

# Logic Programming

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# Summary of Last Lecture

## Definitions (CLP on finite domains)

- `use_module(library(clpfd))` loads the clpfd library
- `Xs ins N .. M` specifies that all values in `Xs` must be in the given range
- `all_different(Xs)` specifies that all values in `Xs` are different
- `label(Xs)` all variables in `Xs` are evaluated to become values
- `#=`, `#\=`, `#>`, ... like the arithmetic comparison operators, but may contain (constraint) variables

## standard approach

- load the library
- specify all constraints
- call `label` to start efficient computation of solutions

# GUPU

## Example (constraint logic programming)

- 59, 60 (solution space)
- 61 (termination)
- 66 (core relation)

# Outline of the Lecture

## Monotone Logic Programs

introduction, basic constructs, unification, database and recursive programming, termination

## Incomplete Data Structures and Constraints

incomplete data structures, definite clause grammars, constraint logic programming, answer set programming

## Full Prolog

semantics, correctness proofs, meta-logical predicates, cuts nondeterministic programming, efficient programs, complexity

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# Efficient Constraint Logic Programming

## Strategies for Solutions

- **take termination seriously**  
non-termination is a sign of inefficiency
- **choose suitable labeling strategies**
- **use system predicates**

```

:- Zs = [A,B,C], Zs ins 1..2,
   A #\= B, B #\= C, A #\= C.
:/- Zs = [A,B,C], Zs ins 1..2,
    all_different(Zs).
  
```

- **make use of redundant constraints**  
recall the magic square example, where the sums equal  $n \cdot (n^2 + 1)/2$ ; using this insight redundant constraints are prevented, and the search is quicker; however, in general a predefined search strategy doesn't need to be more efficient

# Labeling Strategies

## Strategies for Solutions (cont'd)

- **minimise the solution space**  
consider the exclusion of rotations and symmetries for magic square
- **improve representation of solutions**  
inefficient/redundant representations increase the solution space unnecessarily

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## Definition

**labeling (+Options,+Vars)** assign a value to each variable in *Vars*; three categories of options exist

- variable selection strategy
- value order strategy
- branching strategy



## Definition (variable selection strategy)

- **leftmost**, select the variables in the order they occur in *Vars* (default)
- **min**, select the leftmost variable with lowest lower bound next

```
:- X in 1..2, Y in 3..4, labeling([min],[X,Y]).
X = 1, Y = 3;
X = 1, Y = 4;
X = 2, Y = 3;
X = 2, Y = 4
```

- **max**, select the leftmost variable with highest upper bound next

```
:- X in 1..2, Y in 3..4, labeling([max],[X,Y]).
X = 2, Y = 3;
X = 1, Y = 4;
X = 2, Y = 4
```

- **ff**, first fail, select the leftmost variable with smallest domain next, in order to detect infeasibility early

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## Definition (branching strategy)

- **step**, for each variable  $X$ , the choice is between  $X = V$  and  $X \neq V$  ( $V$  determined by value order)
- **enum**, enumerate the domain of  $X$  according to the value order
- **bisect**, choice is between  $X \leq M$  and  $X > M$  ( $M$  the midpoint of the domain)

# The New Kid on the Block

## Answer Set Programming

- novel approach to modelling and solving search and optimisation problems
- $\neg$  programming, but a specification language
- $\neg$  Turing complete
- purely declarative
- restricted to finite models

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## Example (Negation as Failure)

```
light_on :- power_on, not broken.  
power_on.
```

answer set: {*power\_on*, *light\_on*}

## Example (Disjunctive Heads)

```
open | closed :- door.
```

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```
a | b.
```

```
a :- b.
```

answer set:  $\{a\}$ , but not  $\{b\}$  nor  $\{a, b\}$

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## Additional Features

- finite choice functions:  $\{fact_1, fact_2, fact_3\}$ .
- choice and counting:  $1\{fact_1, fact_2, fact_3\}2$ .  
“1” or “2” may be missing

# First-Order Setting

## Definition

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## Example (3-colouring)

```
red(X) | green(X) | blue(X).  
:- red(X), red(Y), edge(X,Y).  
:- green(X), green(Y), edge(X,Y).  
:- blue(X), blue(Y), edge(X,Y).
```

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:- green(X), green(Y), edge(X,Y).  
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```

## Example ((part of) 8-queens problem)

```
:- not (1 = count(Y : queen(X,Y))), row(X)
```

expresses that exactly one queen appears in every row and column

# Grounders and Solvers





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## Grounders

- DLV (DLV Systems, Calabria)
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- Iparse (University of Helsinki)

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## Solvers

- clasp (University of Potsdam)
- cmodels (University of Austin)
- smodels (University of Helsinki)

# Prolog and Answer Set Programming

- proof search
- Turing complete
- control
- efficiency

- model search
- finite domain
- specification language
- generality

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## Example

```
hanoi(0,_,_,_,_, []).  
hanoi(N,X,Y,Z, Ls) :-  
    N > 0, M is N - 1,  
    hanoi(M,X,Z,Y, Ls0),  
    append(Ls0, [move(N,X,Z)], Ls1),  
    hanoi(M,Y,X,Z, Ls2),  
    append(Ls1, Ls2, Ls).
```

## Example

```

disk(1..n).
transition(0..pathlength-1).
location(Peg) :- peg(Peg).
#domain disk(X;Y). #domain peg(P;P1;P2).
#domain transition(T). #domain situation(I).
#domain location(L;L1).

peg(a;b;c).
situation(0..pathlength).
location(Disk) :- disk(Disk).

on(X,L,T+1) :- on(X,L,T), not otherloc(X,L,T+1).
otherloc(X,L,I) :- on(X,L1,I), L1!=L.
:- on(X,L,I), on(X,L1,I), L!=L1.
inpeg(X,P,I) :- on(X,L,I), inpeg(L,P,I). inpeg(P,P,I).
top(P,L,I) :- inpeg(L,P,I), not covered(L,I).
covered(L,I) :- on(X,L,I).
:- on(X,Y,I), X>Y.
on(X,L,T+1) :- move(P1,P2,T), top(P1,X,T), top(P2,L,T).
:- move(P1,P2,T), top(P1,P1,T). movement(P1,P2) :- P1 != P2.
1 {move(A,B,T) : movement(A,B)} 1.
on(n,a,0). on(X,X+1,0) :- X<n.
onewrong :- not inpeg(X,c,pathlength).
:- onewrong.

```