

Logic Programming

Georg Moser

Department of Computer Science @ UIBK

Winter 2016



Summary of Last Lecture

Example

```
ancestor_of(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of(Ancestor, Descendant) :-  
    child_of(Person, Ancestor),  
    ancestor_of(Person, Descendant).
```

Example

```
ancestor_of_2(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of_2(Ancestor, Descendant) :-  
    ancestor_of_2(Person, Descendant),  
    child_of(Person, Ancestor).
```

Outline of the Lecture

Monotone Logic Programs

introduction, basic constructs, logic foundations, unification, semantics, database and recursive programming, termination, complexity

Incomplete Data Structures and Constraints

incomplete data structures, definite clause grammars, constraint logic programming, answer set programming

Full Prolog

semantics (revisited), correctness proofs, meta-logical predicates, cuts non-deterministic programming, efficient programs, complexity

Outline of the Lecture

Monotone Logic Programs

introduction, basic constructs, logic foundations, unification, semantics, database and recursive programming, termination, complexity

Incomplete Data Structures and Constraints

incomplete data structures, definite clause grammars, constraint logic programming, answer set programming

Full Prolog

semantics (revisited), correctness proofs, meta-logical predicates, cuts non-deterministic programming, efficient programs, complexity

Non-Monotonic Reasoning

Definition

an operator Ψ is called **monotone** if $A \subseteq B$ implies $\Psi(A) \subseteq \Psi(B)$

Non-Monotonic Reasoning

Definition

an operator Ψ is called **monotone** if $A \subseteq B$ implies $\Psi(A) \subseteq \Psi(B)$

Fact

suppose Ψ acts on sets of formulas and interprets the consequence relation of a logic program P without negation, then Ψ is monotone

Definition

a **monotone logic program** is a logic program without negation ($\backslash +$)

Monotonicity Criticism

Example (Minsky's Example)

```
on(a,b).  
on(d,a).  
on(d,c).  
clear(Y) :-  
    not_exists_x_on(Y).
```

```
not_exists_x_on(Y) :-  
    on(_X,Y), !, fail.  
not_exists_x_on(_Y).
```

Monotonicity Criticism

Example (Minsky's Example)

```
on(a,b).
on(d,a).
on(d,c).
clear(Y) :-
    not_exists_x_on(Y).
```

```
not_exists_x_on(Y) :-
    on(_X,Y), !, fail.
not_exists_x_on(_Y).
```

Observations

- in this block-world example $\text{:- clear}(d)$ holds
- but monotonicity doesn't; addition of the fact $\text{on}(e,d)$ renders $\text{:- clear}(d)$ false

Theory of Monotone Logic Programs

Definitions

- goal clause

$\text{:- } B_1, \dots, B_n$

consists of sequence B_1, \dots, B_n of goals

Theory of Monotone Logic Programs

Definitions

- goal clause

$:- B_1, \dots, B_n$

consists of sequence B_1, \dots, B_n of goals

- **empty** goal clause $:-$ is denoted by \square

Theory of Monotone Logic Programs

Definitions

- goal clause

$$:- B_1, \dots, B_n$$

consists of sequence B_1, \dots, B_n of goals

- empty goal clause $:-$ is denoted by \square
- resolvent** of goal clause $:- B_1, \dots, B_i, \dots, B_m$ and rule $A :- A_1, \dots, A_n$

is goal clause

$$:- B_1\sigma, \dots, B_{i-1}\sigma, A_1\sigma, \dots, A_n\sigma, B_{i+1}\sigma, \dots, B_m\sigma$$

provided B_i (selected goal) and A unify with most general unifier σ

Theory of Monotone Logic Programs

Definitions

- goal clause

$$:- B_1, \dots, B_n$$

consists of sequence B_1, \dots, B_n of goals

- empty goal clause $:-$ is denoted by \square
- resolvent of goal clause $:- B_1, \dots, B_i, \dots, B_m$ and rule $A :- A_1, \dots, A_n$ is goal clause

$$:- B_1\sigma, \dots, B_{i-1}\sigma, A_1\sigma, \dots, A_n\sigma, B_{i+1}\sigma \dots, B_m\sigma$$

provided B_i (**selected goal**) and A unify with most general unifier σ

Theory of Monotone Logic Programs

Definitions

- goal clause

$$:- B_1, \dots, B_n$$

consists of sequence B_1, \dots, B_n of goals

- empty goal clause $:-$ is denoted by \square
- resolvent of goal clause $:- B_1, \dots, B_i, \dots, B_m$ and rule $A :- A_1, \dots, A_n$ is goal clause

$$:- B_1\sigma, \dots, B_{i-1}\sigma, A_1\sigma, \dots, A_n\sigma, B_{i+1}\sigma \dots, B_m\sigma$$

provided B_i (selected goal) and A unify with **most general unifier** σ

NB: see week 2 for the most general unifier

Selective Linear Definite Clause Resolution

Definitions

- SLD-derivation of logic program P and goal clause G consists of

Selective Linear Definite Clause Resolution

Definitions

- **SLD-derivation** of logic program P and goal clause G consists of
 - 1 maximal sequence G_0, G_1, G_2, \dots of goal clauses

Selective Linear Definite Clause Resolution

Definitions

- **SLD-derivation** of logic program P and goal clause G consists of
 - 1 maximal sequence G_0, G_1, G_2, \dots of goal clauses
 - 2 sequence C_0, C_1, C_2, \dots of variants of rules in P

Selective Linear Definite Clause Resolution

Definitions

- **SLD-derivation** of logic program P and goal clause G consists of
 - 1 maximal sequence G_0, G_1, G_2, \dots of goal clauses
 - 2 sequence C_0, C_1, C_2, \dots of variants of rules in P
 - 3 sequence $\sigma_0, \sigma_1, \sigma_2, \dots$ of substitutions

Selective Linear Definite Clause Resolution

Definitions

- **SLD-derivation** of logic program P and goal clause G consists of
 - 1 maximal sequence G_0, G_1, G_2, \dots of goal clauses
 - 2 sequence C_0, C_1, C_2, \dots of variants of rules in P
 - 3 sequence $\sigma_0, \sigma_1, \sigma_2, \dots$ of substitutionssuch that
 - $G_0 = G$

Selective Linear Definite Clause Resolution

Definitions

- **SLD-derivation** of logic program P and goal clause G consists of
 - 1 maximal sequence G_0, G_1, G_2, \dots of goal clauses
 - 2 sequence C_0, C_1, C_2, \dots of variants of rules in P
 - 3 sequence $\sigma_0, \sigma_1, \sigma_2, \dots$ of substitutions

such that

- $G_0 = G$
- G_{i+1} is resolvent of G_i and C_i with mgu σ_i

Selective Linear Definite Clause Resolution

Definitions

- **SLD-derivation** of logic program P and goal clause G consists of
 - 1 maximal sequence G_0, G_1, G_2, \dots of goal clauses
 - 2 sequence C_0, C_1, C_2, \dots of **variants** of rules in P
 - 3 sequence $\sigma_0, \sigma_1, \sigma_2, \dots$ of substitutions

such that

- $G_0 = G$
- G_{i+1} is resolvent of G_i and C_i with mgu σ_i
- C_i has no variables in common with G, C_0, \dots, C_{i-1}

Selective Linear Definite Clause Resolution

Definitions

- SLD-derivation of logic program P and goal clause G consists of
 - 1 maximal sequence G_0, G_1, G_2, \dots of goal clauses
 - 2 sequence C_0, C_1, C_2, \dots of variants of rules in P
 - 3 sequence $\sigma_0, \sigma_1, \sigma_2, \dots$ of substitutionssuch that
 - $G_0 = G$
 - G_{i+1} is resolvent of G_i and C_i with mgu σ_i
 - C_i has no variables in common with G, C_0, \dots, C_{i-1}
- **SLD refutation** is finite SLD derivation ending in \square

Selective Linear Definite Clause Resolution

Definitions

- SLD-derivation of logic program P and goal clause G consists of
 - 1 maximal sequence G_0, G_1, G_2, \dots of goal clauses
 - 2 sequence C_0, C_1, C_2, \dots of variants of rules in P
 - 3 sequence $\sigma_0, \sigma_1, \sigma_2, \dots$ of substitutions

such that

- $G_0 = G$
- G_{i+1} is resolvent of G_i and C_i with mgu σ_i
- C_i has no variables in common with G, C_0, \dots, C_{i-1}
- SLD refutation is finite SLD derivation ending in \square
- **computed answer substitution** of SLD refutation of P and G with substitutions $\sigma_0, \sigma_1, \dots, \sigma_m$ is restriction of $\sigma_0\sigma_1 \cdots \sigma_m$ to variables in G

Example

```
plus(0,X,X).  
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).  
times(0,X,0).  
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).  
:- times(X,X,Y)
```

Example

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
:- times(X,X,Y)

```

SLD-refutation

```

G0: :- times(X,X,Y)
C0: times(s(X0),Y0,Z0) :- times(X0,Y0,U0), plus(U0,Y0,Z0)

```


Example

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
:- times(X,X,Y)

```

SLD-refutation

```

G0: :- times(X,X,Y)
C0: times(s(X0),Y0,Z0) :- times(X0,Y0,U0), plus(U0,Y0,Z0)
σ0:

```

Example

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
                  :- times(X,X,Y)

```

SLD-refutation

```

G0: :- times(X,X,Y)
C0: times(s(X0),Y0,Z0) :- times(X0,Y0,U0), plus(U0,Y0,Z0)
σ0: X ↦ s(X0), Y0 ↦ s(X0), Z0 ↦ Y

```

Example

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
:- times(X,X,Y)

```

SLD-refutation

```

G0: :- times(X,X,Y)
    C0: times(s(X0),Y0,Z0) :- times(X0,Y0,U0), plus(U0,Y0,Z0)
    σ0: X ↦ s(X0), Y0 ↦ s(X0), Z0 ↦ Y
G1: :- times(X0,s(X0),U0), plus(U0,s(X0),Y)

```

Example

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
:- times(X,X,Y)

```

SLD-refutation

```

G0: :- times(X,X,Y)
C0: times(s(X0),Y0,Z0) :- times(X0,Y0,U0), plus(U0,Y0,Z0)
σ0: X ↦ s(X0), Y0 ↦ s(X0), Z0 ↦ Y
G1: :- times(X0,s(X0),U0), plus(U0,s(X0),Y)
C1: times(0,X1,0).

```

Example

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
:- times(X,X,Y)

```

SLD-refutation

```

G0: :- times(X,X,Y)
    C0: times(s(X0),Y0,Z0) :- times(X0,Y0,U0), plus(U0,Y0,Z0)
    σ0: X ↦ s(X0), Y0 ↦ s(X0), Z0 ↦ Y
G1: :- times(X0,s(X0),U0), plus(U0,s(X0),Y)
    C1: times(0,X1,0).
    σ1: X0 ↦ 0, X1 ↦ s(0), U0 ↦ 0

```

Example

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
:- times(X,X,Y)

```

SLD-refutation

```

G0: :- times(X,X,Y)
    C0: times(s(X0),Y0,Z0) :- times(X0,Y0,U0), plus(U0,Y0,Z0)
    σ0: X ↦ s(X0), Y0 ↦ s(X0), Z0 ↦ Y

G1: :- times(X0,s(X0),U0), plus(U0,s(X0),Y)
    C1: times(0,X1,0).
    σ1: X0 ↦ 0, X1 ↦ s(0), U0 ↦ 0

G2: :- plus(0,s(0),Y)
    C2: plus(0,X2,X2).
    σ2: X2 ↦ s(0), Y ↦ s(0)

```

Example

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
:- times(X,X,Y)

```

SLD-refutation

```

G0: :- times(X,X,Y)
    C0: times(s(X0),Y0,Z0) :- times(X0,Y0,U0), plus(U0,Y0,Z0)
    σ0: X ↦ s(X0), Y0 ↦ s(X0), Z0 ↦ Y
G1: :- times(X0,s(X0),U0), plus(U0,s(X0),Y)
    C1: times(0,X1,0).
    σ1: X0 ↦ 0, X1 ↦ s(0), U0 ↦ 0
G2: :- plus(0,s(0),Y)
    C2: plus(0,X2,X2).
    σ2: X2 ↦ s(0), Y ↦ s(0)
G3: □

```

Example

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
:- times(X,X,Y)

```

SLD-refutation

```

G0: :- times(X,X,Y)
    C0: times(s(X0),Y0,Z0) :- times(X0,Y0,U0), plus(U0,Y0,Z0)
    σ0: X ↦ s(X0), Y0 ↦ s(X0), Z0 ↦ Y
G1: :- times(X0,s(X0),U0), plus(U0,s(X0),Y)
    C1: times(0,X1,0).
    σ1: X0 ↦ 0, X1 ↦ s(0), U0 ↦ 0
G2: :- plus(0,s(0),Y)
    C2: plus(0,X2,X2).
    σ2: X2 ↦ s(0), Y ↦ s(0)
G3: □          computed answer substitution: X ↦ s(0), Y ↦ s(0)

```


Definition

- a **selection function** selects the next goal G in goal clause, where resolution is attempted
- Prolog's selection function proceeds left to right

Definition

- a **selection function** selects the next goal G in goal clause, where resolution is attempted
- Prolog's selection function proceeds left to right

Theorem

- \forall logic programs P and goal clause G
- \forall computed answer substitutions σ
- \forall selection functions S
- \exists computed answer substitution σ' using S

Definition

- a **selection function** selects the next goal G in goal clause, where resolution is attempted
- Prolog's selection function proceeds left to right

Theorem

\forall logic programs P and goal clause G

\forall computed answer substitutions σ

\forall selection functions S

\exists computed answer substitution σ' using S

such that σ' is at least as general as σ (with respect to variables in G)

Search or SLD Trees

Definition

a **search tree** (aka **SLD** tree) of a goal G is a tree T such that

- the root of T is labelled with G
- the nodes of T are labelled with conjunctions of goals, where one goal is selected (wrt a selection function)

Search or SLD Trees

Definition

a **search tree** (aka **SLD tree**) of a goal G is a tree T such that

- the root of T is labelled with G
- the nodes of T are labelled with conjunctions of goals, where one goal is selected (wrt a selection function)
- for each clause, whose head unifies with the selected goal \exists edge from node N
- edges are labelled with (partial) answer substitutions

Search or SLD Trees

Definition

a **search tree** (aka **SLD tree**) of a goal G is a tree T such that

- the root of T is labelled with G
- the nodes of T are labelled with conjunctions of goals, where one goal is selected (wrt a selection function)
- for each clause, whose head unifies with the selected goal \exists edge from node N
- edges are labelled with (partial) answer substitutions
- leaves are **success nodes**, if the empty goal (denoted by \square) has been reached or **failure nodes** otherwise

Search or SLD Trees

Definition

a **search tree** (aka **SLD tree**) of a goal G is a tree T such that

- the root of T is labelled with G
- the nodes of T are labelled with conjunctions of goals, where one goal is selected (wrt a selection function)
- for each clause, whose head unifies with the selected goal \exists edge from node N
- edges are labelled with (partial) answer substitutions
- leaves are **success nodes**, if the empty goal (denoted by \square) has been reached or **failure nodes** otherwise

Remark

a search tree captures all possible SLD derivations wrt a given goal and selection function

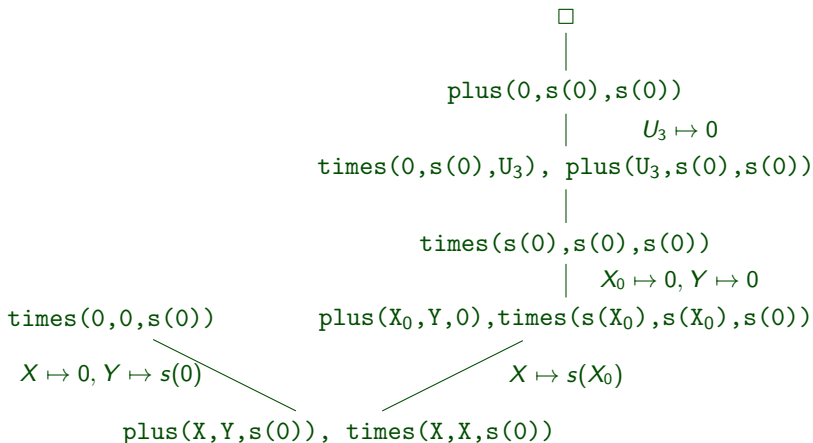
Example (cont'd)

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).

times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U),
                    plus(U,Y,Z).

```

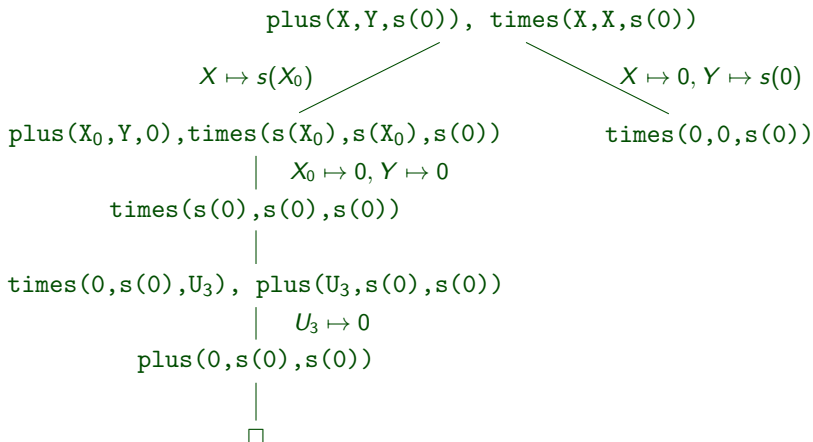


Example (cont'd)

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U),
                    plus(U,Y,Z).

```



Example (revisited)

```
ancestor_of(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of(Ancestor, Descendant) :-  
    child_of(Person, Ancestor),  
    ancestor_of(Person, Descendant).
```

Example (revisited)

```
ancestor_of(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of(Ancestor, Descendant) :-  
    child_of(Person, Ancestor),  
    ancestor_of(Person, Descendant).
```

- Ancestor

Example (revisited)

```
ancestor_of(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of(Ancestor, Descendant) :-  
    child_of(Person, Ancestor),  
    ancestor_of(Person, Descendant).
```

- Ancestor
- Descendant

Example (revisited)

```
ancestor_of(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of(Ancestor, Descendant) :-  
    child_of(Person, Ancestor),  
    ancestor_of(Person, Descendant).
```

- Ancestor
- Descendant
- Person

Example (revisited)

```
ancestor_of(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of(Ancestor, Descendant) :-  
    child_of(Person, Ancestor),  
    ancestor_of(Person, Descendant).
```

- Ancestor
- Descendant
- Person

In English

Someone is ancestor of a descendant, if the descendant is his (or her) child, or if he (or she) has a child and this person is the ancestor of the descendant.

binding of logical variables is expressed as references

Example (revisited)

```
ancestor_of(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of(Ancestor, Descendant) :-  
    child_of(Person, Ancestor),  
    ancestor_of(Person, Descendant).
```

- Ancestor
- Descendant
- Person

In English

Someone is ancestor of a descendant, if the descendant is his (or her) child, or if he (or she) has a child and this person is the ancestor of the descendant.

binding of logical variables is expressed as references

Example (revisited)

```
ancestor_of(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of(Ancestor, Descendant) :-  
    child_of(Person, Ancestor),  
    ancestor_of(Person, Descendant).
```

- Ancestor
- Descendant
- Person

In English

*Someone is ancestor of a **descendant**, if the **descendant** is his (or her) child, or if he (or she) has a child and this person is the ancestor of the **descendant**.*

binding of logical variables is expressed as references

Example (revisited)

```
ancestor_of(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of(Ancestor, Descendant) :-  
    child_of(Person, Ancestor),  
    ancestor_of(Person, Descendant).
```

- Ancestor
- Descendant
- Person

In English

*Someone is ancestor of a descendant, if the descendant is his (or her) child, or if he (or she) has a child and this **person** is the **ancestor** of the descendant.*

binding of logical variables is expressed as references

Example (revisited)

```
ancestor_of(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of(Ancestor, Descendant) :-  
    child_of(Person, Ancestor),  
    ancestor_of(Person, Descendant).
```

- Ancestor
- Descendant
- Person

In English

Someone is ancestor of a descendant, if the descendant is his (or her) child, or if he (or she) has a child and this person is the ancestor of the descendant.

binding of logical variables is expressed as references

Declarative Reading

Definition

the declarative reading of a program is its concept as (set of) logical formulas

Declarative Reading

Definition

the declarative reading of a program is its concept as (set of) logical formulas

Analysis

1 specialisation

- if we remove clauses of a defined relation, then this relation becomes smaller; the program is **specialised**
- if the specialisation provides wrong answers, the original program certainly will

Declarative Reading

Definition

the declarative reading of a program is its concept as (set of) logical formulas

Analysis

1 specialisation

- if we remove clauses of a defined relation, then this relation becomes smaller; the program is **specialised**
- if the specialisation provides wrong answers, the original program certainly will

2 generalisation

- if we remove goals from the body of a clause, the relation is extended; the program is **generalised**
- if the generalised program cannot derive correct facts, the original can neither

Procedure Reading

Example (multiplication)

logic program

```
plus(0,X,X).  
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).  
times(0,X,0).  
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

ground queries

```
:- plus(s(s(0)),s(0),s(s(s(0))))
```

Procedure Reading

Example (multiplication)

logic program

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).

```

ground queries

```

:- plus(s(s(0)),s(0),s(s(s(0))))   X ↦ s(0), Y ↦ s(0), Z ↦ s(s(0))

```

Procedure Reading

Example (multiplication)

logic program

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).

```

ground queries

```

:- plus(s(s(0)),s(0),s(s(s(0))))   X ↦ s(0), Y ↦ s(0), Z ↦ s(s(0))
:- plus(s(0),s(0),s(s(0)))

```


Procedure Reading

Example (multiplication)

logic program

```
plus(0,X,X).  
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).  
times(0,X,0).  
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

ground queries

```
:- plus(s(s(0)),s(0),s(s(s(0))))  
:- plus(s(0),s(0),s(s(0)))       $X \mapsto 0, Y \mapsto s(0), Z \mapsto s(0)$ 
```

Procedure Reading

Example (multiplication)

logic program

```
plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

ground queries

```
:- plus(s(s(0)),s(0),s(s(s(0))))
:- plus(s(0),s(0),s(s(0)))      X ↦ 0, Y ↦ s(0), Z ↦ s(0)
:- plus(0,s(0),s(0))
```

Procedure Reading

Example (multiplication)

logic program

```

plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).

```

ground queries

```

:- plus(s(s(0)),s(0),s(s(s(0))))
:- plus(s(0),s(0),s(s(0)))
:- plus(0,s(0),s(0))

```

$X \mapsto s(0)$

Procedure Reading

Example (multiplication)

logic program

```
plus(0,X,X).  
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).  
times(0,X,0).  
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

ground queries

```
:- plus(s(s(0)),s(0),s(s(s(0))))  
:- plus(s(0),s(0),s(s(0)))  
:- plus(0,s(0),s(0))
```

solved

...is Too Complicated

Example (renaming is needed)

logic program

```
plus(0,X,X).  
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).  
times(0,X,0).  
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

query

```
:- plus(s(s(0)),s(0),X)
```

...is Too Complicated

Example (renaming is needed)

logic program

```
plus(0,X,X).
```

```
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
```

```
times(0,X,0).
```

```
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

query

```
:- plus(s(s(0)),s(0),X)
```

...is Too Complicated

Example (renaming is needed)

logic program

```
plus(0,X,X).
```

```
plus(s(X1),Y1,s(Z1)) :- plus(X1,Y1,Z1).
```

```
times(0,X,0).
```

```
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

query

```
:- plus(s(s(0)),s(0),X)      X1 ↦ s(0), Y1 ↦ s(0), X ↦ s(Z1)
```

...is Too Complicated

Example (renaming is needed)

logic program

```
plus(0,X,X).
plus(s(X1),Y1,s(Z1)) :- plus(X1,Y1,Z1).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

query

```
:- plus(s(s(0)),s(0),X)           X ↦ s(Z1)
:- plus(s(0),s(0),Z1)
```


...is Too Complicated

Example (renaming is needed)

logic program

```
plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

query

```
:- plus(s(s(0)),s(0),X)           X ↦ s(Z1)
:- plus(s(0),s(0),Z1)
```

...is Too Complicated

Example (renaming is needed)

logic program

```
plus(0,X,X).
plus(s(X2),Y2,s(Z2)) :- plus(X2,Y2,Z2).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

query

```
:- plus(s(s(0)),s(0),X)                                X ↦ s(Z1)
:- plus(s(0),s(0),Z1)    X2 ↦ 0, Y2 ↦ s(0), Z1 ↦ s(Z2)
```

...is Too Complicated

Example (renaming is needed)

logic program

```
plus(0,X,X).
plus(s(X2),Y2,s(Z2)) :- plus(X2,Y2,Z2).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

query

<code>:- plus(s(s(0)),s(0),X)</code>	$X \mapsto s(Z_1)$
<code>:- plus(s(0),s(0),Z₁)</code>	$Z_1 \mapsto s(Z_2)$
<code>:- plus(0,s(0),Z₂)</code>	

...is Too Complicated

Example (renaming is needed)

logic program

```
plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

query

<code>:- plus(s(s(0)),s(0),X)</code>	$X \mapsto s(Z_1)$
<code>:- plus(s(0),s(0),Z₁)</code>	$Z_1 \mapsto s(Z_2)$
<code>:- plus(0,s(0),Z₂)</code>	

...is Too Complicated

Example (renaming is needed)

logic program

```
plus(0,X3,X3).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

query

<code>:- plus(s(s(0)),s(0),X)</code>	$X \mapsto s(Z_1)$
<code>:- plus(s(0),s(0),Z₁)</code>	$Z_1 \mapsto s(Z_2)$
<code>:- plus(0,s(0),Z₂)</code>	$X_3 \mapsto s(0), Z_2 \mapsto s(0)$

...is Too Complicated

Example (renaming is needed)

logic program

```
plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

query

<code>:- plus(s(s(0)),s(0),X)</code>	$X \mapsto s(Z_1)$
<code>:- plus(s(0),s(0),Z_1)</code>	$Z_1 \mapsto s(Z_2)$
<code>:- plus(0,s(0),Z_2)</code>	$Z_2 \mapsto s(0)$

solution

...is Too Complicated

Example (renaming is needed)

logic program

```
plus(0,X,X).
plus(s(X),Y,s(Z)) :- plus(X,Y,Z).
times(0,X,0).
times(s(X),Y,Z) :- times(X,Y,U), plus(U,Y,Z).
```

query

```
:- plus(s(s(0)),s(0),X)           X ↦ s(Z1)
:- plus(s(0),s(0),Z1)           Z1 ↦ s(Z2)
:- plus(0,s(0),Z2)             Z2 ↦ s(0)
```

solution $X \mapsto s(s(s(0)))$

Definition

- a **type** is a (possible infinite) set of terms
- types are conveniently defined by unary relations

Definition

- a **type** is a (possible infinite) set of terms
- types are conveniently defined by unary relations

Example

```
male(X).    female(X).
```

Definition

- a **type** is a (possible infinite) set of terms
- types are conveniently defined by unary relations

Example

```
male(X).    female(X).
```

Definition

- to define complex types, **recursive** logic programs may be necessary
- the latter types are called **recursive types**
- recursive types, defined by unary recursive programs, are called **simple recursive types**
- a program defining a type is a **type definition**; a call to a predicate defining a type is a **type condition**

Simple Recursive Types

Example

```
is_tree(nil).  
is_tree(tree(Element,Left,Right)) :-  
    is_tree(Left),  
    is_tree(Right).
```

Simple Recursive Types

Example

```
is_tree(nil).  
is_tree(tree(Element,Left,Right)) :-  
    is_tree(Left),  
    is_tree(Right).
```

Definition

- a type is **complete** if closed under the instance relation
- with every complete type T one associates an **incomplete** type $!T$ which is a set of terms with instances in T and instances not in T

Simple Recursive Types

Example

```
is_tree(nil).  
is_tree(tree(Element,Left,Right)) :-  
    is_tree(Left),  
    is_tree(Right).
```

Definition

- a type is **complete** if closed under the instance relation
- with every complete type T one associates an **incomplete** type $!T$ which is a set of terms with instances in T and instances not in T

Example

- the type $\{0, s(0), s(s(0)), \dots\}$ is complete
- the type $\{X, 0, s(0), s(s(0)), \dots\}$ is incomplete

Lists

Notation

- `[]` empty list

Lists

Notation

- `[]` empty list
- `[H | T]` list with head *H* and tail *T*

Lists

Notation

- $[]$ empty list
- $[H | T]$ list with head H and tail T
- $[A]$ $[A | []]$ list with one element

Lists

Notation

- $[]$ empty list
- $[H | T]$ list with head H and tail T
- $[A]$ $[A | []]$ list with one element
- $[A, B]$ $[A | [B | []]]$ list with two elements

Lists

Notation

- $[]$ empty list
- $[H | T]$ list with head H and tail T
- $[A]$ $[A | []]$ list with one element
- $[A, B]$ $[A | [B | []]]$ list with two elements
- $[A, B | T]$ $[A | [B | T]]$ list with at least two elements

Lists

Notation

- $[]$ empty list
- $[H | T]$ list with head H and tail T
- $[A]$ $[A | []]$ list with one element
- $[A, B]$ $[A | [B | []]]$ list with two elements
- $[A, B | T]$ $[A | [B | T]]$ list with at least two elements

Example

```
is_list([]).  is_list([X|Xs]) :- is_list(Xs).
```

Lists

Notation

- `[]` empty list
- `[H | T]` list with head H and tail T
- `[A]` `[A | []]` list with one element
- `[A, B]` `[A | [B | []]]` list with two elements
- `[A, B | T]` `[A | [B | T]]` list with at least two elements

Example

```
is_list([]).  is_list([X|Xs]) :- is_list(Xs).
```

Notation

formal object	cons pair syntax	element syntax
<code>.(a, [])</code>	<code>[a []]</code>	<code>[a]</code>
<code>.(a, .(b, []))</code>	<code>[a [b []]]</code>	<code>[a, b]</code>