

Introduction to Model Checking

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Outline

- Notations
- Transition systems
- Model Checking of Linear Time Properties
- Regular Languages
 - Finite Automata
 - Büchi Automata
 - Generalized Büchi Automata

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- sequences of states: $\rho = s_1s_2s_3 \dots \in S^\omega$

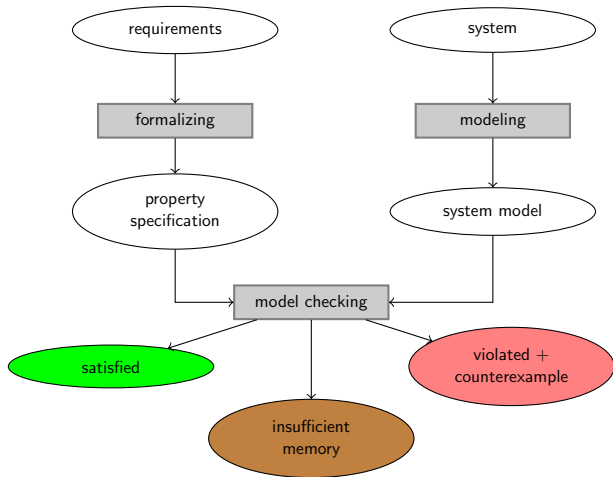
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- states: $S = \{s, t, \dots\}$
- sequences of states: $\rho = s_1s_2s_3 \dots \in S^\omega$
- **no distinction between set and its characterizing vector**
 example: if $AP = \{a_1, a_2, a_3\}$ then $w \in (2^{AP})^\omega$ is sequence of sets or equivalently, sequence of bitvectors

$$w = \{a_1, a_2\} \emptyset \{a_1, a_3\} \dots = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \dots$$

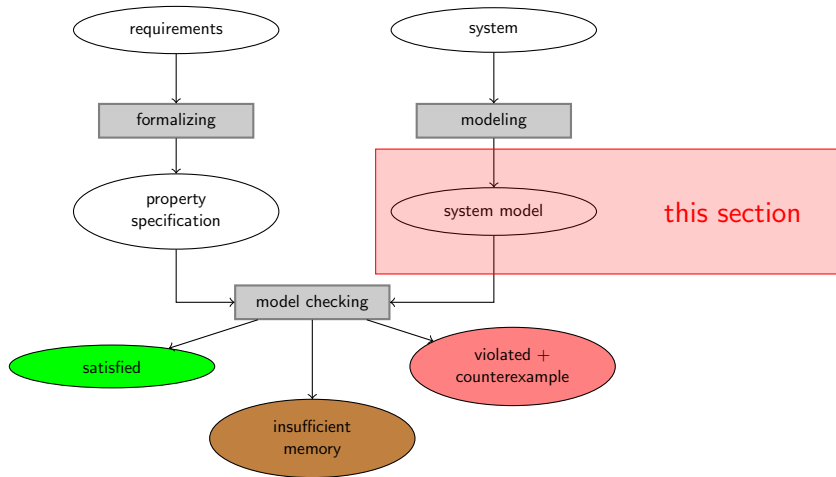
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Model checking overview



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Transition systems

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- digraphs where nodes represent **states**, and edges model **transitions**
- **state**:
 - the current phase of a traffic light
 - the current values of all program variables + the program counter
- **transition**: (“state change”)
 - a switch from one phase to the next one
 - the execution of a program statement

Transition system

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- AP is a set of **atomic propositions**
- $L : S \rightarrow 2^{AP}$ is a **labeling function**

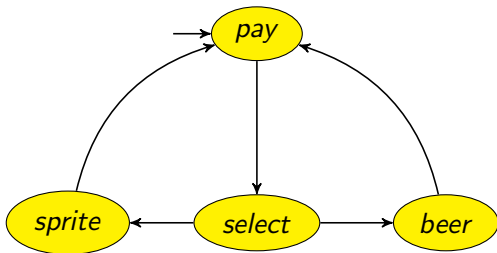
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notation: $s \rightarrow s'$ instead of $(s, s') \in \rightarrow$

A beverage vending machine



states?, transitions?, initial states?

$$TS = (S = \{pay, select, sprite, beer\}, \rightarrow, I = \{pay\}, AP, L)$$

where \rightarrow is the following set of transitions

$pay \rightarrow select$

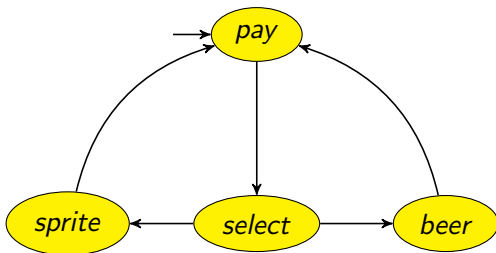
$select \rightarrow beer$

$beer \rightarrow pay$

$select \rightarrow sprite$

$sprite \rightarrow pay$

Atomic propositions?



(paid, beer paid, sprite paid will be displayed)

$$AP = \{\text{paid, sprite, beer}\}$$

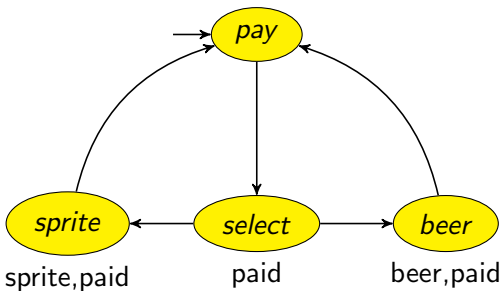
$$L(\text{pay}) = \emptyset$$

$$L(\text{select}) = \{\text{paid}\}$$

$$L(\text{beer}) = \{\text{beer, paid}\}$$

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 - only describes what a system should do, not **how**

The role of nondeterminism

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- to model **concurrency by interleaving**
 - no assumption about the relative speed of processes
- to model **implementation freedom**
 - only describes what a system should do, not **how**
- to model **under-specified** systems, or **abstractions** of real systems
 - use incomplete information

in automata theory, nondeterminism may be exponentially more succinct, but that's not the issue here!

Executions

- execution ρ of TS : sequence of states

$$\rho = s_0 s_1 \dots s_n \dots$$

such that

- $s_i \rightarrow s_{i+1}$ for all $0 \leq i \in \mathbb{N}$
- $s_0 \in I$

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- **trace** of an execution: sequence of sets of atomic propositions, i.e., $trace(\rho) \in (2^{AP})^\omega$

$$trace(\rho) = L(s_0) L(s_1) L(s_2) L(s_3) \dots$$

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- $Traces(TS)$: set of all traces of all executions of TS
it defines the **observable behaviour** of TS

Example

$$\rho = \text{pay} \rightarrow \text{select} \rightarrow \text{sprite} \rightarrow \text{pay} \rightarrow \text{select} \rightarrow \text{beer} \dots$$

$$\text{trace}(\rho) = \emptyset \{ \text{paid} \} \{ \text{paid, sprite} \} \emptyset \{ \text{paid} \} \{ \text{paid, beer} \} \dots$$

interesting properties

- without having paid there is no sprite (true)
- we will see beer infinitely often (false)
- after each beer another coin is inserted (not expressible, needs AP coin, paid may contain credit card)

states \sim implementation

- \Rightarrow **properties only speak about atomic propositions, never about states!**
 (we are not interesting in implementation, only result must be correct)

Summary

transition systems \neq finite automata since

- there are **no** accept states
- set of states may be countably infinite
(but in this lecture: only finite sets of states)
- may have infinite branching
- non-determinism has a different role

Summary

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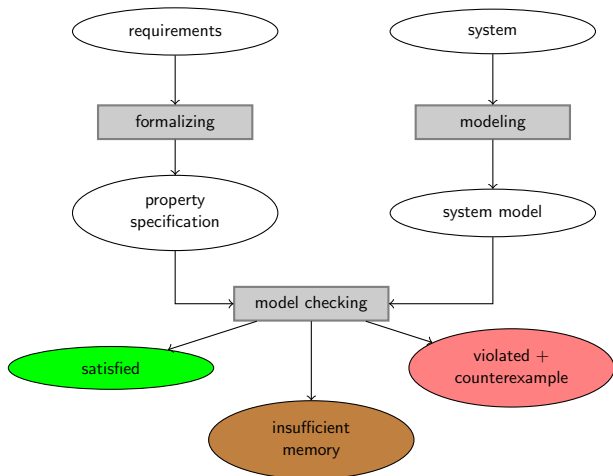
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\Rightarrow transition systems are appropriate for reactive system behavior

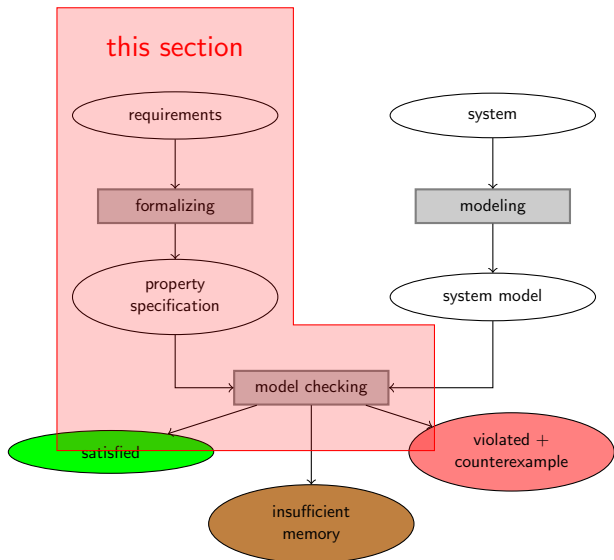
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Requirements \neq Specification

requirements

- high-level description (consider scheduler for exclusive access)
 - (the scheduler should be correct)
 - no two clients get access at the same time
 - the scheduler should be fair
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 - what we observe from system: $Traces(TS) \subseteq (2^{AP})^\omega$
- \Rightarrow how to answer question “does system satisfy requirements”?
 problem: too imprecise what is fair
- \Rightarrow we need requirements in a precise, i.e., mathematical **specification**

Linear Time Properties

one main idea to specify requirements: describe allowed traces

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- upcoming problems
 - how to **specify sets \mathcal{S} conveniently** ...
 - ... such that **$\text{Traces}(TS) \subseteq \mathcal{S}$ can be decided**

The requirements of model checking

essentially we need a mechanism to represent the set $\mathcal{S}(R)$ of **allowed traces** for some requirement R conveniently

- possible classes: finite, regular, context-free, context-sensitive, ...
- model checking requires checking $\text{Traces}(TS) \subseteq \mathcal{S}(R)$
or equivalently: $\text{Traces}(TS) \cap \mathcal{S}(\neg R) = \emptyset$
where $\neg R$ describes **forbidden traces**

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- closure under **intersection**
- **emptiness** decidable
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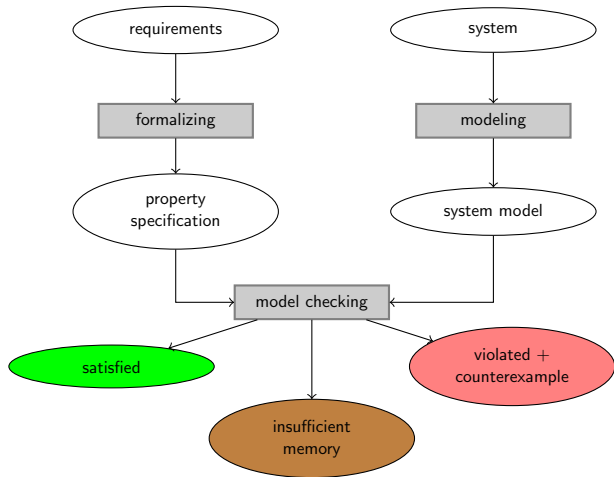
⇒ requirements on class of language

- closure under **intersection**
- **emptiness** decidable
- expressive enough to represent $\text{Traces}(TS)$ and $\mathcal{S}(\neg R)$
- use **regular languages**, they are closed under all boolean operations
- possible representations of regular languages
 - regular expressions
 - non-recursive grammars
 - **finite automata**

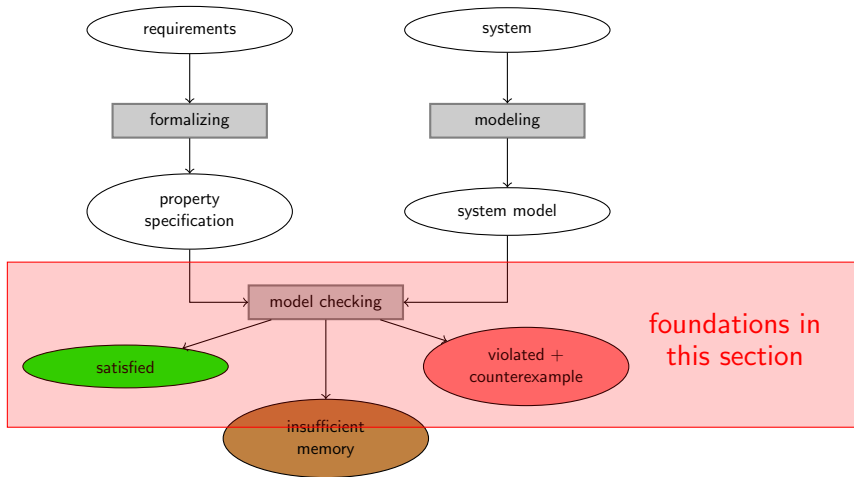
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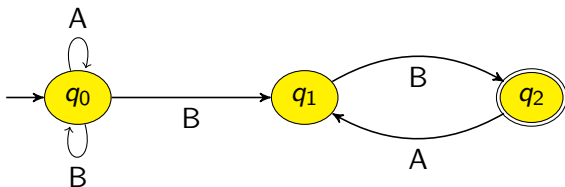
Model checking overview



Finite Automata

a **nondeterministic finite automaton** (NFA) \mathcal{A} is a tuple $(Q, \Sigma, \delta, q_0, F)$ where:

- $Q = \{q_0, \dots, q_n\}$ is a **finite set of states**
- Σ is an **alphabet**
- $\delta : Q \times \Sigma \rightarrow 2^Q$ is a **transition function**
- q_0 is the **initial state**
- $F \subseteq Q$ is a set of **final** (or: accepting) states



later, after definition: $\mathcal{L}(\mathcal{A}) = (A \vee B)^* BB(AB)^*$

Language of an NFA

- NFA $\mathcal{A} = (Q, \Sigma, \delta, q_0, F)$ and word $w = A_1 \dots A_n \in \Sigma^*$
- **run** of w in \mathcal{A} : finite sequence $q_0 q_1 \dots q_n$ such that
 - $q_i \xrightarrow{A_{i+1}} q_{i+1}$ for all $0 \leq i < n$

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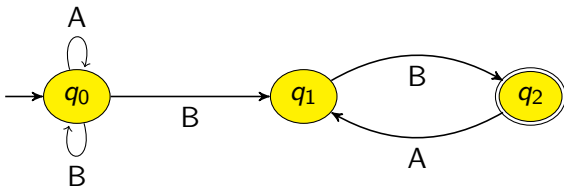
$$\mathcal{L}(\mathcal{A}) = \{ w \in \Sigma^* \mid \text{there exists an accepting run for } w \text{ in } \mathcal{A} \}$$

- NFA \mathcal{A} and \mathcal{A}' are **equivalent** iff $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\mathcal{A}')$
- language \mathcal{L} is **regular** iff $\mathcal{L} = \mathcal{L}(\mathcal{A})$ for some NFA \mathcal{A}

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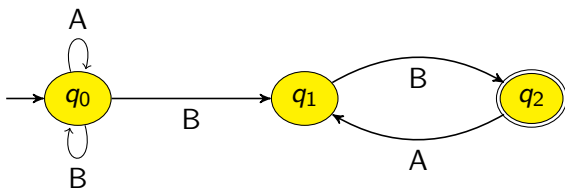


later, after definition: $\mathcal{L}(\mathcal{A}) = (A \vee B)^* BB(AB)^\omega = \dots BBABABAB \dots$

Büchi Automata

A *nondeterministic Büchi automaton* (NBA) \mathcal{A} is a tuple $(Q, \Sigma, \delta, q_0, F)$ where:

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Generalized Büchi Automata

generalized Büchi automaton (GNBA) is tuple

$\mathcal{A} = (Q, \Sigma, \delta, q_0, F_1, \dots, F_k)$ where

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- run $q_0 q_1 \dots q_n \dots$ is **accepting** iff for **each** $1 \leq j \leq k$ there are **infinitely many indices** $i: q_i \in F_j$

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- run $q_0 q_1 \dots q_n \dots$ is **accepting** iff for **each** $1 \leq j \leq k$ there are **infinitely many indices** $i: q_i \in F_j$
- NBAs are GNBA's where $k = 1$
- each GNBA can be translated into equivalent NBA (with states $Q \times \{1, \dots, \max(1, k)\}$)

GNBAs to specify requirements

Safety properties: (refutation by a finite prefix of an ω -word)

1. always at most one traffic light is showing green
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- GNBAs are closed under union, intersection, and negation

⇒ many interesting properties can be expressed by GNBAs

GNBAs to specify requirements

	R	$\neg R$
1.	$\begin{pmatrix} \text{green1} \\ \text{green2} \end{pmatrix} \quad k = 0$	
2.	$\begin{pmatrix} \text{red} \\ \text{green} \end{pmatrix} \quad k = 0$	
3.	$\begin{pmatrix} \text{red} \\ \text{green} \end{pmatrix}$	
4.	$\begin{pmatrix} \text{select} \\ \text{get} \end{pmatrix}$	

Recall: requirements of model checking

- model checking requires checking $Traces(TS) \cap \mathcal{S}(\neg R) = \emptyset$
where $\neg R$ describes forbidden traces

⇒ requirements on class of language

- expressive enough to represent $Traces(TS)$
- closure under **intersection**
- **emptiness** decidable

Expressing Transition Systems as GNBA

aim: for $TS = (S, \rightarrow, I, AP, L)$ construct \mathcal{A}_{TS} with $\mathcal{L}(\mathcal{A}_{TS}) = \text{Traces}(TS)$

problems:

- labels/letters are at the states in TS , but on the transitions in GNBA
- several initial states in TS , but only one initial state in GNBA

Expressing Transition Systems as GNBA

aim: for $TS = (S, \rightarrow, I, AP, L)$ construct \mathcal{A}_{TS} with $\mathcal{L}(\mathcal{A}_{TS}) = \text{Traces}(TS)$

problems:

- labels/letters are at the states in TS , but on the transitions in GNBA
- several initial states in TS , but only one initial state in GNBA

solution:

- label A of transition system state corresponds to upcoming letter to read in GNBA
- use states of TS as states of GNBA, but use new initial state

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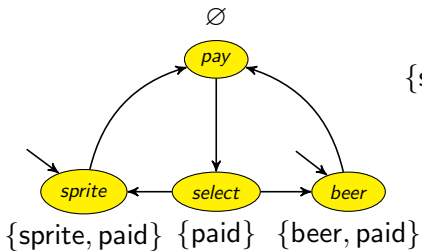
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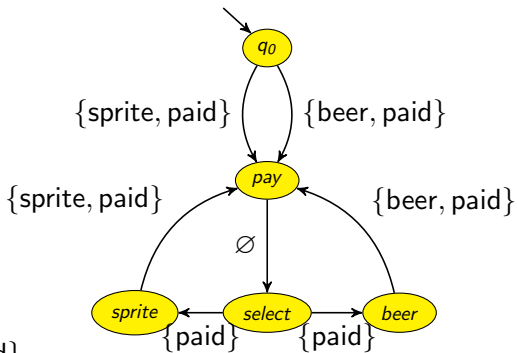
concrete: $\mathcal{A}_{TS} = (S \uplus \{q_0\}, 2^{AP}, \delta, q_0)$ with δ defined as follows

- $\delta(s, A) = \{s' \mid L(s) = A, s \rightarrow s'\}$
- $\delta(q_0, A) = \bigcup_{s \in I} \delta(s, A)$

Example



TS



\mathcal{A}_{TS}

Soundness of \mathcal{A}_{TS}

Theorem

$$\mathcal{L}(\mathcal{A}_{TS}) = \text{Traces}(TS)$$

let $w = A_0 A_1 A_2 \dots$

- $w \in \text{Traces}(TS)$
- iff exist execution $s_0 s_1 s_2 \dots$ of TS :
 $s_0 \in I$ and for all $i \in \mathbb{N}$:
 - $L(s_i) = A_i$
 - $s_i \rightarrow s_{i+1}$
- iff exist (accepting) run $q_0 s_1 s_2 \dots$ of \mathcal{A}_{TS} :
 $s_1 \in \delta(q_0, A_0)$ and for all $i \geq 1$:
 - $s_{i+1} \in \delta(s_i, A_i)$
- iff $w \in \mathcal{L}(\mathcal{A}_{TS})$

GNBA for Intersection

aim: for $\mathcal{A}_i = (\mathcal{Q}_i, \Sigma, \delta_i, q_{0,i}, F_{1,i}, \dots, F_{k_i,i})$ construct $\mathcal{A}_{\mathcal{A}_1 \cap \mathcal{A}_2}$ with
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idea: simulate runs in \mathcal{A}_1 and \mathcal{A}_2 in parallel

- use cartesian product of states
- demand that all final states are visited infinitely often

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- $Q = Q_1 \times Q_2$

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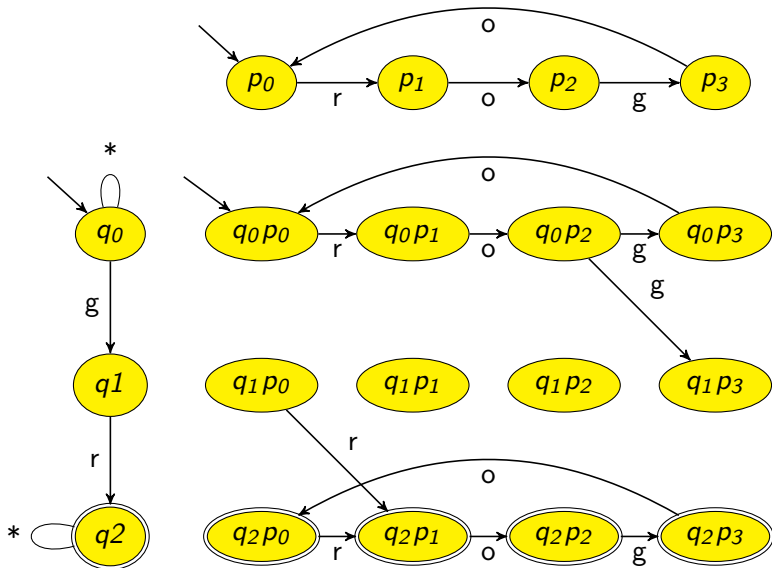
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- $F'_j = F_{j,1} \times \mathcal{Q}_2$ and $F''_j = \mathcal{Q}_1 \times F_{j,2}$

Example: no direct switch from green to red



Soundness of $\mathcal{A}_{\mathcal{A}_1 \cap \mathcal{A}_2}$

Theorem

$$\mathcal{L}(\mathcal{A}_{\mathcal{A}_1 \cap \mathcal{A}_2}) = \mathcal{L}(\mathcal{A}_1) \cap \mathcal{L}(\mathcal{A}_2)$$

let $w = A_0 A_1 A_2 \dots$

- $w \in \mathcal{L}(\mathcal{A}_1) \cap \mathcal{L}(\mathcal{A}_2)$
- iff exists accepting run $q_{0,1} q_{1,1} q_{2,1} \dots$ of w in \mathcal{A}_1
and exists accepting run $q_{0,2} q_{1,2} q_{2,2} \dots$ of w in \mathcal{A}_2 :
 - $q_{j+1,i} \in \delta_i(q_{j,i}, A_j)$ for all $0 \leq j$ and $1 \leq i \leq 2$
 - for each $1 \leq j \leq k_i$, $1 \leq i \leq 2$ there are infinitely many $q_{m,i} \in F_{j,i}$
- iff exist accepting run $(q_{0,1}, q_{0,2}) (q_{1,1}, q_{1,2}) (q_{2,1}, q_{2,2}) \dots$ of $\mathcal{A}_{\mathcal{A}_1 \cap \mathcal{A}_2}$:
 - $(q_{j+1,1}, q_{j+1,2}) \in \delta((q_{j,1}, q_{j,2}), A_j)$ for all $0 \leq j$
 - for each F'_j there are infinitely many $(q_{m,1}, q) \in F_{j,1} \times Q_2$ and
for each F''_j there are infinitely many $(q, q_{m,2}) \in Q_1 \times F_{j,2}$
- iff $w \in \mathcal{L}(\mathcal{A}_{\mathcal{A}_1 \cap \mathcal{A}_2})$

Checking Emptiness of GNBA's

let G be a graph (V, E) with nodes V and edges E

- set $C \subseteq V$ is a **cycle** of G iff
for all $v_1, v_2 \in C$ there is a non-empty path from v_1 to v_2

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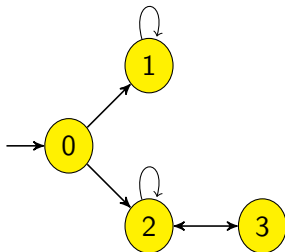
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(C is SCC iff both C is cycle and $C' \supset C$ implies C' is not a cycle)
- remarks:
 - two SCCs C_1 and C_2 are either disjoint or identical
 - the set of SCCs of a graph can be determined in linear time (Kosaraju)



Algorithm for Checking $\mathcal{L}(\mathcal{A}) = \emptyset$ for GNBA \mathcal{A}

$\mathcal{A} = (Q, \Sigma, \delta, q_0, F_1, \dots, F_k)$ accepts at least one ω -word

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and perform reachability-analysis from q_0 (linear time, depth first search)

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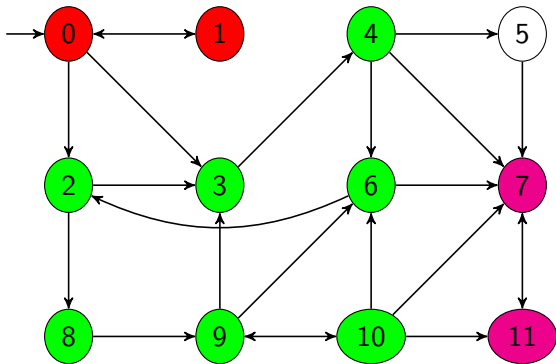
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- if no SCC with final states from each F_i reachable from q_0 : $\mathcal{L}(\mathcal{A}) = \emptyset$
- otherwise, obtain path from q_0 to $q_1 \in SCC$ and non-empty path from q_1 to q_1 traversing all nodes in the SCC with corresponding words w_{01} and w_{11}
 $\Rightarrow w_{01} w_{11}^\omega \in \mathcal{L}(\mathcal{A})$

Example (GNBA where input letters are omitted)



$$F_1 = \{0, 9\}$$

$$F_2 = \{0, 3, 10\}$$

$$F_3 = \{5, 10, 11\}$$

extracted accepted run: $0(2346289106)^\omega$

Summary

- model checking for linear time properties:
 - specify allowed traces $\mathcal{S}(R)$ or forbidden traces $\mathcal{S}(\neg R)$
 - decide

$$\text{Traces}(T) \subseteq \mathcal{S}(R) \quad \text{or} \quad \text{Traces}(TS) \cap \mathcal{S}(\neg R) = \emptyset$$

- NFA over finite words \rightarrow (G)NBA over infinite words
(regular languages \rightarrow regular ω -languages)
- GNBA can encode several requirements (allowed / forbidden traces)
- GNBA can encode transition systems
- GNBA are closed under Boolean operations (here: only intersection)
- emptiness of GNBA is decidable