



Program Verification

Part 3 – Semantics of Functional Programs

René Thiemann

Department of Computer Science

Overview

- definition of a small functional programming language
- operational semantics
- a model in many-sorted logic
- derived inference rules

Functional Programming – Data Types

Data Type Definitions

- a functional program contains a sequence of **data type definitions**
- while processing the sequence, we determine the set of types \mathcal{T}_y , the signature Σ , and the predicates \mathcal{P} , which are all initially empty
- each data type definition has the following form

$$\begin{array}{l} \text{data } \tau = c_1 : \tau_{1,1} \times \dots \times \tau_{1,m_1} \rightarrow \tau \\ \quad | \dots \\ \quad | c_n : \tau_{n,1} \times \dots \times \tau_{n,m_n} \rightarrow \tau \end{array}$$

where

- $\tau \notin \mathcal{T}_y$ fresh type name
- $c_1, \dots, c_n \notin \Sigma$ and $c_i \neq c_j$ for $i \neq j$ fresh and distinct constructor names
- each $\tau_{i,j} \in \{\tau\} \cup \mathcal{T}_y$ only known types
- exists c_i such that $\tau_{i,j} \in \mathcal{T}_y$ for all j non-recursive constructor
- effect: add type, constructors and equality predicate
 - $\mathcal{T}_y := \mathcal{T}_y \cup \{\tau\}$
 - $\Sigma := \Sigma \cup \{c_1 : \tau_{1,1} \times \dots \times \tau_{1,m_1} \rightarrow \tau, \dots, c_n : \tau_{n,1} \times \dots \times \tau_{n,m_n} \rightarrow \tau\}$
 - $\mathcal{P} := \mathcal{P} \cup \{=_{\tau} \subseteq \tau \times \tau\}$

Data Type Definitions: Examples

- $\mathcal{T}_y = \Sigma = \mathcal{P} = \emptyset$
- **data** $\text{Nat} = \text{Zero} : \text{Nat} \mid \text{Succ} : \text{Nat} \rightarrow \text{Nat}$
- processing updates $\mathcal{T}_y = \{\text{Nat}\}$,
 $\Sigma = \{\text{Zero} : \text{Nat}, \text{Succ} : \text{Nat} \rightarrow \text{Nat}\}$
 and $\mathcal{P} = \{=_{\text{Nat}} \subseteq \text{Nat} \times \text{Nat}\}$
- **data** $\text{List} = \text{Nil} : \text{List} \mid \text{Cons} : \text{Nat} \times \text{List} \rightarrow \text{List}$
- processing updates $\mathcal{T}_y = \{\text{Nat}, \text{List}\}$,
 $\Sigma = \{\text{Zero} : \text{Nat}, \text{Succ} : \text{Nat} \rightarrow \text{Nat}, \text{Nil} : \text{List}, \text{Cons} : \text{Nat} \times \text{List} \rightarrow \text{List}\}$
 and $\mathcal{P} = \{=_{\text{Nat}} \subseteq \text{Nat} \times \text{Nat}, =_{\text{List}} \subseteq \text{List} \times \text{List}\}$
- **data** $\text{BList} = \text{NilB} : \text{BList} \mid \text{ConsB} : \text{Bool} \times \text{BList} \rightarrow \text{BList}$
 not allowed, since $\text{Bool} \notin \mathcal{T}_y$
- **data** $\text{LList} = \text{Nil} : \text{LList} \mid \text{Cons} : \text{List} \times \text{LList} \rightarrow \text{LList}$
 not allowed, since Nil and Cons are already in Σ
- **data** $\text{Tree} = \text{Node} : \text{Tree} \times \text{Nat} \times \text{Tree} \rightarrow \text{Tree}$
 not allowed, since all constructors are recursive

Data Type Definitions: Standard Model

- while processing data type definitions we also build a model \mathcal{M} for the functional program, called the **standard model**
- when processing

$$\begin{array}{l} \text{data } \tau = c_1 : \tau_{1,1} \times \dots \times \tau_{1,m_1} \rightarrow \tau \\ \quad \quad \quad | \dots \\ \quad \quad \quad | c_n : \tau_{n,1} \times \dots \times \tau_{n,m_n} \rightarrow \tau \end{array}$$

- define universe \mathcal{A}_τ for new type τ inductively via the following inference rules (one for each $1 \leq i \leq n$)

$$\frac{t_1 \in \mathcal{A}_{\tau_{i,1}} \quad \dots \quad t_{m_i} \in \mathcal{A}_{\tau_{i,m_i}}}{c_i(t_1, \dots, t_{m_i}) \in \mathcal{A}_\tau}$$

- define $c_i^{\mathcal{M}}(t_1, \dots, t_{m_i}) = c_i(t_1, \dots, t_{m_i})$
- define $=_\tau^{\mathcal{M}} = \{(t, t) \mid t \in \mathcal{A}_\tau\}$

uninterpreted constructors
equality

Data Type Definitions: Example and Standard Model

- **data** $\text{Nat} = \text{Zero} : \text{Nat} \mid \text{Succ} : \text{Nat} \rightarrow \text{Nat}$
- processing creates universe \mathcal{A}_{Nat} via the inference rules

$$\frac{}{\text{Zero} \in \mathcal{A}_{\text{Nat}}} \qquad \frac{t \in \mathcal{A}_{\text{Nat}}}{\text{Succ}(t) \in \mathcal{A}_{\text{Nat}}}$$

i.e., $\mathcal{A}_{\text{Nat}} = \{\text{Zero}, \text{Succ}(\text{Zero}), \text{Succ}(\text{Succ}(\text{Zero})), \dots\}$

- $\text{Zero}^{\mathcal{M}} = \text{Zero} \quad \text{Succ}^{\mathcal{M}}(t) = \text{Succ}(t)$
- $=_{\text{Nat}}^{\mathcal{M}} = \{(\text{Zero}, \text{Zero}), (\text{Succ}(\text{Zero}), \text{Succ}(\text{Zero})), \dots\}$
- **data** $\text{List} = \text{Nil} : \text{List} \mid \text{Cons} : \text{Nat} \times \text{List} \rightarrow \text{List}$
- processing creates universe $\mathcal{A}_{\text{List}}$ via the inference rules

$$\frac{}{\text{Nil} \in \mathcal{A}_{\text{List}}} \qquad \frac{t_1 \in \mathcal{A}_{\text{Nat}} \quad t_2 \in \mathcal{A}_{\text{List}}}{\text{Cons}(t_1, t_2) \in \mathcal{A}_{\text{List}}}$$

i.e., $\mathcal{A}_{\text{List}} = \{\text{Nil}, \text{Cons}(\text{Zero}, \text{Nil}), \text{Cons}(\text{Succ}(\text{Zero}), \text{Nil}), \dots\}$

- $=_{\text{List}}^{\mathcal{M}} = \{(\text{Nil}, \text{Nil}), (\text{Cons}(\text{Zero}, \text{Nil}), \text{Cons}(\text{Zero}, \text{Nil})), \dots\}$

Well-Definedness of Standard Model

- question: is the standard model really a model in the sense of many-sorted logic
 - is there a unique type for each $c_i \in \Sigma$ and $=_\tau \in \mathcal{P}$
 - are the definitions of c_i^M and $=_\tau^M$ well-defined
 - are the definitions of \mathcal{A}_τ well-defined, i.e., $\mathcal{A}_\tau \neq \emptyset$
- recall: each data definition has the following form

$$\begin{array}{l}
 \text{data } \tau = c_1 : \tau_{1,1} \times \dots \times \tau_{1,m_1} \rightarrow \tau \\
 \quad \quad \quad | \dots \\
 \quad \quad \quad | c_n : \tau_{n,1} \times \dots \times \tau_{n,m_n} \rightarrow \tau
 \end{array}$$

where

- $\tau \notin \mathcal{T}_y$ fresh type name
- $c_1, \dots, c_n \notin \Sigma$ and $c_i \neq c_j$ for $i \neq j$ fresh and distinct constructor names
- each $\tau_{i,j} \in \{\tau\} \cup \mathcal{T}_y$ only known types
- exists c_i such that $\tau_{i,j} \in \mathcal{T}_y$ for all j non-recursive constructor
- what could happen if one of the conditions is dropped?

Non-Empty Universes

- without the last condition (non-recursive constructor) the following data type declaration would be allowed (assuming that `Nat` and `Succ` are fresh names)

`data Nat = Succ : Nat → Nat`

with the universe defined as the inductive set \mathcal{A}_{Nat}

$$\frac{t \in \mathcal{A}_{\text{Nat}}}{\text{Succ}(t) \in \mathcal{A}_{\text{Nat}}}$$

- consequence: $\mathcal{A}_{\text{Nat}} = \emptyset$
- hence, non-recursive constructors are essential for having non-empty universes

Non-Empty Universes: Proof

Theorem

Let there be a list of data type declarations and an arbitrary type τ from this list. Then $\mathcal{A}_\tau \neq \emptyset$.

Proof

Let τ_1, \dots, τ_n be the sequence of types that have been defined. We show

$$P(n) := \forall 1 \leq i \leq n. \mathcal{A}_{\tau_i} \neq \emptyset$$

by induction on n . This will entail the theorem.

In the base case we have to prove $P(0)$, which is trivially true. Now let us show $P(n+1)$ assuming $P(n)$. Because of $P(n)$, we only have to prove $\mathcal{A}_{\tau_{n+1}} \neq \emptyset$. By the definition of data types, there must be some $c_i : \tau_{i,1} \times \dots \times \tau_{i,m_i} \rightarrow \tau_{n+1}$ where all $\tau_{i,j} \in \{\tau_1, \dots, \tau_n\}$. By the IH $P(n)$ we know that $\mathcal{A}_{\tau_{i,j}} \neq \emptyset$ for all j between 1 and m_i . Hence, there must be terms $t_1 \in \mathcal{A}_{\tau_{i,1}}, \dots, t_{m_i} \in \mathcal{A}_{\tau_{i,m_i}}$. Consequently, $c_i(t_1, \dots, t_{m_i}) \in \mathcal{A}_{\tau_{n+1}}$, and hence $\mathcal{A}_{\tau_{n+1}} \neq \emptyset$.

Current State



- presented: data type definitions
- semantics:
 - free constructors: each constructor is interpreted as itself
 - universe as inductively defined sets: no infinite terms, such as infinite lists
`Cons(Zero, Cons(Zero, ...))`
(modeling of infinite data structures would be possible via domain-theory)
- upcoming: functional programs, i.e., function definitions

Functional Programming – Function Definitions

Splitting the signature

- distinguish between
 - **constructors**, declared via **data** (capital letters in Haskell)
e.g., **Nil**, **Succ**, **Cons**
 - **defined functions**, declared via equations (lowercase letters in Haskell)
e.g., **append**, **add**, **reverse**
- formally, we have $\Sigma = \mathcal{C} \uplus \mathcal{D}$
- \mathcal{C} is set of constructors, defined via **data**
 - constructors are written c, c_i, d in generic constructors such as data type definitions
 - start with uppercase letters in concrete examples (**Succ**, **Cons**)
- \mathcal{D} is set of defined symbols, defined via function declarations
 - defined (function) symbols are written f, f_i, g in generic constructors such as function definitions
 - start with lowercase letters in concrete examples (**append**, **reverse**)
- we use F, G for elements of Σ whenever separation between \mathcal{C} and \mathcal{D} is not relevant
- note that in the standard model, \mathcal{A}_τ is exactly $\mathcal{T}(\mathcal{C})_\tau := \mathcal{T}(\mathcal{C}, \emptyset)_\tau$, which is the set of **constructor ground terms** of type τ

Notions for Preparing Function Definitions

- a **pattern** is a term in $\mathcal{T}(\mathcal{C}, \mathcal{V})$, usually written p or p_i
- a term t in $\mathcal{T}(\Sigma, \mathcal{V})$ is **linear**, if all variables within t occur only once
 - `reverse(Cons(x, Cons(y, xs)))` 
 - `reverse(Cons(x, Cons(x, xs)))` 
- the **variables of a term** t are defined as $\mathcal{Vars}(t)$
 - $\mathcal{Vars}(x) = \{x\}$
 - $\mathcal{Vars}(F(t_1, \dots, t_n)) = \mathcal{Vars}(t_1) \cup \dots \cup \mathcal{Vars}(t_n)$

Function Definitions

- besides data type definitions, a functional program consists of a sequence of **function definitions**, each having the following form

$$\begin{aligned}
 f &: \tau_1 \times \dots \times \tau_n \rightarrow \tau \\
 \ell_1 &= r_1 \\
 \dots &= \dots \\
 \ell_m &= r_m
 \end{aligned}$$

where

- f is a **fresh name** and $\mathcal{D} := \mathcal{D} \cup \{f : \tau_1 \times \dots \times \tau_n \rightarrow \tau\}$ (hence, f is also added to $\Sigma = \mathcal{C} \cup \mathcal{D}$)
- each left-hand side (lhs) ℓ_i is **linear**
- each lhs ℓ_i is of the form $f(p_1, \dots, p_n)$ with all p_j 's being **patterns**
- each lhs ℓ_i and rhs r_i **respect the type**: $\ell_i, r_i \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$
- each equation $\ell_i = r_i$ satisfies the **variable condition** $\text{Vars}(r_i) \subseteq \text{Vars}(\ell_i)$

Function Definitions: Examples

- assume data types `Nat` and `List` have been defined as before (slide 5)

`add` : `Nat` × `Nat` → `Nat`

`add`(`Zero`, y) = y

`add`(`Succ`(x), y) = `add`(x , `Succ`(y))

`append` : `List` × `List` → `List`

`append`(`Cons`(x , xs), ys) = `Cons`(x , `append`(xs , ys))

`append`(xs , ys) = ys

`head` : `List` → `Nat`

`head`(`Cons`(x , xs)) = x

`zeros` : `List`

`zeros` = `Cons`(`Zero`, `zeros`)

Function Definitions: Non-Examples

- assume program from previous slides + `data Bool = True | False`

`even : Nat → Bool`

`even(Zero) = True`

`even(Succ(x)) = odd(x)` ✗

`odd : Nat → Bool`

`odd(Zero) = False`

`odd(Succ(x)) = even(x)` ✗

`random : Nat`

`random = x` ✗

`minus : Nat × Nat → Nat`

`minus(Succ(x), Succ(y)) = minus(x, y)`

`minus(x, Zero) = x`

`minus(x, x) = Zero` ✗

`minus(add(x, y), x) = y` ✗

Semantics for Function Definitions

- problem: given a function definition

$$f : \tau_1 \times \dots \times \tau_n \rightarrow \tau$$

$$\ell_1 = r_1$$

$$\dots = \dots$$

$$\ell_m = r_m$$

we need to extend the semantics in the standard model, i.e., define the function

$$f^{\mathcal{M}} : \mathcal{A}_{\tau_1} \times \dots \times \mathcal{A}_{\tau_n} \rightarrow \mathcal{A}_{\tau}$$

or equivalently

$$f^{\mathcal{M}} : \mathcal{T}(\mathcal{C})_{\tau_1} \times \dots \times \mathcal{T}(\mathcal{C})_{\tau_n} \rightarrow \mathcal{T}(\mathcal{C})_{\tau}$$

- idea: define $f^{\mathcal{M}}(t_1, \dots, t_n)$ as

the result of $f(t_1, \dots, t_n)$ after evaluation wrt. equations in program

Semantics for Function Definitions – Continued

- required: $f^{\mathcal{M}} : \mathcal{T}(\mathcal{C})_{\tau_1} \times \dots \times \mathcal{T}(\mathcal{C})_{\tau_n} \rightarrow \mathcal{T}(\mathcal{C})_{\tau}$
- idea: define $f^{\mathcal{M}}(t_1, \dots, t_n)$ as
 - the result of $f(t_1, \dots, t_n)$ after evaluation wrt. equations in program
- several issues:
 - how is term **evaluation** defined?
 - briefly: replace instances of lhss by instances of rhss as long as possible
 - is result **unique**?
 - is result element of $\mathcal{T}(\mathcal{C})_{\tau}$?
 - does evaluation **terminate**?

Function Definitions: Examples

- consider previous program, type declarations omitted

$$\text{add}(\text{Zero}, y) = y \tag{1}$$

$$\text{add}(\text{Succ}(x), y) = \text{add}(x, \text{Succ}(y)) \tag{2}$$

$$\text{append}(\text{Cons}(x, xs), ys) = \text{Cons}(x, \text{append}(xs, ys)) \tag{3}$$

$$\text{append}(xs, ys) = ys \tag{4}$$

$$\text{head}(\text{Cons}(x, xs)) = x \tag{5}$$

$$\text{zeros} = \text{Cons}(\text{Zero}, \text{zeros}) \tag{6}$$

- is result **unique**? no: consider $t = \text{append}(\text{Cons}(\text{Zero}, \text{Nil}), \text{Nil})$

$$\text{then } t \stackrel{(3)}{=} \text{Cons}(\text{Zero}, \text{append}(\text{Nil}, \text{Nil})) \stackrel{(4)}{=} \text{Cons}(\text{Zero}, \text{Nil})$$

$$\text{and } t \stackrel{(4)}{=} \text{Nil}$$

- is result element of $\mathcal{T}(\mathcal{C})_\tau$? no: $\text{head}(\text{Nil})$ cannot be evaluated
- does evaluation **terminate**? no: $\text{zeros} = \text{Cons}(\text{Zero}, \text{zeros}) = \dots$
- solution: further restrictions on function definitions

Functional Programming – Operational Semantics

Functional Programming: Operational Semantics

- operational semantics: formal definition on how evaluation proceeds step-by-step
- main operation: applying a substitution $\sigma : \mathcal{V} \rightarrow \mathcal{T}(\Sigma, \mathcal{V})$ on a term, can be defined recursively
 - $x\sigma = \sigma(x)$
 - $F(t_1, \dots, t_n)\sigma = F(t_1\sigma, \dots, t_n\sigma)$
- one-step evaluation relation $\hookrightarrow \subseteq \mathcal{T}(\Sigma, \mathcal{V}) \times \mathcal{T}(\Sigma, \mathcal{V})$ defined as inductive set

$$\frac{\ell = r \text{ is equation in program}}{\ell\sigma \hookrightarrow r\sigma} \text{ root step}$$

$$\frac{F \in \Sigma \quad s_i \hookrightarrow t_i}{F(s_1, \dots, s_i, \dots, s_n) \hookrightarrow F(s_1, \dots, t_i, \dots, s_n)} \text{ rewrite in contexts}$$

- given a term t and a lhs ℓ , for checking whether a root-step is applicable one needs **matching**: $\exists\sigma. \ell\sigma = t$ (and also deliver that σ)
- same evaluation as in functional programming (lecture), except that **order of equations is ignored** and here it becomes **formal**

Matching

- we define matching as an operation on a set of pairs $P = \{(\ell_1, t_1), \dots, (\ell_n, t_n)\}$ and the task is to decide: $\exists \sigma. \ell_1 \sigma = t_1 \wedge \dots \wedge \ell_n \sigma = t_n$, i.e.,
 - either return the required substitution σ in the form of a set of pairs $\{(x_1, s_1), \dots, (x_m, s_m)\}$ with all x_i distinct which can then be interpreted as the substitution σ defined by

$$\sigma(x) = \begin{cases} s_i, & \text{if } x = x_i \text{ for some } i \\ x, & \text{otherwise} \end{cases}$$

- or return \perp indicating that no such substitution exists
- matching algorithm**
 - if P contains a pair $(F(\ell_1, \dots, \ell_n), F(t_1, \dots, t_n))$, then replace this pair by the n pairs $(\ell_1, t_1), \dots, (\ell_n, t_n)$ decompose
 - if P contains $(F(\dots), G(\dots))$ with $F \neq G$, then return \perp clash
 - if P contains $(F(\dots), x)$ with $x \in \mathcal{V}$, then return \perp fun-var
 - if P contains (x, s) and (x, t) with $x \in \mathcal{V}$ and $s \neq t$, then return \perp var-clash
 - if none of the above rules is applicable, then return P

Matching – Example

- we want to test whether there is a root step possible for the term
 $t = \text{append}(\text{Cons}(y, \text{Nil}), \text{Cons}(y, ys))$ w.r.t. the equation
 $(\ell = r) = (\text{append}(\text{Cons}(x, xs), ys) = \text{Cons}(x, \text{append}(xs, ys)))$
- setup matching problem $\{(\ell, t)\}$
 $P = \{(\text{append}(\text{Cons}(x, xs), ys), \text{append}(\text{Cons}(y, \text{Nil}), \text{Cons}(y, ys)))\}$
- decomposition: $P = \{(\text{Cons}(x, xs), \text{Cons}(y, \text{Nil})), (ys, \text{Cons}(y, ys))\}$
- decomposition: $P = \{(x, y), (xs, \text{Nil}), (ys, \text{Cons}(y, ys))\}$
- obtain substitution $\sigma(z) = \begin{cases} y, & \text{if } z = x \\ \text{Nil}, & \text{if } z = xs \\ \text{Cons}(y, ys), & \text{if } z = ys \\ z, & \text{otherwise} \end{cases}$
- so, $t = \ell\sigma \hookrightarrow r\sigma = \text{Cons}(x, \text{append}(xs, ys))\sigma = \text{Cons}(y, \text{append}(\text{Nil}, \text{Cons}(y, ys)))$

Matching – Verification and Termination Proof

- matching algorithm
 - whenever P contains a pair $(F(\ell_1, \dots, \ell_n), F(t_1, \dots, t_n))$, replace this pair by the n pairs $(\ell_1, t_1), \dots, (\ell_n, t_n)$ decompose
 - ...
- soundness = termination + partial verification
- **termination**: in each step, the sum of the size of terms is decreased

$$\begin{aligned}
 |(F(\ell_1, \dots, \ell_n), F(t_1, \dots, t_n))| &= |F(\ell_1, \dots, \ell_n)| + |F(t_1, \dots, t_n)| \\
 &= 1 + \sum_i |\ell_i| + 1 + \sum_i |t_i| \\
 &> \sum_i |\ell_i| + \sum_i |t_i| \\
 &= \sum_i |(\ell_i, t_i)|
 \end{aligned}$$

Matching – Type Preservation

- matching algorithm
 - whenever P contains a pair $(F(\ell_1, \dots, \ell_n), F(t_1, \dots, t_n))$, replace this pair by the n pairs $(\ell_1, t_1), \dots, (\ell_n, t_n)$ decompose
 - ...
- property: we say that a **set of pairs P is type-correct**, iff for all pairs $(\ell, t) \in P$ the types of ℓ and t are identical, i.e., $\exists \tau. \{\ell, t\} \subseteq \mathcal{T}(\Sigma, \mathcal{V})_\tau$
- theorem: whenever P is type-correct, then P will stay type-correct during the algorithm; consequently, any result $\neq \perp$ will be type-correct
- proof: we prove an invariant, so we only need to prove that the property is maintained when performing a step in the algorithm:
consider "decompose"
 - we can assume $\{F(\ell_1, \dots, \ell_n), F(t_1, \dots, t_n)\} \subseteq \mathcal{T}(\Sigma, \mathcal{V})_\tau$
 - so $F : \tau_1 \times \dots \times \tau_n \rightarrow \tau$ for suitable τ_i
 - hence, $\{\ell_i, t_i\} \subseteq \mathcal{T}(\Sigma, \mathcal{V})_{\tau_i}$ for all i

Matching – Structure of Result

- matching algorithm
 - whenever P contains $(F(\ell_1, \dots, \ell_n), F(t_1, \dots, t_n)) \dots$ decompose
 - whenever P contains $(F(\dots), G(\dots))$ with $F \neq G$, then return \perp clash
 - whenever P contains $(F(\dots), x)$ with $x \in \mathcal{V}$, then return \perp fun-var
 - whenever P contains (x, s) and (x, t) with $x \in \mathcal{V}$ and $s \neq t$ then return \perp var-clash
 - when none of the above rules is applicable, return P
- property: **result of matching algorithm** on well-typed inputs is \perp or set $\{(x_1, s_1), \dots, (x_m, s_m)\}$ with all x_i distinct
- proof
 - assume result is not \perp , then it must be some set of pairs $P = \{(u_1, s_1), \dots, (u_m, s_m)\}$ where no rule is applicable
 - if all u_i 's are variables, then the result follows: there cannot be two entries (u_i, s_i) and (u_j, s_j) with $u_i = u_j$ and $s_i \neq s_j$ because then "var-clash" would have been applied
 - it remains to consider the case that some $u_i = F(\ell_1, \dots, \ell_n)$
 - $s_i = F(t_1, \dots, t_k)$, as result is not \perp , cf. "clash" and "fun-var"
 - then $k = n$ because of type preservation: contraction to "decompose"

Matching – Preservation of Solutions

- matching algorithm
 - whenever P contains a pair $(F(\ell_1, \dots, \ell_n), F(t_1, \dots, t_n))$, replace this pair by the n pairs $(\ell_1, t_1), \dots, (\ell_n, t_n)$ decompose
 - whenever P contains $(F(\dots), G(\dots))$ with $F \neq G$, then return \perp clash
 - whenever P contains $(F(\dots), x)$ with $x \in \mathcal{V}$, then return \perp fun-var
 - whenever P contains (x, s) and (x, t) with $x \in \mathcal{V}$ and $s \neq t$ then return \perp var-clash
 - when none of the above rules is applicable, return P
- property: algorithm preserves matching substitutions (where \perp has no matching substitution)
- proof via invariant: whenever P is changed to P' , then σ is a matcher of P iff σ is matcher of P'
 - clash: both " σ is matcher of $\{(F(\dots), G(\dots))\} \cup P$ " and " σ is matcher of \perp " are wrong: $F(t_1, \dots)\sigma = F(t_1\sigma, \dots) \neq G(\dots)$
 - fun-var and var-clash are similar
 - decompose: $F(\ell_1, \dots, \ell_n)\sigma = F(t_1, \dots, t_n)$
 - $\iff F(\ell_1\sigma, \dots, \ell_n\sigma) = F(t_1, \dots, t_n)$
 - $\iff \ell_1\sigma = t_1 \wedge \dots \wedge \ell_n\sigma = t_n$

Matching Algorithm – Summary

- algorithm: apply certain steps until no longer possible
- (one) termination proof
- (many) partial soundness proofs
mainly by showing an invariant that is preserved by each step
 - type preservation
 - preservation of matching substitutions
 - result is \perp or a set which encodes a substitution
- application: compute root steps by testing whether decomposition of term into $\ell\sigma$ for equation $\ell = r$ is possible
- core of functional programming (and term rewriting)
- much better algorithms exists, which avoid to match against **all** lhss, based on precalculation (term indexing), e.g., group equations by root symbol of lhss

Semantics in the Standard Model

Towards Semantics in Standard Model

- evaluation of terms is now explained: one-step relation \hookrightarrow
- algorithm for evaluation is similar to matching algorithm:
 apply \hookrightarrow -steps until no longer possible
- questions are similar as in matching algorithm
 - termination: do we always get result?
 - preservation of types?
 - is result a desired value, i.e., a constructor ground term?
 - is result unique?
- questions don't have positive answer in general, cf. slide 20

Type Preservation of \hookrightarrow

- aim: show that \hookrightarrow preserves types:

$$t \in \mathcal{T}(\Sigma, \mathcal{V})_\tau \longrightarrow t \hookrightarrow s \longrightarrow s \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$$

- proof will be by induction w.r.t. inductively defined set \hookrightarrow for arbitrary τ
- preliminary: we call a **substitution type-correct**, if $\sigma(x) \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$ whenever $x : \tau \in \mathcal{V}$
- easy result: whenever $t \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$ and σ is type-correct, then $t\sigma \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$
(how would you prove it?)

Type Preservation of \hookrightarrow – Proof

- proof: induction w.r.t. inductively defined set \hookrightarrow for arbitrary τ
- base case: $l\sigma \hookrightarrow r\sigma$ for some equation $l = r$ of the program where $l\sigma \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$ and we have to prove $r\sigma \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$
 - since $l\sigma \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$, and $l, r \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$ by the definition of functional programs, we conclude that σ is type-correct, cf. slide 26
 - and since $r \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$ and σ is type-correct, then also $r\sigma \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$, cf. previous slide
- step case: $F(s_1, \dots, s_i, \dots, s_n) \hookrightarrow F(s_1, \dots, t_i, \dots, s_n)$ since $s_i \hookrightarrow t_i$, we know $F(s_1, \dots, s_i, \dots, s_n) \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$ and have to prove $F(s_1, \dots, t_i, \dots, s_n) \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$
 - since $F(s_1, \dots, s_i, \dots, s_n) \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$, we know that $F : \tau_1 \times \dots \times \tau_n \rightarrow \tau \in \Sigma$ and each $s_j \in \mathcal{T}(\Sigma, \mathcal{V})_{\tau_j}$ for $1 \leq j \leq n$
 - by the IH we know $t_i \in \mathcal{T}(\Sigma, \mathcal{V})_{\tau_i}$ – note that here we can take a different type than τ , namely τ_i , because the induction was for **arbitrary** τ
 - but then we immediately conclude $F(s_1, \dots, t_i, \dots, s_n) \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$

Type Preservation of \hookrightarrow^*

- finally, we can show that evaluation (execution of arbitrarily many \hookrightarrow -steps, written \hookrightarrow^*) preserves types, which is an easy induction proof by the number of steps, using type-preservation of \hookrightarrow
- theorem: whenever $t \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$ and $t \hookrightarrow^* s$, then $s \in \mathcal{T}(\Sigma, \mathcal{V})_\tau$
- proofs to obtain global result
 1. show that **matching preserves types** (slide 26)
proof via invariant, since matching algorithm is imperative (while rules-applicable ...)
 2. show that **substitution application preserves types** (slide 31)
proof by induction on terms, following recursive structure of definition of substitution application (slide 22)
 3. show that \hookrightarrow **preserves types** (slide 33)
proof by structural induction wrt. inductively defined set \hookrightarrow ;
uses results 1 and 2
 4. show that \hookrightarrow^* **preserves types**
proof on number of steps; uses result 3

Preservation of Groundness of \hookrightarrow^*

- a term t is **ground** if $\mathcal{V}ars(t) = \emptyset$, or equivalently if $t \in \mathcal{T}(\Sigma)$
- recall aim: we want to evaluate ground term like `append(Cons(Zero, Nil), Nil)` to element of universe, i.e., constructor ground term
- hence, we need to ensure that result of evaluation with \hookrightarrow is ground
- preservation of groundness can be shown with similar proof structure as in the proof of preservation of types

Normal Forms – The Results of an Evaluation

- a term t is a **normal form** (w.r.t. \hookrightarrow) if no further \hookrightarrow -steps are possible:

$$\nexists s. t \hookrightarrow s$$

- whenever $t \hookrightarrow^* s$ and s is in normal form, then we write

$$t \hookrightarrow^! s$$

and call s a **normal form of t**

- normal forms represent the result of an evaluation
- known results at this point: whenever $t \in \mathcal{T}(\Sigma)_{\tau}$ and $t \hookrightarrow^! s$ then
 - $s \in \mathcal{T}(\Sigma, \mathcal{V})_{\tau}$ (type-preservation)
 - $s \in \mathcal{T}(\Sigma)$ (groundness-preservation)
 - $s \in \mathcal{T}(\Sigma)_{\tau}$ (combined)
- missing:
 - $s \in \mathcal{T}(\mathcal{C})_{\tau}$ (constructor-ground term)
 - s is unique
 - s always exists

Pattern Completeness

- a function symbol $f : \tau_1 \times \dots \times \tau_n \rightarrow \tau \in \mathcal{D}$ is **pattern complete** iff for all $t_1 \in \mathcal{T}(\mathcal{C})_{\tau_1}, \dots, t_n \in \mathcal{T}(\mathcal{C})_{\tau_n}$ there is an equation $\ell = r$ in the program, such that ℓ matches $f(t_1, \dots, t_n)$
- a functional program is **pattern complete** iff all $f \in \mathcal{D}$ are pattern complete
- example

$$\text{append}(\text{Cons}(x, xs), ys) = \text{Cons}(x, \text{append}(xs, ys))$$

$$\text{append}(\text{Nil}, ys) = ys$$

$$\text{head}(\text{Cons}(x, xs)) = x$$

- **append** is pattern complete
- **head** is not pattern complete: for **head(Nil)** there is no matching lhs

Pattern Completeness and Constructor Ground Terms

- theorem: if a program is pattern complete and $t \in \mathcal{T}(\Sigma)_\tau$ is a normal form, then $t \in \mathcal{T}(\mathcal{C})_\tau$
- proof of $P(t, \tau)$ by structural induction w.r.t. $\mathcal{T}(\Sigma)_\tau$ for

$$P(t, \tau) := t \text{ is normal form} \longrightarrow t \in \mathcal{T}(\mathcal{C})_\tau$$

- induction yields only one case: $t = F(t_1, \dots, t_n)$ where $F : \tau_1 \times \dots \times \tau_n \rightarrow \tau \in \Sigma$
- IH for each i : if t_i is normal form, then $t_i \in \mathcal{T}(\mathcal{C})_{\tau_i}$
- premise: $F(t_1, \dots, t_n)$ is normal form
- from premise conclude that t_i is normal form:
(if $t_i \hookrightarrow s_i$ then $F(t_1, \dots, t_n) \hookrightarrow F(t_1, \dots, s_i, \dots, t_n)$ shows that $F(t_1, \dots, t_n)$ is not a normal form)
- in combination with IH: each $t_i \in \mathcal{T}(\mathcal{C})_{\tau_i}$
- consider two cases: $F \in \mathcal{C}$ or $F \in \mathcal{D}$
- case $F \in \mathcal{C}$: using $t_i \in \mathcal{T}(\mathcal{C})_{\tau_i}$ immediately yields $F(t_1, \dots, t_n) \in \mathcal{T}(\mathcal{C})_\tau$
- case $F \in \mathcal{D}$: using pattern completeness and $t_i \in \mathcal{T}(\mathcal{C})_{\tau_i}$, conclude that $F(t_1, \dots, t_n)$ must be matched by lhs; this is contradiction to $F(t_1, \dots, t_n)$ being a normal form

Pattern Disjointness

- a function symbol $f : \tau_1 \times \dots \times \tau_n \rightarrow \tau \in \mathcal{D}$ is **pattern disjoint** iff for all $t_1 \in \mathcal{T}(\mathcal{C})_{\tau_1}$, \dots , $t_n \in \mathcal{T}(\mathcal{C})_{\tau_n}$ there is at most one equation $\ell = r$ in the program, such that ℓ matches $f(t_1, \dots, t_n)$
- a functional program is **pattern disjoint** iff all $f \in \mathcal{D}$ are pattern disjoint
- example

$$\text{append}(\text{Cons}(x, xs), ys) = \text{Cons}(x, \text{append}(xs, ys))$$

$$\text{append}(xs, ys) = ys$$

$$\text{head}(\text{Cons}(x, xs)) = x$$

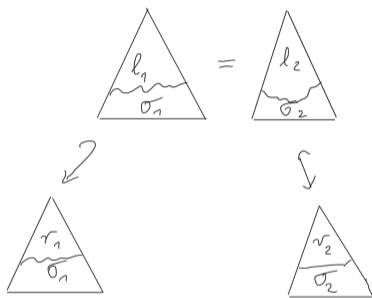
- **head** is pattern disjoint
- **append** is not pattern disjoint: the term $\text{append}(\text{Cons}(\text{Zero}, \text{Nil}), \text{Nil})$ is matched by the lhs of both **append**-equations

Pattern Disjointness and Unique Normal Forms

- theorem: if a program is pattern disjoint then \hookrightarrow is **confluent** and each term has at most one normal form
- **confluence**: whenever $s \hookrightarrow^* t$ and $s \hookrightarrow^* u$ then there exists some v such that $t \hookrightarrow^* v$ and $u \hookrightarrow^* v$
- proof of theorem:
 - pattern disjointness in combination with the other syntactic restrictions on functional programs implies that the defining equations form an **orthogonal term rewrite system**
 - Rosen proved that **orthogonal** term rewrite systems are confluent
 - confluence implies that each term has at most one normal form
 - full proof of Rosen given in term rewriting lecture, we only sketch a weaker property on the next slides, namely **local confluence**: whenever $s \hookrightarrow t$ and $s \hookrightarrow u$ then there exists some v such that $t \hookrightarrow^* v$ and $u \hookrightarrow^* v$
 - local confluence in combination with termination also implies confluence

Proof of Local Confluence: Two Root Steps

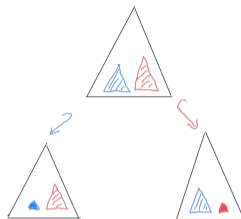
- consider the situation in the diagram where two root steps with equations $l_1 = r_1$ and $l_2 = r_2$ are applied



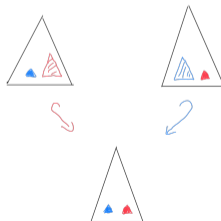
- because of pattern disjointness: $(l_1 = r_1) = (l_2 = r_2)$
- uniqueness of matching: $\sigma_1(x) = \sigma_2(x)$ for all $x \in \text{Vars}(l_{1/2})$
- variable condition of programs: $\sigma_1(x) = \sigma_2(x)$ for all $x \in \text{Vars}(r_{1/2})$
- hence $r_1\sigma_1 = r_2\sigma_2$

Proof of Local Confluence: Independent Steps

- consider the situation in the diagram where two steps at independent positions are applied



- just do the steps in reverse order

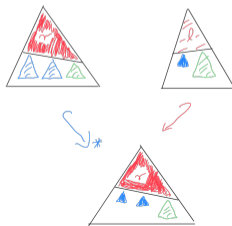


Proof of Local Confluence: Root- and Substitution-Step

- consider the situation in the diagram where a root step overlaps with a step done in the substitution



- just do the steps in reverse order (perhaps multiple times)



Graphical Local Confluence Proof

- the diagrams in the three previous slides describe all situations where one term can be evaluated in two different ways (within one step)
- in all cases the diagrams could be joined
- overall: intuitive graphical proof of local confluence
- often hard task: transform such an intuitive proof into a formal, purely textual proof, using induction, case-analysis, etc.

Semantics for Functional Programs in the Standard Model

- we are now ready to complete the semantics for functional programs
- we call a functional program **well-defined**, if
 - it is pattern disjoint,
 - it is pattern complete, and
 - \hookrightarrow is terminating
- for well-defined programs, we define for each $f : \tau_1 \times \dots \times \tau_n \rightarrow \tau \in \mathcal{D}$

$$f^{\mathcal{M}} : \mathcal{T}(\mathcal{C})_{\tau_1} \times \dots \times \mathcal{T}(\mathcal{C})_{\tau_n} \rightarrow \mathcal{T}(\mathcal{C})_{\tau}$$

$$f^{\mathcal{M}}(t_1, \dots, t_n) = s$$

where s is **the unique normal form** of $f(t_1, \dots, t_n)$, i.e., $f(t_1, \dots, t_n) \hookrightarrow^! s$

- remarks:
 - a normal form exists, since \hookrightarrow is terminating
 - s is unique because of pattern disjointness
 - $s \in \mathcal{T}(\mathcal{C})_{\tau}$ because of pattern completeness, and type- and groundness-preservation

Summary: Standard Model

- standard model
 - universes: $\mathcal{T}(\mathcal{C})_\tau$
 - constructors: $c^{\mathcal{M}}(t_1, \dots, t_n) = c(t_1, \dots, t_n)$
 - defined symbols: $f^{\mathcal{M}}(t_1, \dots, t_n)$ is normal form of $f(t_1, \dots, t_n)$ wrt. \hookrightarrow
- if functional program is well-defined
 - pattern disjoint,
 - pattern complete, and
 - \hookrightarrow is terminating

then standard model is well-defined

- upcoming
 - what about functional programs that are not well-defined?
 - comparison to real functional programming languages
 - treatment in real proof assistants

Without Pattern Disjointness

- consider Haskell program

```
conj :: Bool -> Bool -> Bool
conj True True = True      -- (1)
conj x    y    = False    -- (2)
```

- obviously not pattern disjoint
- however, Haskell still has unique results, since equations are ordered
 - an equation is only applicable if all previous equations are not applicable
 - so, `conj True True` can only be evaluated to `True`
- ordering of equations can be resolved by instantiation equations via **complementary patterns**
- equivalent equations (in Haskell) which do not rely upon order of equations

```
conj :: Bool -> Bool -> Bool
conj True  True  = True      -- (1)
conj False y    = False    -- (2) with x / False
conj True  False = False    -- (2) with x / True, y / False
```

Without Pattern Disjointness – Continued

- pattern disjointness is **sufficient** criterion to ensure confluence
- overlaps can be allowed, if they do not cause conflicts
- example:

```
conj :: Bool -> Bool -> Bool
```

```
conj True  True  = True
```

```
conj False y     = False  -- (1)
```

```
conj x      False = False  -- (2)
```

the only overlap is `conj False False`; it is harmless since the term evaluates to the **same** result using both (1) and (2)

- translating ordered equations into pattern disjoint equations or equations which only have harmless overlaps can be done **automatically**
 - usually, there are several possibilities
 - finding the smallest set of equations is hard
 - automatically done in proof-assistants such as Isabelle; e.g., overlapping `conj` from previous slide is translated into above one
- consequence: **pattern disjointness is no real restriction**

Without Pattern Completeness

- pattern completeness is naturally missing in several functions
- examples from Haskell libraries

```
head :: [a] -> a
```

```
head (x : xs) = x
```

- resolving pattern incompleteness is possible in the standard model
 - determine missing patterns
 - add for these missing cases equations that assign **some element** of the universe

$$\text{head}(\text{Cons}(x, xs)) = x$$

equation as before

$$\text{head}(\text{Nil}) = \text{some element of } \mathcal{T}(\mathcal{C})_{\text{Nat}}$$

new equation

- in this way, **head** becomes pattern complete and $\text{head}^{\mathcal{M}}$ is total
- "some element" really is an element of $\mathcal{T}(\mathcal{C})_{\text{Nat}}$, and **not a special error value** like \perp
- the added equation with "some element" is usually not revealed to the user, so she cannot reason about what number $\text{head}(\text{Nil})$ actually is
- consequence: **pattern completeness is no real restriction**

Without Termination

- definition of standard model just doesn't work properly in case of non-termination
- one possibility: use Scott's **domain theory** where among others, explicit **\perp -elements** are added to universe
- examples
 - $\mathcal{A}_{\text{Nat}} = \{\perp, \text{Zero}, \text{Succ}(\text{Zero}), \text{Succ}(\text{Succ}(\text{Zero})), \dots, \text{Succ}^\infty\}$
 - $\mathcal{A}_{\text{List}} = \{\perp, \text{Nil}, \text{Cons}(\text{Zero}, \text{Nil}), \text{Cons}(\perp, \text{Nil}), \text{Cons}(\perp, \perp), \dots\}$
- then semantics can be given to non-terminating computations
 - $\text{inf} = \text{Succ}(\text{inf})$ leads to $\text{inf}^{\mathcal{M}} = \text{Succ}^\infty$
 - $\text{undef} = \text{undef}$ leads to $\text{undef}^{\mathcal{M}} = \perp$
- problem: certain equalities don't hold wrt. domain theory semantics
 - assume usual definition of program for **minus**, then
 $\forall x. \text{minus}(x, x) = \text{Zero}$ is not true, consider $x = \text{inf}$ or $x = \text{undef}$
- since reasoning in domain theory is more complex, in this course we **restrict to terminating functional programs**
- even large proof assistants like Isabelle and Coq usually restrict to terminating functions for that reason

Inference Rules for the Standard Model

Plan

- from now until the end of these slides consider only well-defined functional programs, so that standard model is well-defined
- aim
 - derive theorems and inference rules which are valid in the standard model
 - these can be used to formally reason about functional programs as on slide 1/18 where associativity of `append` was proven
- examples
 - reasoning about constructors
 - $\forall x, y. \text{Succ}(x) =_{\text{Nat}} \text{Succ}(y) \longleftrightarrow x =_{\text{Nat}} y$
 - $\forall x. \neg \text{Succ}(x) =_{\text{Nat}} \text{Zero}$
 - getting defining equations of functional programs as theorems
 - $\forall x, xs, ys. \text{append}(\text{Cons}(x, xs), ys) =_{\text{List}} \text{Cons}(x, \text{append}(xs, ys))$
 - induction schemes
 - $$\frac{\varphi(\text{Zero}) \quad \forall x. \varphi(x) \longrightarrow \varphi(\text{Succ}(x))}{\forall x. \varphi(x)}$$

Notation – The Normal Form

- when speaking about \leftrightarrow , we always consider some fixed well-defined functional program
- since every term has a unique normal form wrt. \leftrightarrow , we can define a function $\Downarrow: \mathcal{T}(\Sigma, \mathcal{V})_{\tau} \rightarrow \mathcal{T}(\Sigma, \mathcal{V})_{\tau}$ which returns this normal form and write it in postfix notation:

$$t \Downarrow := \text{the unique normal of } t \text{ wrt. } \leftrightarrow$$

- using \Downarrow , the meaning of symbols in the standard model can concisely be written as

$$F^{\mathcal{M}}(t_1, \dots, t_n) = F(t_1, \dots, t_n) \Downarrow$$

- proof

- if $F \in \mathcal{C}$, then $F^{\mathcal{M}}(t_1, \dots, t_n) \stackrel{def}{=} F(t_1, \dots, t_n) \Downarrow$
- if $F \in \mathcal{D}$, then $F^{\mathcal{M}}(t_1, \dots, t_n) \stackrel{def}{=} F(t_1, \dots, t_n) \Downarrow$

The Substitution Lemma

- there are two possibilities to plug in objects into variables
 - as environment: $\alpha : \mathcal{V}_\tau \rightarrow \mathcal{A}_\tau$
result of $\llbracket t \rrbracket_\alpha$ is an element of \mathcal{A}_τ
 - as substitution: $\sigma : \mathcal{V}_\tau \rightarrow \mathcal{T}(\Sigma, \mathcal{V})_\tau$
result of $t\sigma$ is an element of $\mathcal{T}(\Sigma, \mathcal{V})_\tau$
- **substitution lemma**: substitutions can be moved into environment:

$$\llbracket t\sigma \rrbracket_\alpha = \llbracket t \rrbracket_\beta$$

where $\beta(x) := \llbracket \sigma(x) \rrbracket_\alpha$

- proof by structural induction on t
 - $\llbracket x\sigma \rrbracket_\alpha = \llbracket \sigma(x) \rrbracket_\alpha = \beta(x) = \llbracket x \rrbracket_\beta$
 -

$$\begin{aligned} \llbracket F(t_1, \dots, t_n)\sigma \rrbracket_\alpha &= \llbracket F(t_1\sigma, \dots, t_n\sigma) \rrbracket_\alpha \\ &= F^{\mathcal{M}}(\llbracket t_1\sigma \rrbracket_\alpha, \dots, \llbracket t_n\sigma \rrbracket_\alpha) \\ &\stackrel{IH}{=} F^{\mathcal{M}}(\llbracket t_1 \rrbracket_\beta, \dots, \llbracket t_n \rrbracket_\beta) \\ &= \llbracket F(t_1, \dots, t_n) \rrbracket_\beta \end{aligned}$$

Reverse Substitution Lemma in the Standard Model

- the substitution lemma holds independently of the model
- in case of the standard model, we have the special condition that $\mathcal{A}_\tau = \mathcal{T}(\mathcal{C})_\tau$, so
 - the universes consist of terms
 - hence, each **environment** $\alpha : \mathcal{V}_\tau \rightarrow \mathcal{T}(\mathcal{C})_\tau$ is a special kind of **substitution** (constructor ground substitution)
- consequence: possibility to encode environment as substitution

- **reverse substitution lemma:**

$$\llbracket t \rrbracket_\alpha = t\alpha \Downarrow$$

- proof by structural induction on t

- $\llbracket x \rrbracket_\alpha = \alpha(x) \stackrel{(*)}{=} \alpha(x) \Downarrow = x\alpha \Downarrow$ where $(*)$ holds, since $\alpha(x) \in \mathcal{T}(\mathcal{C})$

$$\begin{aligned} \llbracket F(t_1, \dots, t_n) \rrbracket_\alpha &= F^{\mathcal{M}}(\llbracket t_1 \rrbracket_\alpha, \dots, \llbracket t_n \rrbracket_\alpha) \\ &\stackrel{IH}{=} F^{\mathcal{M}}(t_1\alpha \Downarrow, \dots, t_n\alpha \Downarrow) = F(t_1\alpha \Downarrow, \dots, t_n\alpha \Downarrow) \Downarrow \\ &\stackrel{(conf.l.)}{=} F(t_1\alpha, \dots, t_n\alpha) \Downarrow = F(t_1, \dots, t_n)\alpha \Downarrow \end{aligned}$$

Defining Equations are Theorems in Standard Model

- notation: $\vec{\forall} \varphi$ means that universal quantification ranges over all free variables that occur in φ
- example: if φ is `append(Cons(x, xs), ys) =List Cons(x, append(xs, ys))` then $\vec{\forall} \varphi$ is

$$\forall x, xs, ys. \text{append}(\text{Cons}(x, xs), ys) =_{\text{List}} \text{Cons}(x, \text{append}(xs, ys))$$

- theorem: if $\ell = r$ is defining equation of program (of type τ), then

$$\mathcal{M} \models \vec{\forall} \ell =_{\tau} r$$

- consequence: conversion of well-defined functional programs into equations is now possible, cf. previous problem on slide 1/21
- proof of theorem
 - by definition of \models and $=_{\tau}^{\mathcal{M}}$ we have to show $\llbracket \ell \rrbracket_{\alpha} = \llbracket r \rrbracket_{\alpha}$ for all α
 - via reverse substitution lemma this is equivalent to $\ell \alpha \Downarrow = r \alpha \Downarrow$
 - easily follows from confluence, since $\ell \alpha \leftrightarrow r \alpha$

Axiomatic Reasoning

- previous slide already provides us with some theorems that are satisfied in standard model
- **axiomatic reasoning**:
take those theorems as axioms to show property φ
- added axioms are theorems of standard model, so they are **consistent**
- example $AX = \{\vec{\forall} \ell =_{\tau} r \mid \ell = r \text{ is def. eqn.}\}$
- **show $AX \models \varphi$ using first-order reasoning in order to prove $\mathcal{M} \models \varphi$**
(and forget standard model \mathcal{M} during the reasoning!)
- question: is it possible to prove every property φ in this way for which $\mathcal{M} \models \varphi$ holds?
- answer for above example is "no"
 - reason: there are models different than the standard model in which all axioms of AX are satisfied, but where φ does not hold!
 - example on next slide

Axiomatic Reasoning – Problematic Model

- consider addition program, then example AX consists of two axioms

$$\forall y. \text{plus}(\text{Zero}, y) =_{\text{Nat}} y$$

$$\forall x, y. \text{plus}(\text{Succ}(x), y) =_{\text{Nat}} \text{Succ}(\text{plus}(x, y))$$

- we want to prove associativity of **plus**, so let φ be

$$\forall x, y, z. \text{plus}(\text{plus}(x, y), z) =_{\text{Nat}} \text{plus}(x, \text{plus}(y, z))$$

- consider the following model \mathcal{M}'

- $\mathcal{A}_{\text{Nat}} = \mathbb{N} \cup \{x + \frac{1}{2} \mid x \in \mathbb{Z}\} = \{\dots, -1\frac{1}{2}, -\frac{1}{2}, 0, \frac{1}{2}, 1, 1\frac{1}{2}, 2, 2\frac{1}{2}, \dots\}$

- $\text{Zero}^{\mathcal{M}'} = 0$

- $\text{Succ}^{\mathcal{M}'}(n) = n + 1$

- $\text{plus}^{\mathcal{M}'}(n, m) = \begin{cases} n + m, & \text{if } n \in \mathbb{N} \text{ or } m \in \mathbb{N} \\ n - m + \frac{1}{2}, & \text{otherwise} \end{cases}$

- $=_{\text{Nat}}^{\mathcal{M}'} = \{(n, n) \mid n \in \mathcal{A}_{\text{Nat}}\}$

- $\mathcal{M}' \models \bigwedge AX$, but $\mathcal{M}' \not\models \varphi$: consider $\alpha(x) = \frac{19}{2}, \alpha(y) = \frac{9}{2}, \alpha(z) = \frac{7}{2}$

- problem: values in α do not correspond to constructor ground terms

Gödel's Incompleteness Theorem

- taking AX as set of defining equations does not suffice to deduce all valid theorems of standard model
- obvious approach: add more theorems to axioms AX (theorems about $=_{\tau}$, induction rules, ...)
- question: is it then possible to deduce all valid theorems of standard model?
- negative answer by **Gödel's First Incompleteness Theorem**
- **theorem**: consider a well-defined functional program that includes addition and multiplication of natural numbers;
let AX be a decidable set of valid theorems in the standard model;
then **there is a formula φ such that $\mathcal{M} \models \varphi$, but $AX \not\models \varphi$**
- note: adding φ to AX does not fix the problem, since then there is another formula φ' so that $AX \cup \{\varphi\} \not\models \varphi'$
- consequence: **"proving φ via $AX \models \varphi$ " is sound, but never complete**
- upcoming: add more axioms than just defining equations, so that still several proofs are possible

Axioms about Equality

- we define decomposition theorems and disjointness theorems in the form of logical equivalences
- for each $c : \tau_1 \times \dots \times \tau_n \rightarrow \tau \in \mathcal{C}$ we define its **decomposition theorem** as

$$\vec{\forall} c(x_1, \dots, x_n) =_{\tau} c(y_1, \dots, y_n) \longleftrightarrow x_1 =_{\tau_1} y_1 \wedge \dots \wedge x_n =_{\tau_n} y_n$$

and for all $d : \tau'_1 \times \dots \times \tau'_k \rightarrow \tau \in \mathcal{C}$ with $c \neq d$ we define the **disjointness theorem** as

$$\vec{\forall} c(x_1, \dots, x_n) =_{\tau} d(y_1, \dots, y_k) \longleftrightarrow \text{false}$$

- proof of validity of decomposition theorem:

$$\begin{aligned} & \mathcal{M} \models_{\alpha} c(x_1, \dots, x_n) =_{\tau} c(y_1, \dots, y_n) \\ \text{iff } & c(\alpha(x_1), \dots, \alpha(x_n)) = c(\alpha(y_1), \dots, \alpha(y_n)) \\ \text{iff } & \alpha(x_1) = \alpha(y_1) \text{ and } \dots \text{ and } \alpha(x_n) = \alpha(y_n) \\ \text{iff } & \mathcal{M} \models_{\alpha} x_1 =_{\tau_1} y_1 \text{ and } \dots \text{ and } \mathcal{M} \models_{\alpha} x_n =_{\tau_n} y_n \\ \text{iff } & \mathcal{M} \models_{\alpha} x_1 =_{\tau_1} y_1 \wedge \dots \wedge x_n =_{\tau_n} y_n \end{aligned}$$

Axioms about Equality – Example

- for the datatypes of natural numbers and lists we get the following axioms

$$\text{Zero} =_{\text{Nat}} \text{Zero} \longleftrightarrow \text{true}$$

$$\forall x, y. \text{Succ}(x) =_{\text{Nat}} \text{Succ}(y) \longleftrightarrow x =_{\text{Nat}} y$$

$$\text{Nil} =_{\text{List}} \text{Nil} \longleftrightarrow \text{true}$$

$$\forall x, xs, y, ys. \text{Cons}(x, xs) =_{\text{List}} \text{Cons}(y, ys) \longleftrightarrow x =_{\text{Nat}} y \wedge xs =_{\text{List}} ys$$

$$\forall y. \text{Zero} =_{\text{Nat}} \text{Succ}(y) \longleftrightarrow \text{false}$$

$$\forall x. \text{Succ}(x) =_{\text{Nat}} \text{Zero} \longleftrightarrow \text{false}$$

$$\forall y, ys. \text{Nil} =_{\text{List}} \text{Cons}(y, ys) \longleftrightarrow \text{false}$$

$$\forall x, xs. \text{Cons}(x, xs) =_{\text{List}} \text{Nil} \longleftrightarrow \text{false}$$

Induction Theorems

- current axioms are not even strong enough to prove simple theorems, e.g.,
 $\forall x. \text{plus}(x, \text{Zero}) =_{\text{Nat}} x$
- problem: proofs by induction are not yet covered in axioms
- since the principle of **induction cannot be defined** in general **in a single first-order formula**, we will add infinitely many induction theorems to the set of axioms, one for each property
- not a problem, since set of axioms stays decidable, i.e., one can see whether some tentative formula is an element of the axiom set or not
- example: induction over natural numbers

- formula below is general, but not first-order as it quantifies over φ

$$\forall \varphi (x : \text{Nat}). \varphi(\text{Zero}) \longrightarrow (\forall x. \varphi(x) \longrightarrow \varphi(\text{Succ}(x))) \longrightarrow \forall x. \varphi(x)$$

- quantification can be done on meta-level instead:
 let φ be an arbitrary formula with a free variable of type **Nat**; then

$$\varphi(\text{Zero}) \longrightarrow (\forall x. \varphi(x) \longrightarrow \varphi(\text{Succ}(x))) \longrightarrow \forall x. \varphi(x)$$

is a valid theorem; quantifying over φ results in **induction scheme**

Induction Theorems – Example Instances

- induction scheme

$$\varphi(\mathbf{Zero}) \longrightarrow (\forall x. \varphi(x) \longrightarrow \varphi(\mathbf{Succ}(x))) \longrightarrow \forall x. \varphi(x)$$

- example: right-neutral element: $\varphi(x) := \mathbf{plus}(x, \mathbf{Zero}) =_{\mathbf{Nat}} x$

$$\mathbf{plus}(\mathbf{Zero}, \mathbf{Zero}) =_{\mathbf{Nat}} \mathbf{Zero}$$

$$\longrightarrow (\forall x. \mathbf{plus}(x, \mathbf{Zero}) =_{\mathbf{Nat}} x \longrightarrow \mathbf{plus}(\mathbf{Succ}(x), \mathbf{Zero}) =_{\mathbf{Nat}} \mathbf{Succ}(x))$$

$$\longrightarrow \forall x. \mathbf{plus}(x, \mathbf{Zero}) =_{\mathbf{Nat}} x$$

- example with **quantifiers** and **free** variables:

$$\varphi(x) := \forall y. \mathbf{plus}(\mathbf{plus}(x, y), z) =_{\mathbf{Nat}} \mathbf{plus}(x, \mathbf{plus}(y, z))$$

$$\forall y. \mathbf{plus}(\mathbf{plus}(\mathbf{Zero}, y), z) =_{\mathbf{Nat}} \mathbf{plus}(\mathbf{Zero}, \mathbf{plus}(y, z))$$

$$\longrightarrow (\forall x. (\forall y. \mathbf{plus}(\mathbf{plus}(x, y), z) =_{\mathbf{Nat}} \mathbf{plus}(x, \mathbf{plus}(y, z))))$$

$$\longrightarrow (\forall y. \mathbf{plus}(\mathbf{plus}(\mathbf{Succ}(x), y), z) =_{\mathbf{Nat}} \mathbf{plus}(\mathbf{Succ}(x), \mathbf{plus}(y, z))))$$

$$\longrightarrow \forall x. \forall y. \mathbf{plus}(\mathbf{plus}(x, y), z) =_{\mathbf{Nat}} \mathbf{plus}(x, \mathbf{plus}(y, z))$$

Preparing Induction Theorems – Substitutions in Formulas

- current situation
 - substitutions are functions of type $\mathcal{V} \rightarrow \mathcal{T}(\Sigma, \mathcal{V})$
 - lifted to functions of type $\mathcal{T}(\Sigma, \mathcal{V}) \rightarrow \mathcal{T}(\Sigma, \mathcal{V})$, cf. slide 22
 - substitution of variables of formulas is not yet defined, but is required for induction formulas, cf. notation $\varphi(x) \rightarrow \varphi(\text{Succ}(x))$ on previous slide
- formal definition of **applying a substitution σ on formulas**
 - $\text{true } \sigma = \text{true}$
 - $(\neg\varphi)\sigma = \neg(\varphi\sigma)$
 - $(\varphi \wedge \psi)\sigma = \varphi\sigma \wedge \psi\sigma$
 - $P(t_1, \dots, t_n)\sigma = P(t_1\sigma, \dots, t_n\sigma)$
 - $(\forall x. \varphi)\sigma = \forall x. (\varphi\sigma)$ if x does not occur in σ , i.e., $\sigma(x) = x$ and $x \notin \text{Vars}(\sigma(y))$
for all $y \neq x$
 - $(\forall x. \varphi)\sigma = (\forall y. \varphi[x/y])\sigma$ if x occurs in σ where
 - y is a fresh variable, i.e., $\sigma(y) = y$, $y \notin \text{Vars}(\sigma(z))$ for all $z \neq y$, and y is not a free variable of φ
 - $[x/y]$ is the substitution which just replaces x by y
 - effect is **α -renaming**: just rename universally quantified variable before substitution to **avoid variable capture**

Examples

- substitution of formulas

- $(\forall x. \varphi)\sigma = \forall x. (\varphi\sigma)$
- $(\forall x. \varphi)\sigma = (\forall y. \varphi[x/y])\sigma$

if x does not occur in σ
if x occurs in σ where y is fresh

- example substitution applications

- $\varphi := \forall x. \neg x =_{\text{Nat}} y$
- $\varphi[y/\text{Zero}] = \forall x. \neg x =_{\text{Nat}} \text{Zero}$
- $\varphi[y/\text{Succ}(z)] = \forall x. \neg x =_{\text{Nat}} \text{Succ}(z)$
- $\varphi[y/\text{Succ}(x)] = \forall z. \neg z =_{\text{Nat}} \text{Succ}(x)$
without renaming result would be wrong: $\forall x. \neg x =_{\text{Nat}} \text{Succ}(x)$
- $\varphi[x/\text{Succ}(y)] = \forall z. \neg z =_{\text{Nat}} y$
without renaming result would be wrong: $\forall x. \neg \text{Succ}(y) =_{\text{Nat}} y$

no renaming required
no renaming required
renaming $[x/z]$ required
renaming $[x/z]$ required

- example theorems involving substitutions

$$\varphi[x/\text{Zero}] \longrightarrow (\forall y. \varphi[x/y] \longrightarrow \varphi[x/\text{Succ}(y)]) \longrightarrow \forall x. \varphi$$

Substitution Lemma for Formulas

- example induction formula

$$\varphi[x/\text{Zero}] \longrightarrow (\forall y. \varphi[x/y] \longrightarrow \varphi[x/\text{Succ}(y)]) \longrightarrow \forall x. \varphi$$

- proving validity of this formula (in standard model) requires another substitution lemma about substitutions in formulas
- lemma: $\mathcal{M} \models_{\alpha} \varphi\sigma$ iff $\mathcal{M} \models_{\beta} \varphi$ where $\beta(x) := \llbracket \sigma(x) \rrbracket_{\alpha}$
- proof by structural induction on φ for arbitrary α and σ
 - $\mathcal{M} \models_{\alpha} P(t_1, \dots, t_n)\sigma$
 iff $\mathcal{M} \models_{\alpha} P(t_1\sigma, \dots, t_n\sigma)$
 iff $(\llbracket t_1\sigma \rrbracket_{\alpha}, \dots, \llbracket t_n\sigma \rrbracket_{\alpha}) \in P^{\mathcal{M}}$
 iff $(\llbracket t_1 \rrbracket_{\beta}, \dots, \llbracket t_n \rrbracket_{\beta}) \in P^{\mathcal{M}}$
 iff $\mathcal{M} \models_{\beta} P(t_1, \dots, t_n)$
 where we use the substitution lemma of slide 54 to conclude $\llbracket t_i\sigma \rrbracket_{\alpha} = \llbracket t_i \rrbracket_{\beta}$
 - $\mathcal{M} \models_{\alpha} (\neg\varphi)\sigma$ iff $\mathcal{M} \models_{\alpha} \neg(\varphi\sigma)$ iff $\mathcal{M} \not\models_{\alpha} \varphi\sigma$
 iff $\mathcal{M} \not\models_{\beta} \varphi$ (by IH) iff $\mathcal{M} \models_{\beta} \neg\varphi$
 - cases “true” and conjunction are proved in same way as negation

Substitution Lemma for Formulas – Proof Continued

- lemma: $\mathcal{M} \models_{\alpha} \varphi\sigma$ iff $\mathcal{M} \models_{\beta} \varphi$ where $\beta(x) := \llbracket \sigma(x) \rrbracket_{\alpha}$
- proof by structural induction on φ for arbitrary α and σ
 - for quantification we here only consider the more complex case where renaming is required
 - $\mathcal{M} \models_{\alpha} (\forall x. \varphi)\sigma$
 - iff $\mathcal{M} \models_{\alpha} (\forall y. \varphi[x/y])\sigma$ for fresh y
 - iff $\mathcal{M} \models_{\alpha} \forall y. (\varphi[x/y]\sigma)$
 - iff $\mathcal{M} \models_{\alpha[y:=a]} \varphi[x/y]\sigma$ for all $a \in \mathcal{A}$
 - iff $\mathcal{M} \models_{\beta'} \varphi$ for all $a \in \mathcal{A}$ where $\beta'(z) := \llbracket ([x/y]\sigma)(z) \rrbracket_{\alpha[y:=a]}$ (by IH)
 - iff $\mathcal{M} \models_{\beta[x:=a]} \varphi$ for all $a \in \mathcal{A}$ only non-automatic step
 - iff $\mathcal{M} \models_{\beta} \forall x. \varphi$
 - equivalence of β' and $\beta[x := a]$ on variables of φ
 - $\beta'(x) = \llbracket ([x/y]\sigma)(x) \rrbracket_{\alpha[y:=a]} = \llbracket \sigma(y) \rrbracket_{\alpha[y:=a]} = \llbracket y \rrbracket_{\alpha[y:=a]} = a$ and $\beta[x := a](x) = a$
 - z is variable of φ , $z \neq x$:
by freshness condition conclude $z \neq y$ and $y \notin \text{Vars}(\sigma(z))$; hence
 $\beta'(z) = \llbracket ([x/y]\sigma)(z) \rrbracket_{\alpha[y:=a]} = \llbracket \sigma(z) \rrbracket_{\alpha[y:=a]} = \llbracket \sigma(z) \rrbracket_{\alpha}$ and
 $\beta[x := a](z) = \beta(z) = \llbracket \sigma(z) \rrbracket_{\alpha}$

Substitution Lemma in Standard Model

- substitution lemma: $\mathcal{M} \models_{\alpha} \varphi\sigma$ iff $\mathcal{M} \models_{\beta} \varphi$ where $\beta(x) := \llbracket \sigma(x) \rrbracket_{\alpha}$
- lemma is valid for all models
- in standard model, substitution lemma permits to characterize universal quantification by substitutions, similar to reverse substitution lemma on slide 55
- lemma: let $x : \tau \in \mathcal{V}$, let \mathcal{M} be the **standard model**
 1. $\mathcal{M} \models_{\alpha[x:=t]} \varphi$ iff $\mathcal{M} \models_{\alpha} \varphi[x/t]$
 2. $\mathcal{M} \models_{\alpha} \forall x. \varphi$ iff $\mathcal{M} \models_{\alpha} \varphi[x/t]$ for all $t \in \mathcal{T}(\mathcal{C})_{\tau}$
- proof
 1. first note that the usage of $\alpha[x := t]$ implies $t \in \mathcal{A}_{\tau} = \mathcal{T}(\mathcal{C})_{\tau}$;
by the substitution lemma obtain

$$\mathcal{M} \models_{\alpha} \varphi[x/t]$$
 iff $\mathcal{M} \models_{\beta} \varphi$ for $\beta(z) = \llbracket [x/t](z) \rrbracket_{\alpha} = \alpha[x := \llbracket t \rrbracket_{\alpha}](z)$
 iff $\mathcal{M} \models_{\alpha[x:=t]} \varphi$

$$\left(\llbracket t \rrbracket_{\alpha} = t, \text{ since } t \in \mathcal{T}(\mathcal{C}) \right)$$
 2. immediate by part 1 of lemma

Substitution Lemma and Induction Formulas

- substitution lemma (SL) is crucial result to **lift** structural **induction rule** of universe $\mathcal{T}(\mathcal{C})_\tau$ to a structural **induction formula**
- example: structural induction formula ψ for lists with fresh x, xs

$$\psi := \underbrace{\varphi[ys/\mathbf{Nil}]}_1 \longrightarrow \underbrace{(\forall x, xs. \varphi[ys/xs] \longrightarrow \varphi[ys/\mathbf{Cons}(x, xs)])}_2 \longrightarrow \forall ys. \varphi$$

- proof of $\mathcal{M} \models_\alpha \psi$:
assume premises 1 ($\mathcal{M} \models_\alpha \varphi[ys/\mathbf{Nil}]$) and 2 and show $\mathcal{M} \models_\alpha \forall ys. \varphi$:
by SL the latter is equivalent to “ $\mathcal{M} \models_\alpha \varphi[ys/\ell]$ for all $\ell \in \mathcal{T}(\mathcal{C})_{\mathbf{List}}$ ”;
prove this statement by structural induction on lists
 - **Nil**: showing $\mathcal{M} \models_\alpha \varphi[ys/\mathbf{Nil}]$ is easy: it is exactly premise 1
 - **Cons**(n, ℓ): use SL on premise 2 to conclude

$$\mathcal{M} \models_\alpha (\varphi[ys/xs] \longrightarrow \varphi[ys/\mathbf{Cons}(x, xs)])[x/n, xs/\ell]$$

hence

$$\mathcal{M} \models_\alpha \varphi[ys/\ell] \longrightarrow \varphi[ys/\mathbf{Cons}(n, \ell)]$$

and with IH $\mathcal{M} \models_\alpha \varphi[ys/\ell]$ conclude $\mathcal{M} \models_\alpha \varphi[ys/\mathbf{Cons}(n, \ell)]$

Freshness of Variables

- example: structural induction formula for lists with fresh x, xs

$$\varphi[ys/\text{Nil}] \longrightarrow (\forall x, xs. \varphi[ys/xs] \longrightarrow \varphi[ys/\text{Cons}(x, xs)]) \longrightarrow \forall ys. \varphi$$

- why freshness required? isn't name of quantified variables irrelevant?
- problem: substitution is applied below quantifier!
- example: let us drop freshness condition and "prove" non-theorem

$$\mathcal{M} \models \forall x, xs, ys. ys =_{\text{List}} \text{Nil} \vee ys =_{\text{List}} \text{Cons}(x, xs)$$

- by semantics of $\forall x, xs. \dots$ it suffices to prove

$$\mathcal{M} \models_{\alpha} \underbrace{\forall ys. ys =_{\text{List}} \text{Nil} \vee ys =_{\text{List}} \text{Cons}(x, xs)}_{\varphi}$$

- apply above induction formula and obtain two subgoals $\mathcal{M} \models_{\alpha} \dots$ for
 - $\varphi[ys/\text{Nil}]$ which is $\text{Nil} =_{\text{List}} \text{Nil} \vee \text{Nil} =_{\text{List}} \text{Cons}(x, xs)$
 - $\forall x, xs. \varphi[ys/xs] \longrightarrow \varphi[ys/\text{Cons}(x, xs)]$ which is
 $\forall x, xs. \dots \longrightarrow \text{Cons}(x, xs) =_{\text{List}} \text{Nil} \vee \text{Cons}(x, xs) =_{\text{List}} \text{Cons}(x, xs)$

- solution: rename variables in induction formula whenever required

Structural Induction Formula

- finally definition of induction formula for data structures is possible
- consider

$$\begin{array}{l} \text{data } \tau = c_1 : \tau_{1,1} \times \dots \times \tau_{1,m_1} \rightarrow \tau \\ \quad | \dots \\ \quad | c_n : \tau_{n,1} \times \dots \times \tau_{n,m_n} \rightarrow \tau \end{array}$$

- let $x \in \mathcal{V}_\tau$, let φ be a formula, let variables x_1, x_2, \dots be fresh wrt. φ
- for each c_i define

$$\varphi_i := \forall x_1, \dots, x_{m_i}. \underbrace{\left(\bigwedge_{j, \tau_{i,j} = \tau} \varphi[x/x_j] \right)}_{\text{IH for recursive arguments}} \longrightarrow \varphi[x/c_i(x_1, \dots, x_{m_i})]$$

- the induction formula is $\vec{\nabla} (\varphi_1 \longrightarrow \dots \longrightarrow \varphi_n \longrightarrow \forall x. \varphi)$
- **theorem:** $\mathcal{M} \models \vec{\nabla} (\varphi_1 \longrightarrow \dots \longrightarrow \varphi_n \longrightarrow \forall x. \varphi)$

Proof of Structural Induction Formula

- to prove: $\mathcal{M} \models \vec{\forall} (\varphi_1 \longrightarrow \dots \longrightarrow \varphi_n \longrightarrow \forall x. \varphi)$
- \forall -intro: $\mathcal{M} \models_{\alpha} (\varphi_1 \longrightarrow \dots \longrightarrow \varphi_n \longrightarrow \forall x. \varphi)$ for arbitrary α
- \longrightarrow -intro: assume $\mathcal{M} \models_{\alpha} \varphi_i$ for all i and show $\mathcal{M} \models_{\alpha} \forall x. \varphi$
- \forall -intro via SL: show $\mathcal{M} \models_{\alpha} \varphi[x/t]$ for all $t \in \mathcal{T}(\mathcal{C})_{\tau}$
- prove this by structural induction on t wrt. induction rule of $\mathcal{T}(\mathcal{C})_{\tau}$ (for precisely this α , not for arbitrary α)
- induction step for each constructor $c_i : \tau_{i,1} \times \dots \times \tau_{i,m_i} \rightarrow \tau$
 - aim: $\mathcal{M} \models_{\alpha} \varphi[x/c_i(t_1, \dots, t_{m_i})]$ IH: $\mathcal{M} \models_{\alpha} \varphi[x/t_j]$ for all j such that $\tau_{i,j} = \tau$
 - use assumption $\mathcal{M} \models_{\alpha} \varphi_i$, i.e., (here important: same α)

$$\mathcal{M} \models_{\alpha} \forall x_1, \dots, x_{m_i}. \left(\bigwedge_{j, \tau_{i,j} = \tau} \varphi[x/x_j] \right) \longrightarrow \varphi[x/c_i(x_1, \dots, x_{m_i})]$$

- use SL as \forall -elimination with substitution $[x_1/t_1, \dots, x_{m_i}/t_{m_i}]$, obtain

$$\mathcal{M} \models_{\alpha} \left(\bigwedge_{j, \tau_{i,j} = \tau} \varphi[x/t_j] \right) \longrightarrow \varphi[x/c_i(t_1, \dots, t_{m_i})]$$

- combination with IH yields desired $\mathcal{M} \models_{\alpha} \varphi[x/c_i(t_1, \dots, t_{m_i})]$

Summary: Axiomatic Proofs of Functional Programs

- given a **well-defined** functional program, define a set of **axioms** AX consisting of
 - **equations of defined symbols** (slide 56)
 - **axioms about equality of constructors** (slide 60)
 - **structural induction formulas** (slide 71)
- instead of proving $\mathcal{M} \models \varphi$ deduce $AX \models \varphi$
- fact: standard model is ignored in previous step
- question: why all these efforts and not just state AX ?
- reason:

having proven $\mathcal{M} \models \psi$ for all $\psi \in AX$
implies that **AX is consistent!**

- recall: already just converting functional program equations naively into theorems led to proof of $0 = 1$ on slide 1/21, i.e., inconsistent axioms, and AX now contains much more powerful axioms

Example: Attempt to Prove Associativity of Append via AX

- task: prove associativity of append via **natural deduction** and **AX**
- define $\varphi := \text{append}(\text{append}(xs, ys), zs) =_{\text{List}} \text{append}(xs, \text{append}(ys, zs))$

1. show $\forall xs, ys, zs. \varphi$
2. \forall -intro: show φ where now xs, ys, zs are fresh variables
3. to this end prove intermediate goal: $\forall xs. \varphi$
4. applying induction axiom

$$\varphi[xs/\text{Nil}] \longrightarrow (\forall u, us. \varphi[xs/us] \longrightarrow \varphi[xs/\text{Cons}(u, us)]) \longrightarrow \forall xs. \varphi$$

in combination with modus ponens yields two subgoals, one of them is $\varphi[xs/\text{Nil}]$, i.e.,
 $\text{append}(\text{append}(\text{Nil}, ys), zs) =_{\text{List}} \text{append}(\text{Nil}, \text{append}(ys, zs))$

5. use axiom $\forall ys. \text{append}(\text{Nil}, ys) =_{\text{List}} ys$
6. \forall -elim: $\text{append}(\text{Nil}, \text{append}(ys, zs)) =_{\text{List}} \text{append}(ys, zs)$
7. at this point we would like to **simplify** the rhs in the goal to obtain obligation
 $\text{append}(\text{append}(\text{Nil}, ys), zs) =_{\text{List}} \text{append}(ys, zs)$
8. this is not possible at this point: there are missing axioms
 - $=_{\text{List}}$ is an equivalence relation
 - $=_{\text{List}}$ is a congruence; required to simplify the lhs $\text{append}(\cdot, zs)$ at \cdot
 - ...

- **reconsider** the **reasoning engine** and the available **axioms** in part 5

Summary of Part 3

- definition of well-defined functional programs
 - datatypes and function definitions (first order)
 - type-preserving equations within simple type system
 - well-defined: terminating, pattern complete and pattern disjoint
- definition of operational semantics \leftrightarrow
- definition of standard model
- definition of several axioms (inference rules)
 - all axioms are satisfied in standard model, so they are consistent
- upcoming
 - part 4: detect well-definedness, in particular termination
 - part 5: equational reasoning engine to prove properties of programs