

1 (a) *answer + explanation*

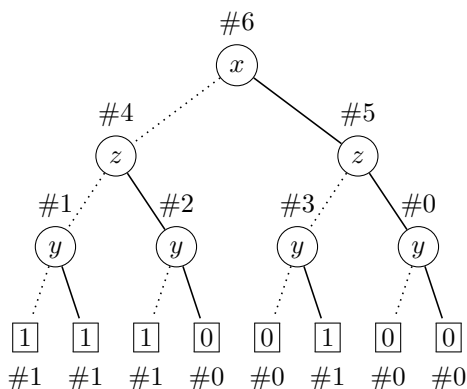
The BDD B_g is reduced because the rules C1, C2 and C3 are not applicable. It is not ordered since on different branches the variables are passed in different order, e.g. $[x, y, z]$ and $[x, z, y]$. Also, there are branches where x is visited twice.

(b) *answer + explanation*

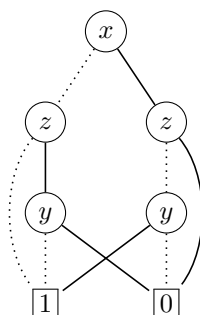
From the truth table

| x | z | y | $g(x, y, z)$ |
|-----|-----|-----|--------------|
| 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 1 |
| 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 0 |
| 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 1 |
| 1 | 1 | 0 | 0 |
| 1 | 1 | 1 | 0 |

we obtain the binary decision tree



Applying the reduce algorithm produces the desired reduced OBDD:



(c) *answer + explanation*

We have

$$\begin{aligned} f(x, y, z) &= (x \oplus y \oplus 1) \cdot (\bar{x} \oplus z \oplus \bar{x}z) \\ &= (x \oplus y \oplus 1) \cdot (x \oplus 1 \oplus z \oplus (x \oplus 1)z) \\ &= (x \oplus y \oplus 1) \cdot (x \oplus 1 \oplus z \oplus xz \oplus z) \\ &= (x \oplus y \oplus 1) \cdot (x \oplus 1 \oplus xz) \\ &= (x \oplus xy \oplus x) \oplus (x \oplus y \oplus 1) \oplus (xz \oplus xyz \oplus xz) \\ &= x \oplus y \oplus xy \oplus xyz \oplus 1 \end{aligned}$$

From the BDD in the solution of part (b) we obtain

$$\begin{aligned} g(x, y, z) &= \bar{x}(\bar{z} \oplus z\bar{y}) \oplus x\bar{z}y \\ &= (x \oplus 1)(z \oplus 1 \oplus z(y \oplus 1)) \oplus x(z \oplus 1)y \\ &= (x \oplus 1)(z \oplus 1 \oplus yz \oplus z) \oplus xyz \oplus xy \\ &= (x \oplus 1)(1 \oplus yz) \oplus xyz \oplus xy \\ &= x \oplus 1 \oplus xyz \oplus yz \oplus xyz \oplus xy \\ &= x \oplus xy \oplus yz \oplus 1 \end{aligned}$$

(d) *answer + explanation*

We have $f(0, 0, 0) = g(0, 0, 0) = f(1, 1, 1) = 1$ and $g(1, 1, 1) = 0$. Neither f nor g is monotone: $f(0, 0, 0) = 1 > 0 = f(0, 1, 0)$ and $g(0, 0, 0) = 1 > 0 = g(1, 1, 1)$. Moreover, $f(0, 0, 0) = f(1, 1, 1)$ and $g(1, 0, 0) = 0 = g(0, 1, 1)$, so f and g are not self-dual. The ANFs computed in part (c) are non-linear, so f and g are not affine. The following table summarizes our findings:

| | f | g |
|-------------------------|-----|-----|
| $h(0, \dots, 0) \neq 0$ | ✓ | ✓ |
| $h(1, \dots, 1) \neq 1$ | | ✓ |
| not monotone | ✓ | ✓ |
| not self-dual | ✓ | ✓ |
| not affine | ✓ | ✓ |

(e) *answer + explanation*

We extend the table of part (d) with \oplus and $+$:

| | f | g | \oplus | $+$ |
|-------------------------|-----|-----|----------|-----|
| $h(0, \dots, 0) \neq 0$ | ✓ | ✓ | | |
| $h(1, \dots, 1) \neq 1$ | | ✓ | ✓ | |
| not monotone | ✓ | ✓ | ✓ | |
| not self-dual | ✓ | ✓ | ✓ | ✓ |
| not affine | ✓ | ✓ | | ✓ |

It follows that a subset $S \subseteq \{f, g, \oplus, +\}$ is adequate if and only if $g \in S$ or both $f \in S$ and $\oplus \in S$.

2 (a) *answer + computation*

The following maximal derivation shows that the two terms are not unifiable:

$$\begin{array}{c} \underline{f(h(z), g(x, x), z) \approx f(h(x), y, h(y))} \\ \text{d} \Downarrow \\ \underline{h(z) \approx h(x), g(x, x) \approx y, z \approx h(y)} \\ \text{d} \Downarrow \\ \underline{z \approx x, g(x, x) \approx y, z \approx h(y)} \\ \text{v} \Downarrow \{z \mapsto x\} \\ \underline{g(x, x) \approx y, x \approx h(y)} \\ \text{v} \Downarrow \{y \mapsto g(x, x)\} \\ \underline{x \approx h(g(x, x))} \\ \text{failure} \Downarrow \\ \perp \end{array}$$

(b) *answer + explanation*

We first rename the variables x and y in the second argument of the implication and then transform the resulting formula into an equivalent prenex normal form:

$$\begin{aligned} & \forall x \exists y (P(x) \rightarrow P(y)) \rightarrow \forall y \exists x Q(x, y) \\ & \equiv \forall x \exists y (P(x) \rightarrow P(y)) \rightarrow \forall u \exists v Q(v, u) \\ & \equiv \exists x \forall y ((P(x) \rightarrow P(y)) \rightarrow \forall u \exists v Q(v, u)) \\ & \equiv \exists x \forall y \forall u \exists v ((P(x) \rightarrow P(y)) \rightarrow Q(v, u)) \end{aligned}$$

Next, we transform the quantifier-free part of the prenex normal form into CNF:

$$\begin{aligned} & \equiv \exists x \forall y \forall u \exists v (\neg(\neg P(x) \vee P(y)) \vee Q(v, u)) \\ & \equiv \exists x \forall y \forall u \exists v ((P(x) \wedge \neg P(y)) \vee Q(v, u)) \\ & \equiv \exists x \forall y \forall u \exists v ((P(x) \vee Q(v, u)) \wedge (\neg P(y) \vee Q(v, u))) \end{aligned}$$

We obtain an equisatisfiable Skolem normal form by replacing the existentially quantified variables x and v by the fresh Skolem constant c and the fresh Skolem function $g(y, u)$, respectively:

$$\approx \forall y \forall u ((P(c) \vee Q(g(y, u), u)) \wedge (\neg P(y) \vee Q(g(y, u), u)))$$

(c) *answer + explanation*

The clausal form is not satisfiable as seen by the following refutation:

1. $\{Q(x), \neg P(f(x), f(x))\}$
2. $\{R(f(x), y), Q(x)\}$
3. $\{\neg Q(a)\}$
4. $\{R(x, f(y)), R(f(u), v)\}$
5. $\{P(x, y), \neg R(x, y)\}$
6. $\{\neg P(f(a), f(a))\}$ resolve 1, 3 $\{x \mapsto a\}$
7. $\{\neg R(f(a), f(a))\}$ resolve 5, 6 $\{x \mapsto f(a), y \mapsto f(a)\}$
8. $\{R(f(u), f(y))\}$ factor 4 $\{x \mapsto f(u), v \mapsto f(y)\}$
9. \square resolve 7, 8 $\{u \mapsto a, y \mapsto a\}$

3 (a)

answer

The sequent $\neg(\neg q \wedge p) \vdash q \vee \neg p$ is valid:

| | | |
|----|-------------------------|-----------------------|
| 1 | $\neg(\neg q \wedge p)$ | assumption |
| 2 | $q \vee \neg q$ | LEM |
| 3 | q | assumption |
| 4 | $q \vee \neg p$ | $\vee i_1$ 3 |
| 5 | $\neg q$ | assumption |
| 6 | p | assumption |
| 7 | $\neg q \wedge p$ | $\wedge i$ 5, 6 |
| 8 | \perp | $\neg e$ 1, 7 |
| 9 | $\neg p$ | $\neg i$ 6-8 |
| 10 | $q \vee \neg p$ | $\vee i_2$ 9 |
| 11 | $q \vee \neg p$ | $\vee e$ 2, 3-4, 5-10 |

(b)

answer

The sequent $\forall x R(x) \vee \forall x \exists y S(x, y) \vdash \forall x \exists y (S(x, y) \vee R(x))$ is valid:

| | | |
|----|---|-----------------------|
| 1 | $\forall x R(x) \vee \forall x \forall y S(x, y)$ | premise |
| 2 | x_0 | |
| 3 | $\forall x R(x)$ | assumption |
| 4 | $R(x_0)$ | $\forall e$ 3 |
| 5 | $S(x_0, y_0) \vee R(x_0)$ | $\vee i_2$ 4 |
| 6 | $\exists y (S(x_0, y) \vee R(x_0))$ | $\exists i$ 5 |
| 7 | $\forall x \exists y S(x, y)$ | assumption |
| 8 | $\exists y S(x_0, y)$ | $\forall e$ 7 |
| 9 | y_0 $S(x_0, y_0)$ | assumption |
| 10 | $S(x_0, y_0) \vee R(x_0)$ | $\vee i_1$ 9 |
| 11 | $\exists y (S(x_0, y) \vee R(x_0))$ | $\exists i$ 10 |
| 12 | $\exists y (S(x_0, y) \vee R(x_0))$ | $\exists e$ 8, 9-11 |
| 13 | $\exists y S(x_0, y) \vee R(x_0)$ | $\vee e$ 1, 3-6, 7-11 |
| 14 | $\forall x \exists y S(x, y) \vee R(x)$ | $\forall i$ 2-13 |

(c) *answer*

The sequent $\forall x R(x) \wedge \forall x \exists y S(x, y) \vdash \exists y \forall x (S(x, y) \wedge R(x))$ is not valid. Consider the model \mathcal{M} over the universe $A = \{a, b\}$ and the interpretations:

$$R^{\mathcal{M}} = \{a, b\} \qquad S^{\mathcal{M}} = \{(a, a), (b, b)\}$$

This model satisfies the premise, since both $\mathcal{M} \models \forall x R(x)$ and $\mathcal{M} \models \forall x \exists y S(x, y)$ hold. However the conclusion is not satisfied since for both choices of $y \in A$, there exists an $x \in A$ such that $(x, y) \notin S^{\mathcal{M}}$. Formally, $\mathcal{M} \not\models_{\{y \mapsto a, x \mapsto b\}} S(x, y)$, hence $\mathcal{M} \not\models_{\{y \mapsto a, x \mapsto b\}} S(x, y) \wedge R(x)$, and further $\mathcal{M} \not\models_{\{y \mapsto a\}} \forall x (S(x, y) \wedge R(x))$. The same reasoning applies to the environment $\{y \mapsto b, x \mapsto a\}$, resulting in $\mathcal{M} \not\models_{\{y \mapsto b\}} \forall x (S(x, y) \wedge R(x))$. Together these imply $\mathcal{M} \not\models \exists y \forall x (S(x, y) \wedge R(x))$.

4 (a)

answer + explanation

From the table

| | p | q | $p \vee q$ | $\neg q$ | $\text{EX } \neg q$ | $q \rightarrow \text{EX } \neg q$ | $(p \vee q) \wedge (q \rightarrow \text{EX } \neg q)$ | φ |
|---|-----|-----|------------|----------|---------------------|-----------------------------------|---|-----------|
| 1 | ✓ | | ✓ | ✓ | | ✓ | ✓ | ✓ |
| 2 | | ✓ | ✓ | | | | | |
| 3 | | ✓ | ✓ | | ✓ | ✓ | ✓ | ✓ |
| 4 | | | | ✓ | ✓ | ✓ | | |
| 5 | ✓ | | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |

we conclude that the CTL formula $\varphi = \text{EG}((p \vee q) \wedge (q \rightarrow \text{EX } \neg q))$ holds in states 1, 3 and 5 of \mathcal{M} .

(b)

answer + explanation

The requirement q restricts the possible initial states to 2 and 3. Because the next state may not satisfy q , this only leaves state 3. State 4 satisfies neither p nor q , so $p \text{U} q$ is not satisfied, and the only possible successor is state 5. The path may loop in state 5, but to discharge $p \text{U} q$, eventually the path needs to leave state 5. The only option to do so is via state 1, which satisfies p , and all its successors satisfy q , which then discharges $p \text{U} q$. Thus, all paths satisfying the formula must have the prefix $3 5^+ 1$, and all paths which start with this prefix satisfy the formula.

(c) *answer + explanation*

For instance,

$$\chi_1 = p \wedge \neg \text{EG } p$$

$$\chi_2 = \text{EG } q$$

$$\chi_3 = q \wedge \text{AF } \neg q$$

$$\chi_4 = \text{EG } (\neg p \wedge \neg q)$$

$$\chi_5 = \text{EG } p$$

One easily checks that $\mathcal{M}, j \models \chi_i$ if and only if $j = i$:

| | p | q | $\neg p$ | $\neg q$ | $\neg p \wedge \neg q$ | $\neg \text{EG } p$ | $\text{AF } \neg q$ | χ_1 | χ_2 | χ_3 | χ_4 | χ_5 |
|---|-----|-----|----------|----------|------------------------|---------------------|---------------------|----------|----------|----------|----------|----------|
| 1 | ✓ | | | ✓ | | ✓ | ✓ | ✓ | | | | |
| 2 | | ✓ | ✓ | | | ✓ | | | ✓ | | | |
| 3 | | ✓ | ✓ | | | ✓ | ✓ | | | ✓ | | |
| 4 | | | ✓ | ✓ | ✓ | ✓ | ✓ | | | | ✓ | |
| 5 | ✓ | | | ✓ | | | ✓ | | | | | ✓ |

5

true false statement

The sequent $p \rightarrow q \vdash \neg p \rightarrow \neg q$ is not valid.

The function $f(x, y) = x \oplus y \oplus \bar{y}$ is monotone.

Resolution is complete but not sound for predicate logic.

Satisfaction of CTL formulas in finite models is decidable.

In DPLL any backjump can always be simulated by a backtrack instead.

It is not possible to verify if some comparator network is a sorting network.

The CTL formula $p \wedge \text{EXEF } p$ is semantically equivalent to the LTL formula $\text{F } p$.

For every boolean function there exist at least two different reduced BDD representations. *(all answers received 2 points)*

The Skolem normal form of a predicate logic formula cannot contain any existential quantifiers.

The substitution $\{x \mapsto h(z), y \mapsto h(z)\}$ is a most general unifier of the terms $f(x, y, g(x))$ and $f(h(z), h(z), g(z))$.