

# Game Theory

Georg Moser

Institute of Computer Science @ UIBK

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## Content

motivation, introduction to decision theory, decision theory

basic model of game theory, dominated strategies, common knowledge, Bayesian games, incomplete information, Nash equilibrium

two-person zero-sum games, Bayesian equilibria, sequential equilibria of extensive-form games, subgame-perfect equilibria

(efficient) computation of Nash equilibria, complexity class PPD, complexity of Nash equilibria

## Summary of Last Lecture

### Algorithm

- INPUT: a nondegenerate bimatrix game
- OUTPUT: all Nash equilibria

### Method

- 1  $\forall k \in \{1, \dots, \min\{m, n\}\}$
- 2  $\forall k$ -sized subsets  $(I, J)$  of  $M, N$
- 3 solve the following equation

$$\begin{aligned} \sum_{i \in I} x_i b_{ij} &= v \quad \text{for } j \in J & \sum_{j \in J} a_{ij} y_j &= u \quad \text{for } i \in I \\ \sum_{i \in I} x_i &= 1 & \sum_{j \in J} y_j &= 1 \end{aligned}$$

such that  $x \geq 0$ ,  $y \geq 0$  and the best response condition is fulfilled for  $x$  and  $y$

## Equilibria via Labeled Polytopes

### Definition

- an **affine combination** of points  $z_1, \dots, z_k$  is of form

$$\sum_{i=1}^k z_i \lambda_i \quad \lambda_i \in \mathbb{R} \quad \sum_{i=1}^k \lambda_i = 1$$

- it is called **convex combination** if  $\lambda_i \geq 0$  for all  $i$
- a set of points is **convex** if closed under forming convex combinations
- points are **affinely independent** if none is an affine combinations of others
- a convex set has **dimension**  $d$  if it has  $d + 1$  (but not more) affinely independent points

## Definition

- a **polyhedron**  $P \in \mathbb{R}^d$  is a set
 
$$\{z \in \mathbb{R}^d \mid Cz \leq q\} \quad \text{for some matrix } C, \text{ vector } q$$
- $P$  is **full-dimensional** if it has dimension  $d$  (i.e.,  $d + 1$  (but not more) affinely independent elements)
- $P$  is a **polytope** if bounded
- the **face** of  $P$  is  $\{z \in P \mid c^\top z = q_0\}$  for  $c \in \mathbb{R}^d, q_0 \in \mathbb{R}$

## Example

the following objects are polytopes

- pyramids, i.e., tetrahedrons
- Rubben's cube
- octahedron
- dices in rôle games, i.e., icosahedron

Definition let  $P$  denote a polyhedron

- a **vertex** of  $P$  is the unique element of a zero-dimensional face of  $P$
- an **edge** is a one-dimensional face of  $P$
- a **facet** of a  $d$ -dimensional  $P$  is a  $d - 1$ -dimensional face

## Definition

best response polyhedron

the **best response polyhedron** of a player is the set of that player's mixed strategies together with a bound of expected payoffs to the **other** player

## Example

consider  $\Gamma$

$$A = \begin{pmatrix} 3 & 3 \\ 2 & 5 \\ 0 & 6 \end{pmatrix} \quad B = \begin{pmatrix} 3 & 2 \\ 2 & 6 \\ 3 & 1 \end{pmatrix}$$

then

$$\overline{Q} = \left\{ (y_4, y_5, u) \mid \begin{array}{l} 3y_4 + 3y_5 \leq u, \quad 3y_4 + 5y_5 \leq u, \quad 6y_5 \leq u, \\ y_4 \geq 0, \quad y_5 \geq 0, \quad y_4 + y_5 = 1 \end{array} \right\}$$

## Definition

best response polyhedra for player 1 and 2

$$\overline{P} = \{(x, v) \in \mathbb{R}^m \times \mathbb{R} \mid x \geq 0, \mathbf{1}^\top x = 1, B^\top x \leq \mathbf{1}v\}$$

$$\overline{Q} = \{(y, u) \in \mathbb{R}^n \times \mathbb{R} \mid Ay \leq \mathbf{1}u, y \geq 0, \mathbf{1}^\top y = 1\}$$

## Definition

a point  $(y, u) \in \overline{Q}$  has **label**  $k \in M \cup N$  if

- the  $k^{\text{th}}$  inequality in the definition of  $\overline{Q}$  is **binding**
- i.e.,  $\sum_{j \in N} a_{kj} y_j = u$  if  $k = i \in M$  or
- for  $k = j \in N, y_j = 0$

## Example

the point  $(\frac{2}{3}, \frac{1}{3}, 3)$  has labels 1 and 2, as  $x_1, x_2$  are best responses to  $y$  for player 1 that yields pay-off 3

## Definition

a point  $(x, v) \in \overline{P}$  has **label**  $k \in M \cup N$  if

- $k = i \in M$  and  $x_i = 0$  or
- $k = j \in N$  and  $\sum_{i \in M} b_{ik} x_i = v$

## Lemma

an equilibrium  $(x, y)$  is a pair such that

- pair  $((x, v), (y, u)) \in \overline{P} \times \overline{Q}$
- this pair is completely labeled, i.e. every label  $k \in M \cup N$  labels either  $(x, v)$  or  $(y, u)$

## Proof

again this is a reformulation of the best response condition



## Assumptions

suppose  $A$  and  $B^\top$  are non-negative and have no zero columns

## Definition

consider  $\bar{P}$ :

- we divide each  $\sum_{i \in M} b_{ij} x_i \leq v$  by  $v$
- this gives  $\sum_{i \in M} b_{ij} (\frac{x_i}{v}) \leq 1$
- we treat  $\frac{x_i}{v}$  as a new variable (again called  $x_i$ )

## Definition

the normalised **polytopes** have the following generic form:

$$P = \{x \in \mathbb{R}^m \mid x \geq \mathbf{0}, B^\top x \leq \mathbf{1}\}$$

$$Q = \{y \in \mathbb{R}^n \mid Ay \leq \mathbf{1}, y \geq \mathbf{0}\}$$

## Lemma

the polyhedra  $P$  and  $Q$  are full-dimensional polytopes, moreover there is a one-to-one correspondence between  $\bar{P}$  ( $\bar{Q}$ ) and  $P$  ( $Q$ ) such that the **labels are preserved**

consider  $\Gamma$ ,  $A = \begin{pmatrix} 3 & 3 \\ 2 & 5 \\ 0 & 6 \end{pmatrix}$  and  $B = \begin{pmatrix} 3 & 2 \\ 2 & 6 \\ 3 & 1 \end{pmatrix}$

the polyhedra  $\bar{P}$ ,  $\bar{Q}$  are defined as follows:

$$\bar{P} = \left\{ (x_1, x_2, x_3, v) \mid \begin{array}{ll} x_1 \geq 0 & \textcircled{1} \\ x_2 \geq 0 & \textcircled{2} \\ x_3 \geq 0 & \textcircled{3} \\ 3x_1 + 2x_2 + 3x_3 \leq v & \textcircled{4} \\ 2x_1 + 6x_2 + 1x_3 \leq v & \textcircled{5} \\ x_1 + x_2 + x_3 = 1 & \end{array} \right\}$$

$$\bar{Q} = \left\{ (y_4, y_5, u) \mid \begin{array}{ll} 3y_4 + 3y_5 \leq u & \textcircled{1} \\ 3y_4 + 5y_5 \leq u & \textcircled{2} \\ 6y_5 \leq u & \textcircled{3} \\ y_4 \geq 0 & \textcircled{4} \\ y_5 \geq 0 & \textcircled{5} \\ y_4 + y_5 = 1 & \end{array} \right\}$$

## Example

consider for example  $Q$ :

$$Q = \left\{ \left( \frac{y_4}{u}, \frac{y_5}{u} \right) \mid \begin{array}{ll} 3\frac{y_4}{u} + 3\frac{y_5}{u} \leq 1 & \textcircled{1} \\ 3\frac{y_4}{u} + 5\frac{y_5}{u} \leq 1 & \textcircled{2} \\ 6\frac{y_5}{u} \leq 1 & \textcircled{3} \\ \vdots & \end{array} \right\}$$

## Observation

- $P$ ,  $Q$  are bounded, hence polytopes
- in this transformation labels are preserved
- every vertex in  $P$  ( $Q$ ) has  $m$  ( $n$ ) labels as the game is nondegenerated

## Example

points of polytope  $P$ :

$$\begin{array}{ll} \mathbf{0} = (0, 0, 0) & \text{labels } \textcircled{1}, \textcircled{2}, \textcircled{3} \\ a = (\frac{1}{3}, 0, 0) & \text{labels } \textcircled{2}, \textcircled{3}, \textcircled{4} \\ b = (\frac{2}{7}, \frac{1}{14}, 0) & \text{labels } \textcircled{3}, \textcircled{4}, \textcircled{5} \\ c = (0, \frac{1}{6}, 0) & \text{labels } \textcircled{1}, \textcircled{3}, \textcircled{5} \\ d = (0, \frac{1}{8}, \frac{1}{4}) & \text{labels } \textcircled{1}, \textcircled{4}, \textcircled{5} \\ e = (0, 0, \frac{1}{3}) & \text{labels } \textcircled{1}, \textcircled{2}, \textcircled{4} \end{array}$$

## Example (cont'd)

points of polytope  $Q$ :

$$p = (0, \frac{1}{6})$$

labels ③, ④

$$q = (\frac{1}{12}, \frac{1}{6})$$

labels ②, ③

$$r = (\frac{1}{6}, \frac{1}{9})$$

labels ①, ②

$$s = (\frac{1}{3}, 0)$$

labels ①, ⑤

## Algorithm

- INPUT: a nondegenerate bimatrix game
- OUTPUT: all Nash equilibria

## Method

- 1 define polytopes  $P, Q$
- 2  $\forall$  vertex  $x$  of  $P - \{0\}$
- 3  $\forall$  vertex  $y$  of  $Q - \{0\}$
- 4 if  $(x, y)$  is completely labeled, output the Nash equilibrium

$$(x \cdot \frac{1}{\mathbf{1}^\top x}, y \cdot \frac{1}{\mathbf{1}^\top y})$$

## Observation

vertex enumeration is more efficient than support enumeration

## Nash equilibria and NP-completeness

## Definition

a **search problem**  $S$  consists of

- 1 a set of **inputs**  $I_S \subseteq \Sigma^*$
- 2  $\forall x \in I_S \exists$  **solution set**  $S_x \subseteq \Sigma^{|x|^k}$  for some integer  $k$
- 3 such that  $\forall x \in I_S \forall y \in \Sigma^*$  it is decidable in polytime whether  $y \in S_x$

a search problem is **total** if  $\forall x \in I_S S_x \neq \emptyset$ 

## Definition

we write NASH for the problem of finding a Nash equilibrium in a game in strategic form

## Example

NASH is a total search problem

## NP-completeness of Generalisations

## Definition

a bimatrix game  $\Gamma$  represented by payoff matrices  $A$  and  $B$  is **symmetric** if  $A = B^\top$ 

## Theorem

the following problems are complete for NP (even for symmetric games): given a two-player game  $\Gamma$  in strategic form, does  $\Gamma$  have:

- at least two Nash equilibria?
- a Nash equilibrium in which player  $i$  has utility at least a given amount?
- a Nash equilibrium with support of size greater than a given number?
- a Nash equilibrium whose support contains strategy  $s$ ?
- ...

## The Class Polynomial Parity Argument (Directed Case)

the class PPAD can be defined as the class of total search problems, where totality follows from an argument like follows

- a directed graph  $G$  is defined on a finite but exponentially large set of vertexes
- each vertex has indegree and outdegree at most 1
- given a vertex  $x$  is easy to check that
  - 1  $x \in G$
  - 2 find the adjacent vertexes of  $x$
  - 3 identify the direction of the edge
- $\exists$  a vertex with no incoming edges that is known (the **standard source**)
- all vertexes with no outgoing edges, or all sources other than the standard source are solutions

### Example

NASH  $\in$  PPAD

## Graphical Games

### Definition

a **graphical game** is a  $n$ -person game, with  $n$  large, but the utility of each player depends only on the strategies of few other players

- $\exists$  directed graph  $G = (\{1, \dots, n\}, E)$
- such that  $(i, j) \in E$  implies that the utility of player  $j$  depends on the strategy chosen by player  $i$
- $\forall$  mixed strategies  $x, y$  if  $x_j = y_j$  and  $\forall (i, j) \in E: x_i = y_i$ , then  $u_j(x) = u_j(y)$

### Observation ③

given a graphical  $n$ -player game  $\Gamma$  such that

- indegree of the graph  $G$  at most  $d$
- maximal  $m$  pure strategy per player

then  $\Gamma$  needs only  $nm^{d+1}$  numbers for its description

## Succinct Representations of Games

### Observation ①

- given an  $n$ -player game
- such that each player has the same number of (pure) strategies  $m$
- then representing a game in strategic form needs  $nm^n$  numbers

### Observation ②

this trivialises any complexity considerations:

- the support enumeration algorithm roughly needs  $(2^m)^n$  many steps
- but this is a **polynomial** algorithm in  $nm^n$ , if  $m$  is fixed

## NASH is complete for PPAD

### Definition

the problem BROUWER, a discrete version of Brouwer's fixpoint theorem: any continuous function  $f$  on (let's say) cube has a fixpoint

### Theorem

NASH (even for two players) is complete for PPAD

### Proof Sketch

- BROUWER is complete for PPAD
- reduction from BROUWER to a graphical game  $\Gamma$  with many players
- reduction from  $\Gamma$  to NASH

### Final Remark

if  $P = NP$ , then also  $P = PPAD$ , but  $P = PPAD$  need not imply  $P = NP$