(\neg(\mathrm{f}(\mathrm{~g}(\mathrm{a})) \approx \mathrm{f}(\mathrm{c})) \vee \mathrm{g}(\mathrm{a}) \approx \mathrm{d}) \wedge \neg(\mathrm{c} \approx \mathrm{~d})
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## Example

$$
\underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{c}}_{x_{1}} \wedge(\neg(\underbrace{\mathrm{f}(\mathrm{~g}(\mathrm{a})) \approx \mathrm{f}(\mathrm{c})}_{x_{2}}) \vee \underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{d})}_{x_{3}} \wedge \neg(\underbrace{\mathrm{c} \approx \mathrm{~d}}_{x_{4}})
$$

- abstract to propositional skeleton $\psi_{1}=x_{1} \wedge\left(\neg x_{2} \vee x_{3}\right) \wedge \neg x_{4}$ satisfiable: $\quad v_{1}\left(x_{1}\right)=\mathrm{T}$ and $v_{1}\left(x_{2}\right)=v_{1}\left(x_{4}\right)=\mathrm{F}$
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## Example

$$
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$T$-unsatisfiable
- block valuation $v_{2}$ in future: add $\neg x_{1} \vee \neg x_{2} \vee \neg x_{3} \vee x_{4}$
- $\psi_{3}=x_{1} \wedge\left(\neg x_{2} \vee x_{3}\right) \wedge \neg x_{4} \wedge\left(\neg x_{1} \vee x_{2} \vee x_{4}\right) \wedge\left(\neg x_{1} \vee \neg x_{2} \vee \neg x_{3} \vee x_{4}\right)$


## Example

$$
\underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{c}}_{x_{1}} \wedge(\neg(\underbrace{\mathrm{f}(\mathrm{~g}(\mathrm{a})) \approx \mathrm{f}(\mathrm{c})}_{x_{2}}) \vee \underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{d}}_{x_{3}}) \wedge \neg(\underbrace{\mathrm{c} \approx \mathrm{~d}}_{x_{4}})
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$T$-unsatisfiable
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- $\psi_{3}=x_{1} \wedge\left(\neg x_{2} \vee x_{3}\right) \wedge \neg x_{4} \wedge\left(\neg x_{1} \vee x_{2} \vee x_{4}\right) \wedge\left(\neg x_{1} \vee \neg x_{2} \vee \neg x_{3} \vee x_{4}\right)$
- unsatisfiable


## Outline

- Summary of Last Week
- Satisfiability Modulo Theories
- DPLL(T)
- Equality and Uninterpreted Functions in Practice


## Approach

- most state-of-the-art SMT solvers use $\operatorname{DPLL}(T)$ :
lazy approach combining DPLL with theory propagation


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- T-backjump $\quad M I^{d} N\left\|F, C \Longrightarrow M I^{\prime}\right\| F, C$ if $M I^{d} N \vDash \neg C$ and $\exists$ clause $C^{\prime} \vee I^{\prime}$ such that
- $F, C \vDash_{T} C^{\prime} \vee I^{\prime}$
- $M \vDash \neg C^{\prime}$ and $I^{\prime}$ is undefined in $M$, and $I^{\prime}$ or $I^{\prime c}$ occurs in $F$ or in $M I^{d} N$


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if $F \not \vDash_{T} C$ and all atoms of $C$ occur in $M$ or $F$
- $T$-forget

$$
M\|F, C \quad \Longrightarrow \quad M\| F
$$

if $F \vDash_{T} C$

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$$
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$$

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$$
M\|F, C \quad \Longrightarrow \quad M\| F
$$

if $F \vDash_{T} C$

- T-propagate
$M\|F \quad \Longrightarrow \quad M I\| F$
if $M \vDash_{T} I$, literal $/$ or $I^{c}$ occurs in $F$, and $/$ is undefined in $M$


## Naive Lazy Approach in DPLL( $T$ )

- whenever state $M \| F$ is final wrt unit propagate, decide, fail, $T$-backjump: check $T$-consistency of $M$ with $T$-solver


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## Improvement 1: Incremental $T$-Solver

- $T$-solver checks $T$-consistency of model $M$ whenever literal is added to $M$


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## Improvement 1: Incremental T-Solver

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## Improvement 2: On-Line SAT solver

- after $T$-learn added clause, apply fail or $T$-backjump instead of restart


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- apply $T$-propagate before decide


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## Remark

all three improvements can be combined

## Example (Revisited with DPLL( $T$ ))

$$
\begin{aligned}
& \underbrace{g(a) \approx c}_{1} \wedge(\neg(\underbrace{f(g(a))) \approx f(c)}_{2}) \vee \underbrace{g(a) \approx d}_{3}) \wedge \neg(\underbrace{c \approx d}_{4}) \\
& \| 1,(\overline{2} \vee 3), \overline{4}
\end{aligned}
$$

## Example (Revisited with DPLL( $T$ ))

$$
\underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{c}}_{1} \wedge(\neg(\underbrace{\mathrm{f}(\mathrm{~g}(\mathrm{a})) \approx \mathrm{f}(\mathrm{c})}_{2}) \vee \underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{d}}_{3}) \wedge \neg(\underbrace{\mathrm{c} \approx \mathrm{~d}}_{4})
$$

$$
\begin{array}{r}
\| 1,(\overline{2} \vee 3), \overline{4} \\
1 \| 1,(\overline{2} \vee 3), \overline{4}
\end{array}
$$

unit propagate

## Example (Revisited with DPLL( $T$ ))

$$
\underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{c}}_{1} \wedge(\neg(\underbrace{\mathrm{f}(\mathrm{~g}(\mathrm{a})) \approx \mathrm{f}(\mathrm{c})}_{2}) \vee \underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{d}}_{3}) \wedge \neg(\underbrace{\mathrm{c} \approx \mathrm{~d}}_{4})
$$

$$
\begin{array}{r}
\| 1,(\overline{2} \vee 3), \overline{4} \\
1 \| 1,(\overline{2} \vee 3), \overline{4} \\
1 \overline{4} \| 1,(\overline{2} \vee 3), \overline{4}
\end{array}
$$

unit propagate unit propagate

## Example (Revisited with DPLL( $T$ ))

$$
\underbrace{g(a) \approx c}_{1} \wedge(\neg(\underbrace{f(g(a)) \approx f(c)}_{2}) \vee \underbrace{g(a) \approx d}_{3}) \wedge \neg(\underbrace{c \approx d}_{4})
$$

|  | $\\| 1,(\overline{2} \vee 3), \overline{4}$ |  |
| ---: | ---: | ---: |
| $\Longrightarrow$ | $1 \\| 1,(\overline{2} \vee 3), \overline{4}$ | unit propagate |
| $\Longrightarrow$ | $1 \overline{4} \\| 1,(\overline{2} \vee 3), \overline{4}$ | unit propagate |
| $\Longrightarrow$ | $1 \overline{4}^{d} \\| 1,(\overline{2} \vee 3), \overline{4}$ | decide |

## Example (Revisited with DPLL( $T$ ))

$$
\underbrace{g(a) \approx c}_{1} \wedge(\neg(\underbrace{f(g(a)) \approx f(c)}_{2}) \vee \underbrace{g(a) \approx d}_{3}) \wedge \neg(\underbrace{c \approx d}_{4})
$$

|  | $\\| 1,(\overline{2} \vee 3), \overline{4}$ |  |
| :--- | ---: | ---: |
| $\Longrightarrow$ | $1 \\| 1,(\overline{2} \vee 3), \overline{4}$ | unit propagate |
| $\Longrightarrow$ | $1 \overline{4} \\| 1,(\overline{2} \vee 3), \overline{4}$ | unit propagate |
| $\Longrightarrow$ | $1 \overline{4}^{d} \\| 1,(\overline{2} \vee 3), \overline{4}$ | decide |
| $\Longrightarrow$ | $1 \overline{4}^{d} \overline{2}^{d} \\| 1,(\overline{2} \vee 3), \overline{4},(\overline{1} \vee 2 \vee 4)$ | $T$-learn |

## Example (Revisited with DPLL( $T$ ))

$$
\underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{c}}_{1} \wedge(\neg(\underbrace{\mathrm{f}(\mathrm{~g}(\mathrm{a})) \approx \mathrm{f}(\mathrm{c})}_{2}) \vee \underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{d}}_{3}) \wedge \neg(\underbrace{\mathrm{c} \approx \mathrm{~d}}_{4})
$$

$$
\begin{gathered}
\| 1,(\overline{2} \vee 3), \overline{4} \\
1 \| 1,(\overline{2} \vee 3), \overline{4} \\
1 \overline{4} \| 1,(\overline{2} \vee 3), \overline{4} \\
1 \overline{4} \overline{2}^{d} \| 1,(\overline{2} \vee 3), \overline{4} \\
1 \overline{4} \overline{2}^{d} \| 1,(\overline{2} \vee 3), \overline{4},(\overline{1} \vee 2 \vee 4) \\
1 \overline{4} 2 \| 1,(\overline{2} \vee 3), \overline{4},(\overline{1} \vee 2 \vee 4)
\end{gathered}
$$

unit propagate unit propagate decide $T$-learn
$T$-backjump

## Example (Revisited with DPLL( $T$ ))

$$
\underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{c}}_{1} \wedge(\neg(\underbrace{\mathrm{f}(\mathrm{~g}(\mathrm{a})) \approx \mathrm{f}(\mathrm{c})}_{2}) \vee \underbrace{\mathrm{g}(\mathrm{a}) \approx \mathrm{d}}_{3}) \wedge \neg(\underbrace{\mathrm{c} \approx \mathrm{~d}}_{4})
$$

|  | $\\| 1,(\overline{2} \vee 3), \overline{4}$ |
| :---: | :---: |
| $\Longrightarrow$ | $1 \\| 1,(\overline{2} \vee 3), \overline{4}$ |
| $\Longrightarrow$ | $1 \overline{4} \\| 1,(\overline{2} \vee 3), \overline{4}$ |
| $\Longrightarrow$ | $1 \overline{4} \overline{2}^{d} \\| 1,(\overline{2} \vee 3), \overline{4}$ |
| $\Longrightarrow$ | $1 \overline{4} \overline{2}^{d} \\| 1,(\overline{2} \vee 3), \overline{4},(\overline{1} \vee 2 \vee 4)$ |
| $\Longrightarrow$ | $1 \overline{4} 2 \\| 1,(\overline{2} \vee 3), \overline{4},(\overline{1} \vee 2 \vee 4)$ |
| $\Longrightarrow$ | $1 \overline{4} 23 \\| 1,(\overline{2} \vee 3), \overline{4},(\overline{1} \vee 2 \vee 4)$ |

unit propagate unit propagate decide $T$-learn $T$-backjump unit propagate

## Example (Revisited with DPLL( $T$ ))



## Lazyness in DPLL( $T$ )


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## Lazyness in DPLL( $T$ )


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$T$-solver
SAT solver

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## - Summary of Last Week

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## Example (SMT-LIB 2 for Propositional Logic)

formula $\left(x_{1} \vee \neg x_{3}\right) \wedge\left(x_{2} \vee x_{3} \vee \neg x_{1}\right) \wedge\left(\neg x_{1} \vee x_{2} \vee x_{3}\right)$ can be expressed by

```
(declare-const x1 Bool)
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## Example (SMT-LIB 2 for Propositional Logic)

formula $\left(x_{1} \vee \neg x_{3}\right) \wedge\left(x_{2} \vee x_{3} \vee \neg x_{1}\right) \wedge\left(\neg x_{1} \vee x_{2} \vee x_{3}\right)$ can be expressed by

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- get-model prints model (after satisfiability check)


## Example (SMT-LIB 2 for EUF)

$\mathrm{f}(\mathrm{f}(\mathrm{a})) \approx \mathrm{a} \wedge \mathrm{f}(\mathrm{a}) \approx \mathrm{b} \wedge \neg(\mathrm{a} \approx \mathrm{b})$ is expressed as

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(declare-sort A)
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- (distinct $x y$ ) is equivalent to not (= $x$ y)


## Example

$2 x \geqslant y+z \wedge \neg(x \approx y)$ is expressed as

```
(declare-const x Int)
(declare-const y Int)
(declare-const z Int)
(assert (>= (* 2 x) (+ y z)))
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$><,<=,>,>=\operatorname{are}<_{\mathbb{Z}}, \leqslant_{\mathbb{Z}},>_{\mathbb{Z}}, \geqslant_{\mathbb{Z}}$


## EUF in python/z3

```
A = DeclareSort('A') # new uninterpreted sort named 'A'
a = Const('a', A) # create constant of sort A
b = Const('b', A) # create another constant of sort A
f = Function('f', A, A) # create function of sort A -> A
s = Solver()
s.add(f(f(a)) == a, f(a) == b, a != b)
print s.check() # sat
m = s.model()
print "interpretation assigned to A:"
print m[A] # [A!val!0, A!val!1]
print "interpretations:"
print m[f] # [A!val!0 -> A!val!1, A!val!1 -> A!val!0, ...]
print m[a] # A!val!0
print m[b] # A!val!1
```


## Example (Quantifiers and Monkeys)

In a village of monkeys every monkey owns at least two bananas:

```
(declare-sort monkey)
(declare-sort banana)
(declare-fun owns (monkey banana) Bool)
(declare-fun b1 (monkey) banana)
(declare-fun b2 (monkey) banana)
(assert (forall ((M monkey)) (not (= (b1 M) (b2 M)))))
(assert (forall ((M monkey)) (owns M (b1 M))))
(assert (forall ((M monkey)) (owns M (b2 M))))
(assert (forall ((M1 monkey) (M2 monkey) (B banana))
    (implies (and (owns M1 B) (owns M2 B)) (= M1 M2))))
```


## DPLL( $T$ )

Robert Nieuwenhuis, Albert Oliveras, and Cesare Tinelli. Solving SAT and SAT Modulo Theories: From an Abstract Davis-Putnam-Logemann-Loveland Procedure to DPLL(T). Journal of the ACM 53(6), pp. 937-977, 2006.

## Application

$\square$ Miroslav N. Velev and Randal E. Bryant.
Bit-level abstraction in the verification of pipelined microprocessors by correspondence checking.
In Proc. of Formal Methods in Computer-Aided Design, pp. 18-35, 1998.

