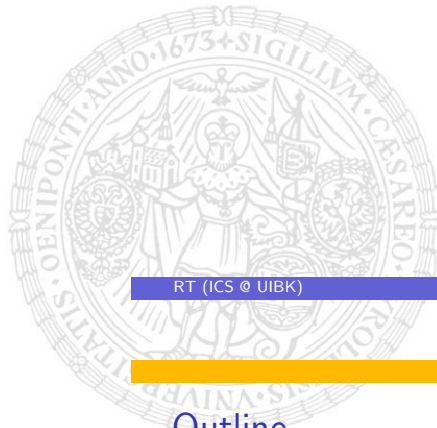


## Introduction to Model Checking

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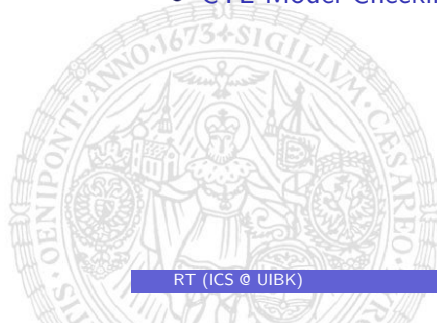
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### Outline

- Last Lecture
- CTL Model Checking



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# Computation Tree Logic

- Formulas over states (capital greek letters)
  - true
  - $a \in AP$  atomic proposition
  - $\neg \Phi$  and  $\Phi \wedge \Psi$  negation and conjunction
  - $E \varphi$  there exists a path fulfilling  $\varphi$
  - $A \varphi$  all paths fulfill  $\varphi$
- Formulas over paths (lower case greek letters)
  - $X \Phi$  the next state fulfills  $\Phi$
  - $\Phi U \Psi$   $\Phi$  holds until a  $\Psi$ -state is reached

## Semantics of CTL

A state-formula  $\Phi$  holds in state  $s$  (written  $s \models \Phi$ ) iff

- $s \models \text{true}$
- $s \models a$  iff  $a \in L(s)$
- $s \models \neg \Phi$  iff  $s \not\models \Phi$
- $s \models \Phi \wedge \Psi$  iff  $s \models \Phi$  and  $s \models \Psi$
- $s \models E \varphi$  iff  $\pi \models \varphi$  for some path  $\pi$  that starts in  $s$
- $s \models A \varphi$  iff  $\pi \models \varphi$  for all paths  $\pi$  that start in  $s$

A path-formula  $\varphi$  holds for path  $\pi$  (written  $\pi \models \varphi$ ) iff

- $\pi \models X \Phi$  iff  $\pi[1] \models \Phi$
- $\pi \models \Phi U \Psi$  iff  $(\exists j \geq 0. \pi[j] \models \Psi \text{ and } (\forall 0 \leq k < j. \pi[k] \models \Phi))$

where  $\pi[j]$  denotes the state  $s_j$  in the path  $\pi = s_0 s_1 s_2 \dots$

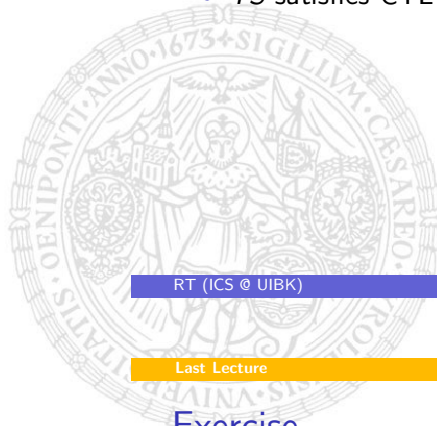
## Transition System Semantics

- For CTL-state-formula  $\Phi$ , the **satisfaction set**  $Sat(\Phi)$  is defined by:

$$Sat(\Phi) = \{s \in S \mid s \models \Phi\}$$

- $TS$  satisfies CTL-state-formula  $\Phi$  iff  $\Phi$  holds in all its initial states:

$$I \subseteq Sat(\Phi)$$



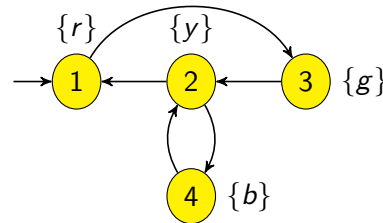
## Exercise

Provide two transition systems  $TS_1, TS_2$  (same atomic propositions, every state has at least one outgoing edge) and a CTL-formula  $\Phi$  such that  $Traces(TS_1) = Traces(TS_2)$  and  $TS_1 \models \Phi$ , but  $TS_2 \not\models \Phi$ .



## Exercise

Consider the following transition system which models a traffic light which can blink.



Compute the set  $Sat(\Phi)$  for the following formulas.

- $AF y$
- $AF g$
- $A(\neg b U b)$
- $AG y$
- $EF g$
- $E(\neg b U b)$
- $AGAF y$
- $EG g$
- $AGAF b$

## Main Idea

- Semantics of CTL-state formula  $\Phi$  is defined inductively on sub-formulas ( $Sat(\Phi)$  is set of satisfying states)
- $\Rightarrow$  compute  $Sat(\Psi)$  inductively for all sub-state-formulas  $\Psi$  of  $\Phi$
- $\Rightarrow$  afterwards model checking can be done by checking  $I \subseteq Sat(\Phi)$

CTL Model checking boils down to simple set operations  
no Büchi automata required

## CTL Model Checking: Everything but Until

Let  $TS = (S, \rightarrow, I, AP, L)$

- $s \models \text{true}$

$$\Rightarrow \text{Sat}(\text{true}) = S$$

- $s \models a$  iff  $a \in L(s)$

$$\Rightarrow \text{Sat}(a) = \{s \mid a \in L(s)\}$$

- $s \models \neg \Phi$  iff  $s \not\models \Phi$

$$\Rightarrow \text{Sat}(\neg \Phi) = S \setminus \text{Sat}(\Phi)$$

- $s \models \Phi \wedge \Psi$  iff  $s \models \Phi$  and  $s \models \Psi$

$$\Rightarrow \text{Sat}(\Phi \wedge \Psi) = \text{Sat}(\Phi) \cap \text{Sat}(\Psi)$$

- $s \models \text{EX } \Phi$  iff there is a path  $s \ s' \ s'' \dots$  such that  $s' \models \Phi$

$$\Rightarrow \text{Sat}(\text{EX } \Phi) = \{s \mid \exists s' : s \rightarrow s', s' \in \text{Sat}(\Phi)\}$$

- $s \models \text{AX } \Phi$  iff for all paths  $s \ s' \ s'' \dots$  it holds:  $s' \models \Phi$

$$\Rightarrow \text{Sat}(\text{AX } \Phi) = \{s \mid \forall s' : s \rightarrow s' \Rightarrow s' \in \text{Sat}(\Phi)\}$$

## CTL Model Checking: Until

Remember LTL equivalence:

$$\Phi \text{ U } \Psi \equiv \Psi \vee (\Phi \wedge X(\Phi \text{ U } \Psi))$$

In CTL:

$$\text{E } \Phi \text{ U } \Psi \equiv \Psi \vee (\Phi \wedge \text{EX}(\text{E } \Phi \text{ U } \Psi))$$

Hence:

$$\begin{aligned} \text{Sat}(\text{E } \Phi \text{ U } \Psi) &\equiv \text{Sat}(\Psi) \cup (\text{Sat}(\Phi) \cap \text{Sat}(\text{EX}(\text{E } \Phi \text{ U } \Psi))) \\ &\equiv \text{Sat}(\Psi) \cup (\text{Sat}(\Phi) \cap \{s \mid \exists s' : s \rightarrow s', s' \in \text{Sat}(\text{E } \Phi \text{ U } \Psi)\}) \end{aligned}$$

One can prove that  $\text{Sat}(\text{E } \Phi \text{ U } \Psi)$  is least set  $T$  satisfying

$$T = \text{Sat}(\Psi) \cup (\text{Sat}(\Phi) \cap \{s \mid \exists s' : s \rightarrow s', s' \in T\})$$

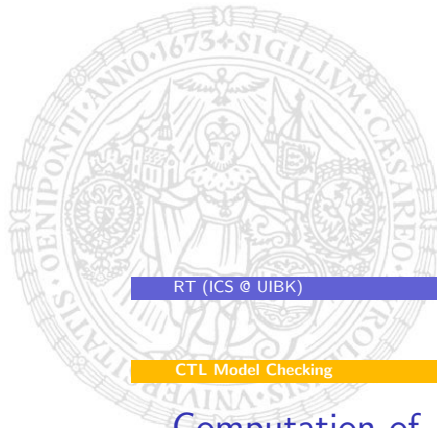
## CTL Model Checking: Until (2)

$Sat(E \Phi U \Psi)$  is least set  $T$  satisfying

$$T = Sat(\Psi) \cup (Sat(\Phi) \cap \{s \mid \exists s' : s \rightarrow s', s' \in T\})$$

Corresponding operation  $o : 2^S \rightarrow 2^S$ :

$$o(T) = Sat(\Psi) \cup (Sat(\Phi) \cap \{s \mid \exists s' : s \rightarrow s', s' \in T\})$$

Computation of  $Sat(E \Phi U \Psi)$ 

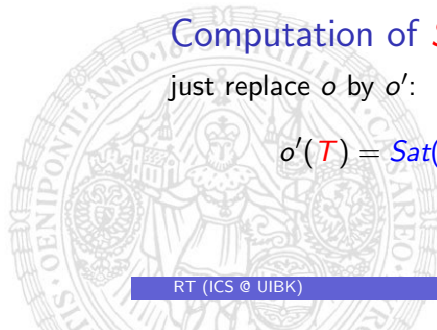
Define

$$o(T) = Sat(\Psi) \cup (Sat(\Phi) \cap \{s \mid \exists s' : s \rightarrow s', s' \in T\})$$

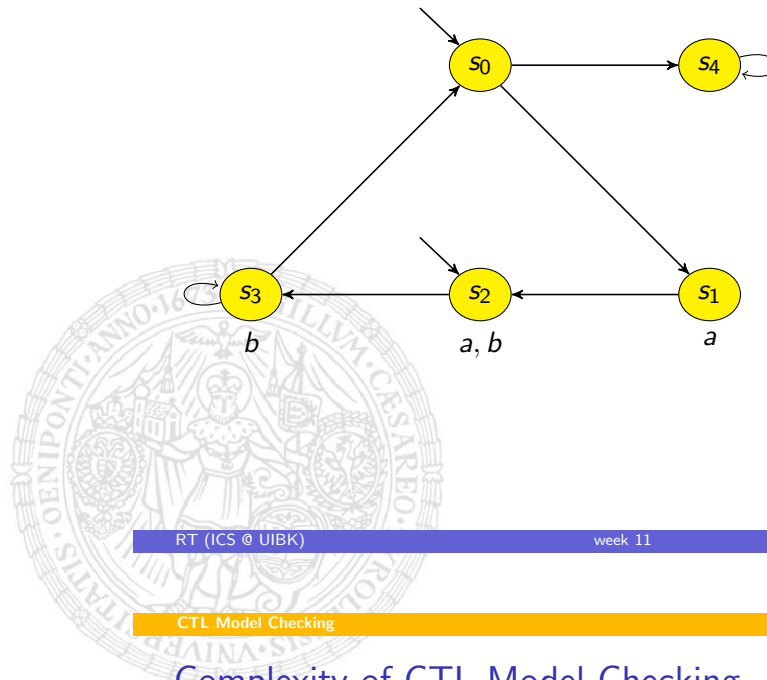
Computation of  $Sat(A \Phi U \Psi)$ 

just replace  $o$  by  $o'$ :

$$o'(T) = Sat(\Psi) \cup (Sat(\Phi) \cap \{s \mid \forall s' : s \rightarrow s' \Rightarrow s' \in T\})$$



## Example



## Complexity of CTL Model Checking

Model-Checking  $TS = (S, \rightarrow, I, AP, L) \models \Phi$ :

- Number of sets  $Sat(\Psi)$  to be computed:  $|\Phi|$
  - Complexity of computing a single set  $Sat(\Psi)$ :  
 $\mathcal{O}(|S| + |\rightarrow|) \leq \mathcal{O}(|TS|)$
  - Complexity of checking  $I \subseteq Sat(\Psi)$ :  $\mathcal{O}(|I|) \leq \mathcal{O}(|TS|)$
- $\Rightarrow$  overall complexity:  $\mathcal{O}(|\Phi| \cdot |TS|)$

## Exercises

- Consider the transition system on Slide 15 where  $L(s_4)$  is changed to  $\{b\}$ . Does the modified model satisfy the formula  $\Phi$ ?

$$\Phi = A(a U b) \vee EX(A G b)$$

Use the algorithm of this lecture with an additional rule for disjunction.

$$Sat(\Psi \vee \Psi') = Sat(\Psi) \cup Sat(\Psi')$$

- Provide a direct fixpoint characterization of  $Sat(EG \Phi)$  without using the following equivalence.

$$EG \Phi \equiv \neg AF \neg \Phi \equiv \neg A \text{ true } U \neg \Phi$$

