

# Game Theory

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## Summary of Last Lecture

### Example

consider the following game  $\Gamma$

	$C_2$	
	$L$	$R$
$C_1$		
$T$	0, 0	0, -1
$B$	1, 0	-1, 3

the unique equilibrium is

$$\left(\frac{3}{4}[T] + \frac{1}{4}[B], \frac{1}{2}[L] + \frac{1}{2}[R]\right)$$

based on  $\Gamma$  we can define a Bayesian game  $\Gamma^b$  (using parameter  $\epsilon$  with Bayesian equilibrium  $(\sigma_1, \sigma_2)$ )

$$\sigma_1(\cdot|\alpha) = \begin{cases} [T] & \alpha > \frac{2+\epsilon}{8+\epsilon^2} \\ [B] & \alpha < \frac{2+\epsilon}{8+\epsilon^2} \end{cases} \quad \sigma_2(\cdot|\beta) = \begin{cases} [L] & \beta > \frac{4-\epsilon}{8+\epsilon^2} \\ [B] & \beta < \frac{4-\epsilon}{8+\epsilon^2} \end{cases}$$

## Observation

if  $\epsilon \rightarrow 0$ , the Bayesian equilibrium  $(\sigma_1, \sigma_2)$  becomes the unique equilibrium in the game with complete information

## Auctions

not really a new idea

- used by the Babylonians (500 BC)
- first Roman fire brigade offered to buy the burning house and only extinguished the fire if the offer was accepted
- after having killed Emperor Pertinax, the Prätorian Guard auctioned off the Roman Empire (193)
- Johann Wolfgang von Goethe sold a manuscript through a second-price auction (1797)
- biggest revenue yet was generated by the US FCC spectrum auctions (1994–2008)

## First Price Auctions

- let  $F$  be an increasing and differentiable function
- let  $M$  be the maximal value of the object
- and let  $\beta$  denote the bidding function  
assumed to be increasing and differentiable

## Lemma

assume types/bids are uniformly distributed ( $F(y) = \frac{y}{M}$ ):

$$\beta(v_i) = (1 - \frac{1}{n})v_i \quad \forall v_i \in [0, M]$$

## Definition

- an auction where the private values are independent is called **independent private values**
- if the value of the object is the same for all bidders, but the bidders have different private information, the auction is an **common value** auction

# Content

motivation, introduction to decision theory, decision theory

basic model of game theory, dominated strategies, common knowledge, Bayesian games, incomplete information, Nash equilibrium

two-person zero-sum games, Bayesian equilibria, sequential equilibria of extensive-form games, subgame-perfect equilibria

(efficient) computation of Nash equilibria, complexity class PPD, complexity of Nash equilibria, refinements of equilibrium in strategic form, persistent equilibria, games with communication, sender-receiver games

## Mixed and Behavioural Strategies

given a game  $\Gamma^e$  in extensive form, we defined the normal representation of  $\Gamma^e$  as a strategic-form game  $\Gamma = (N, (C_i)_{i \in N}, (u_i)_{i \in N})$

### Definition

- 1  $\forall i \in N$ ,  $S_i$  denotes information states of  $i$ ; set  $S^* = \bigcup_{i \in N} S_i$
- 2  $\forall s \in S_i$ , let  $Y_s$  denote the set of nodes that belong to  $i$  in information state  $s$
- 3  $D_s$  is the set of possible moves at  $s$
- 4 define strategies  $C_i = \prod_{s \in S_i} D_s$

### Definition

a mixed-strategy profile of  $\Gamma^e$  is any randomised strategy of the normal representation of  $\Gamma^e$ ; set of profiles is

$$\prod_{i \in N} \Delta(C_i)$$

# Multiagent Representation

let  $\Gamma^e$  be a game in extensive form

## Definition

multiagent representation

the **multiagent representation** of  $\Gamma^e$  is the strategic-form game

$$\Gamma' = (S^*, (D_s)_{s \in S^*}, (v_s)_{s \in S^*})$$

- 1  $S^*$  is the collection of all information states
- 2  $D_s$  is the set of moves at each state  $s$
- 3  $v_s: \prod_{s \in S^*} D_s \rightarrow \mathbb{R}$ , if for any  $(c_i)_{i \in N} \forall i \in N, t \in S_i: c_i(t) = d_t$ , then  $v_s((d_s)_{s \in S^*}) = u_i((c_i)_{i \in N})$

## Definition

a **behavioural-strategy profile** of  $\Gamma^e$  is any randomised strategy of the multiagent representation of  $\Gamma^e$ ; set of profiles is

$$\prod_{s \in S^*} \Delta(D_s) = \prod_{i \in N} \prod_{s \in S_i} \Delta(D_s)$$

## Definition

- $\forall$  player  $i$
- $\forall$  pure strategies  $c_i \in C_i$
- $\forall$  information state  $s \in S_i$

$s$  and  $c_i$  are **compatible** if  $\exists c_{-i} \in C_{-i}$  such that  $\sum_{x \in Y_s} P(x|c) > 0$

## Definition

$C_i^*, C_i^\dagger$

- 1  $C_i^*(s)$  denotes all strategies in  $C_i$  compatible with information state  $s$
- 2  $C_i^\dagger(d_s, s) = \{c_i \in C_i^*(s) \mid c_i(s) = d_s\}$

## Definition

a behavioural strategy  $\sigma_i = (\sigma_{i,s})_{s \in S_i}$  is **behavioural representation** of a mixed strategy  $\tau_i \in \Delta(C_i)$  if

$$\sigma_{i,s}(d_s) \left( \sum_{c_i \in C_i^*(s)} \tau(c_i) \right) = \sum_{e_i \in C_i^\dagger(d_i, s)} \tau(e_i)$$

## Definition

- 1 two mixed strategies are **behaviourally equivalent** if they share a common behavioural representation
- 2 two mixed strategy profiles  $\tau, \tau'$  (in  $\prod_{i \in N} \Delta(C_i)$ ) are **behaviourally equivalent** if  $\forall i$   $\tau_i$  and  $\tau'_i$  are behaviourally equivalent

## Theorem

if  $\Gamma^e$  is a game with perfect recall, then any two mixed strategies in  $\Delta(C_i)$  that are behaviourally equivalent are payoff equivalent

## Remark

the condition on perfect recall is crucial

## Definition

for any behavioural strategy  $\sigma_i = (\sigma_{i,s})_{s \in S_i}$ , the **mixed representation**  $\tau_i \in \Delta(C_i)$  satisfies

$$\tau_i(c_i) = \prod_{s \in S_i} \sigma_{i,s}(c_i(s)) \quad \forall c_i$$

## Equilibria in Behavioural Strategies

## Definition

a (Nash) equilibrium of an extensive-form game is any equilibrium  $\sigma$  of the multiagent representation such that the mixed representation of  $\sigma$  is an equilibrium of the normal representation

## Theorem

if  $\Gamma^e$  admits perfect recall and  $\tau$  is an equilibrium of the normal representation of  $\Gamma^e$ , then any behavioural representation of  $\tau$  is an equilibrium (of the multiagent representation of  $\Gamma^e$ )

## Theorem

$\forall \Gamma^e$  with perfect recall  $\exists$  a Nash equilibrium (of  $\Gamma^e$ )

# Games with Perfect Information

## Recall

a game with **perfect information** is any extensive-form game in which each information state is unique

## Definition

- a node  $x \in \Gamma^e$  is a **subroot** if for every  $s \in S^*$  either  $Y_s \cap \Gamma^e|_x = \emptyset$  or  $Y_s \subseteq \Gamma^e|_x$
- a subgame of  $\Gamma^e$  is the game induced by a  $\Gamma^e|_x$  for subroot  $x$
- an equilibrium  $\sigma$  of  $\Gamma^e$  is **subgame-perfect** if for each subgame of  $\Gamma^e$  (the obvious restriction of)  $\sigma$  is an equilibrium

## Theorem

- if  $\Gamma^e$  has perfect information, then there exists at least one pure and subgame-perfect equilibrium
- any game with perfect information admits a winning strategy