

# Logic Programming

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# Summary of Last Lecture

## Definitions

- a **proof tree** for a program  $P$  and a goal  $G$  is a tree, whose nodes are goals and whose edges represent reduction of goals
- the root is the query  $G$
- the edges are labelled with (partial) answer substitutions
- a proof tree for a conjunction of goals  $G_1, \dots, G_n$  is the set of proof trees for  $G_i$

## Example (generate and test)

```
permutation_sort(Xs,Ys) :- permutation(Xs,Ys), ordered(Ys).  
permutation(Xs,[Z|Zs]) :- select(Z,Xs,Ys), permutation(Ys,Zs).  
permutation([],[]).  
ordered([X]).  
ordered([X,Y|Ys]) :- X <= Y, ordered([Y|Ys]).
```

# Outline of the Lecture

## Monotone Logic Programs

introduction, basic constructs, logic foundations, unification, semantics, database and recursive programming, termination, complexity

## Incomplete Data Structures and Constraints

incomplete data structures, definite clause grammars, constraint logic programming, answer set programming

## Full Prolog

semantics (revisited), correctness proofs, meta-logical predicates, cuts non-deterministic programming, efficient programs, complexity

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# Accessing compound terms

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## Example

```
: - functor(father(haran,lot),F,A)
```

```
F ↦ father
```

```
A ↦ 2
```

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: - functor(father(haran,lot),F,A)
```

```
F ↦ father
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```
A ↦ 2
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## Example

```
: - arg(2,father(haran,lot),X)
```

```
X ↦ lot
```



## Example

```
subterm(Term,Term) .  
subterm(Sub,Term) : -  
    compound(Term),  
    functor(Term,F,N),  
    subterm(N,Sub,Term) .  
  
subterm(N,Sub,Term) : -  
    N > 1,  
    N1 is N - 1,  
    subterm(N1,Sub,Term) .  
subterm(N,Sub,Term) : -  
    arg(N,Term,Arg),  
    subterm(Sub,Arg) .  
  
:- subterm(X,f(a,f(a,b))), X = a
```

## Example

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subterm(Term,Term).  
subterm(Sub,Term) :-  
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    N > 1,  
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subterm(N,Sub,Term) :-  
    arg(N,Term,Arg),  
    subterm(Sub,Arg).  
  
:- subterm(X,f(a,f(a,b))), X = a  
:- subterm(X,f(U,f(V,W))), X = f(V,W).
```

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X ↦ [father,haran,lot]
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## Remark

- programs written with functor and arg can also be written with univ
- programs using univ are typically simpler
- programs using functor and arg are more efficient
- univ can be built from functor and arg

## Approach

- 1 sometimes it is useful (easier) to think of a relation as a function
- 2 use this definition for coding
- 3 afterwards see, if alternative uses make declarative sense

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delete([X|Xs],Z,?)      :- X = Z                .
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```



## Example

```
delete2([X|Xs],X,Ys) :- delete2(Xs,X,Ys).  
delete2([X|Xs],Z,[X|Ys]) :- delete2(Xs,Z,Ys).  
delete2([],X,[]).
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## Example

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delete2([X|Xs],Z,[X|Ys]) :- delete2(Xs,Z,Ys).  
delete2([],X,[]).  
  
:- delete2([a,b,c,b],b,[a,c])  
true  
  
:- delete2([a,b,c,b],b,[a,b,c,b])  
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```

## Example

```

delete2([X|Xs],X,Ys) : - delete2(Xs,X,Ys).
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delete2([],X,[]).

: - delete2([a,b,c,b],b,[a,c])
true

: - delete2([a,b,c,b],b,[a,b,c,b])
true

```

## Example (Select $\approx$ Delete<sub>2</sub>)

```

select(X,[X|Xs],Xs).
select(X,[Y|Ys],[Y|Zs]) : - select(X,Ys,Zs)

: - delete2([a],b,[a])
true

: - select(b,[a],X)
false

```

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### Example (again, but different)

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```

### Example (non termination, yet again)

```
% hinfinte ← not strongly terminating, weakly terminating  
  
hinfinte.  
hinfinte :- hinfinte.  
  
:- hinfinte.
```

# Termination Analysis

## Fact

- *for termination analysis only recursive calls (cycles in call tree) are essential*
- *let's remove non-recursive rules*

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    child_of(Descendant, Ancestor),  
ancestor_of_2(Ancestor, Descendant) :-  
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```

equivalently

```
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```

## Example

```
ancestor_of_2(Ancestor , Descendant) :-  
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- **Ancestor** doesn't occur in first goal (= recursive call)
- no influence on termination behaviour

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- last goal has no effect → let's remove (generalisation)

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- no influence on termination behaviour
- **Descendant** remains unchanged
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## Example (specialised and generalised)

```
% ancestor_of_2 <- uniform nontermination
```

```
ancestor_of_2(Ancestor, Descendant) :-
    ancestor_of_2(Person, Descendant), false,
    child_of(Person, Ancestor).
```

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***:- Goal, false.***

*cannot terminate*

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ancestor_of(Ancestor, Descendant) :-
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    ancestor_of(Person, Descendant).
```

```
:- \+ child_of(X,X).
:- ancestor_of(Ancestor, Descendant), false. % terminates
:- false, ancestor_of(Ancestor, Descendant). % remark order
```

# Termination Domains

## Example (recall)

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```

## Observation

due to selection strategy Prolog may fail to find a solution to a goal, even though the goal has a finite computation

## Example

```
married(X,Y) :- married(Y,X).
```

```
parent_of(X,Y) :- child_of(Y,X).
```

```
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## Example

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## Definitions

- a **domain** is a set of goals closed under the instance relation
- a **termination domain** of a program  $P$  is a domain  $D$  such that  $P$  terminates on all goals in  $D$

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## Example (domain)

```
is_list([]).           is_list([X|Xs]) :- is_list(Xs).  
:- is_list([a,X,b]).
```

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are_married(X,Y) :- married(X,Y).  
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consider *append*/3, where the fact comes after the rule

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## Example

consider *append*/3, where the fact comes after the rule

- 1 *append* terminates if the first argument is a complete list
- 2 *append* terminates if the third argument is complete
- 3 *append* terminates iff the first or third argument is complete

## Complexity of Programs

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- in general resource analysis is even more difficult than termination analysis; in particular this holds for automation

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| • size of proof tree                           | time       |
| • logical inferences per second (LIPS)         | time       |
| • size of terms                                | space      |
| • full cost of SLD resolution                  | space/time |

## Example (ancestor\_of, specialised)

```
ancestor_of(Ancestor, Descendant) :-  
    child_of(Descendant, Ancestor).  
ancestor_of(Ancestor, Descendant) :-  
    child_of(Person, Ancestor),  
    ancestor_of(Person, Descendant).  
  
:- ancestor_of(joseph_II, Descendant).  
:- ancestor_of(Ancestor, joseph_II).
```

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:- ancestor_of(joseph_II, Descendant).
:- ancestor_of(Ancestor, joseph_II).

```

## Example (cont'd)

we can ignore Descendant as it has no effect on the number of steps:

```

ancestor_of_(Ancestor) :-
    child_of(Person, Ancestor),
    ancestor_of_(Person).

```

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- consider goal `ancestor_of(Ancestor, joseph_II)`; here the 2nd argument is irrelevant for the complexity of the program
- `child_of/2` is called with free variables, hence the solution space is given by the whole database
- hence, all ancestors of all persons are computed

## Example (reversed search)

```

ancestor_of_3(Ancestor, Descendant) :-
    child_of(Descendant, Ancestor).
ancestor_of_3(Ancestor, Descendant) :-
    child_of(Descendant, Person),
    ancestor_of_3(Ancestor, Person).

:- ancestor_of(Ancestor, joseph_II).

```