

A Formally Verified Solver for Homogeneous Linear Diophantine Equations*

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Quiz – How many unifiers?

$$f(x, y) \approx f(z, z)$$

#unifiers: ?

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$$f(x, y) \approx f(z, z)$$

#unifiers: 1

$$\{x \mapsto z, y \mapsto z\}$$

Quiz – How many AC unifiers?

$$x \cdot y \approx z \cdot z$$

#unifiers: ?

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$$x \cdot y \approx z \cdot z$$

#unifiers: 5

minimal complete set of AC unifiers:

$$\{x \mapsto z_3, \quad y \mapsto z_3, \quad z \mapsto z_3\}$$

$$\{x \mapsto z_1 \cdot z_1, \quad y \mapsto z_2 \cdot z_2, \quad z \mapsto z_1 \cdot z_2\}$$

$$\{x \mapsto z_1 \cdot z_1 \cdot z_3, \quad y \mapsto z_3, \quad z \mapsto z_1 \cdot z_3\}$$

$$\{x \mapsto z_3, \quad y \mapsto z_2 \cdot z_2 \cdot z_3, \quad z \mapsto z_2 \cdot z_3\}$$

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Quiz – How many AC unifiers?

$$x \cdot y \approx z \cdot z \cdot z$$

#unifiers: ?

Quiz – How many AC unifiers?

$$x \cdot y \approx z \cdot z \cdot z$$

#unifiers: 13

Quiz – How many AC unifiers?

$$v \cdot x \cdot y \approx z \cdot z \cdot z$$

#unifiers: ?

Quiz – How many AC unifiers?

$$v \cdot x \cdot y \approx z \cdot z \cdot z$$

#unifiers: 981

Bibliography



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Homogeneous Linear Diophantine Equations (HLDEs)

$$a_1 x_1 + a_2 x_2 + \cdots + a_m x_m = b_1 y_1 + b_2 y_2 + \cdots + b_n y_n$$

Homogeneous Linear Diophantine Equations (HLDEs)

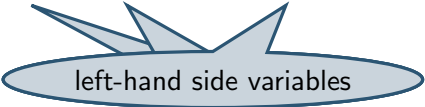
$$a_1x_1 + a_2x_2 + \cdots + a_mx_m = b_1y_1 + b_2y_2 + \cdots + b_ny_n$$



left-hand side coefficients

Homogeneous Linear Diophantine Equations (HLDEs)

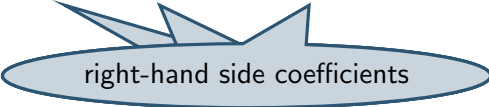
$$a_1 x_1 + a_2 x_2 + \cdots + a_m x_m = b_1 y_1 + b_2 y_2 + \cdots + b_n y_n$$



left-hand side variables

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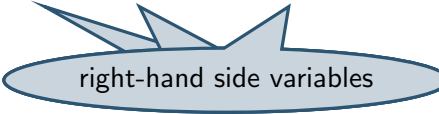
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right-hand side coefficients

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right-hand side variables

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Example

$$x_1 + x_2 = 2y_1$$

Homogeneous Linear Diophantine Equations (HLDEs)

$$a \bullet x = b \bullet y$$

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$$x_1 + x_2 = 2y_1$$

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Example

$$[1, 1] \bullet [x_1, x_2] = [2] \bullet [y_1]$$

Homogeneous Linear Diophantine Equations (HLDEs)

$$a \bullet x = b \bullet y$$

Example

$$[1, 1] \bullet [x_1, x_2] = [2] \bullet [y_1]$$

Remark

we represent HLDEs by lists of coefficients, e.g., $([1, 1], [2])$

Solutions of HLDEs

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- set of (pointwise) minimal solutions
 $\mathcal{M} = \{(x, y) \in \mathcal{S} \mid x \neq 0, \nexists (u, v) \in \mathcal{S}. u \neq 0 \wedge u \ll v \ll x \ll y\}$

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$$x \ll_v y \text{ iff } x_i \leq y_i \text{ and } x \neq y$$

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- given $x_1 + x_2 = 2y_1$, represented by $[1, 1]$ and $[2]$
- consider potential solutions

$$\begin{array}{ccc} x_1 & x_2 & y_1 \\ [0, 0], & [0] & ? \end{array}$$

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$[0, 0], [0] \checkmark$ (trivial solution, not minimal)

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$[0, 0]$, $[1]$?

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| x_1 | x_2 | y_1 | |
|-------|-------|-------|-----------------------------------|
| 0 | 0 | 0 | ✓ (trivial solution, not minimal) |
| 0 | 0 | 1 | ✗ |
| | | ⋮ | |
| 1 | 1 | 1 | ? |

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| | \vdots | | |
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| $[2, 0]$ | $[1]$ | $[1]$ | ? |

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| \vdots | | | |
| $[1, 1]$ | $[1]$ | $[1]$ | ✓ |
| \vdots | | | |
| $[2, 0]$ | $[1]$ | $[1]$ | ✓ |
| \vdots | | | |
| $[3, 1]$ | $[2]$ | $[2]$ | ? |

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| \vdots | | | |
| $[1, 1]$ | $[1]$ | $[1]$ | ✓ |
| \vdots | | | |
| $[2, 0]$ | $[1]$ | $[1]$ | ✓ |
| \vdots | | | |
| $[3, 1]$ | $[2]$ | $[2]$ | ✓ (but not minimal) |

Bounding Minimal Solutions

Lemma (Huet)

if $(x, y) \in \mathcal{M}(a, b)$ then $x_i \leq \max(b)$ and $y_j \leq \max(a)$

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Example

- for $a = [1, 1]$ and $b = [2]$

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Example

- for $a = [1, 1]$ and $b = [2]$

- 18 potential solutions ($3^2 \cdot 2^1$)

$[(0, 0), [0]], ([1, 0], [0]), ([2, 0], [0]), ([0, 1], [0]),$
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([0, 1], [1]), ([1, 1], [1]), ([2, 1], [1]), ([0, 2], [1]),
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- containing 4 actual solutions ($a \bullet x = b \bullet y$)
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Bounding Minimal Solutions

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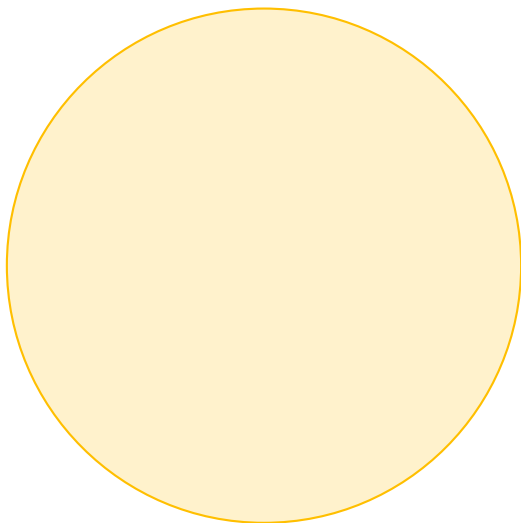
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- containing 4 actual solutions ($a \bullet x = b \bullet y$)
[[([0, 0], [0]), ([2, 0], [1]), ([1, 1], [1]), ([0, 2], [1])]]
- of which 3 are minimal (w.r.t. $<_v$)
[[([2, 0], [1]), ([0, 2], [1]), ([1, 1], [1])]]

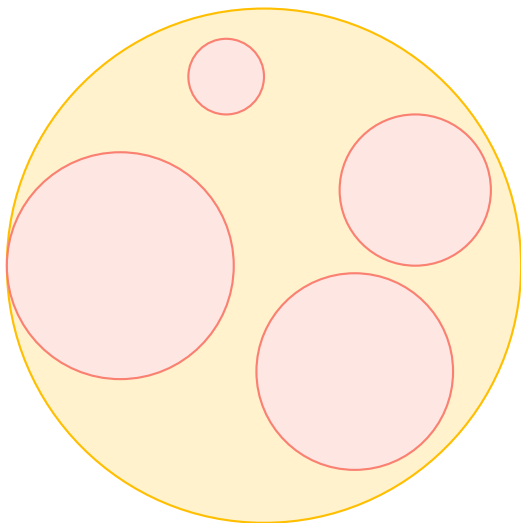
Computing Minimal Complete Sets of Solutions

1. **generate** potential solutions (crude overapproximation)



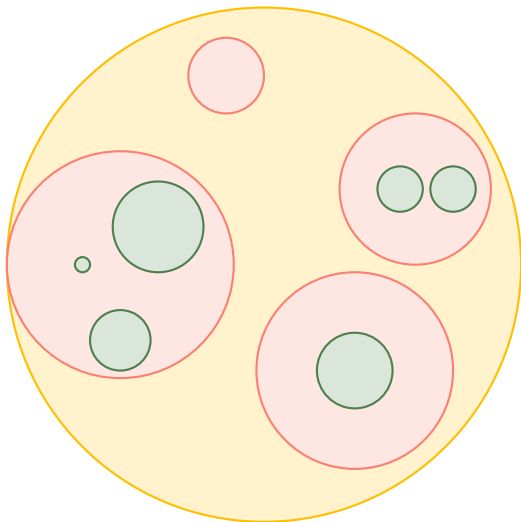
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1. generate potential solutions (crude overapproximation)
2. **check** for actual solutions



Computing Minimal Complete Sets of Solutions

1. generate potential solutions (crude overapproximation)
2. check for actual solutions
3. **minimize** remaining set of candidates



Phase 1 – Generate

- given bound b and coefficients cs

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- given bound `b` and coefficients `cs`
- compute all vectors of length equal to `length cs` within bound

```
gen b [] = [[]]
```

```
gen b (c:cs) = [x:xs | xs <- gen b cs, x <- [0 .. b]]
```

Phase 1 – Generate

- given bound b and coefficients cs
- compute all vectors of length equal to $\text{length } cs$ within bound
`gen b [] = [[]]`
`gen b (c:cs) = [x:xs | xs <- gen b cs, x <- [0 .. b]]`
- given bounds a, b and coefficients as, bs

Example

- equation $x_1 + x_2 = 2y_1$, $a = 2$, $b = 1$, $as = [1, 1]$, $bs = [2]$

Phase 1 – Generate

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`gen b [] = [[]]`
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- compute all potential solutions within bounds
`generate a b as bs =`
`tail [(x, y) | y <- gen b bs, x <- gen a as]`

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`[0,0],` `[1,0],` `[2,0],` `[0,1],` `[1,1],`
`[2,1],` `[0,2],` `[1,2],` `[2,2],`

Phase 1 – Generate

- given bound b and coefficients cs
- compute all vectors of length equal to $\text{length } cs$ within bound
 $\text{gen } b \ [] = [[]]$
 $\text{gen } b \ (c:cs) = [x:xs \mid xs \leftarrow \text{gen } b \ cs, x \leftarrow [0 \dots b]]$
- given bounds a, b and coefficients as, bs
- compute all potential solutions within bounds
 $\text{generate } a \ b \ as \ bs =$
 $\text{tail } [(x, y) \mid y \leftarrow \text{gen } b \ bs, x \leftarrow \text{gen } a \ as]$
- (solutions are generated in reverse lexicographic order $<_{\text{rlex}}$)

Example

- equation $x_1 + x_2 = 2y_1$, $a = 2$, $b = 1$, $as = [1, 1]$, $bs = [2]$

| | | | | |
|---------------|---------------|---------------|---------------|---------------|
| $[0, 0], [0]$ | $[1, 0], [0]$ | $[2, 0], [0]$ | $[0, 1], [0]$ | $[1, 1], [0]$ |
| $[2, 1], [0]$ | $[0, 2], [0]$ | $[1, 2], [0]$ | $[2, 2], [0]$ | |
| $[0, 0], [1]$ | $[1, 0], [1]$ | $[2, 0], [1]$ | $[0, 1], [1]$ | $[1, 1], [1]$ |
| $[2, 1], [1]$ | $[0, 2], [1]$ | $[1, 2], [1]$ | $[2, 2], [1]$ | |

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- (solutions are generated in reverse lexicographic order $<_{\text{rlex}}$)

Example

$$x <_{\text{rlex}} y \text{ iff } \exists i. x_i < y_i \wedge \forall j > i. x_j = y_j$$

- equation $x_1 + x_2 = 2y_1$, $a = 2$, $b = 1$, $as = [1, 1]$, $bs = [2]$

[1, 0], [0] [2, 0], [0] [0, 1], [0] [1, 1], [0]

[2, 1], [0] [0, 2], [0] [1, 2], [0] [2, 2], [0]

[0, 0], [1] [1, 0], [1] [2, 0], [1] [0, 1], [1] [1, 1], [1]

[2, 1], [1] [0, 2], [1] [1, 2], [1] [2, 2], [1]

Phase 2 – Check

- drop non-solutions

`check as bs = filter (isSolution as bs)`

Example

- equation $x_1 + x_2 = 2y_1$, $a = 2$, $b = 1$, $as = [1, 1]$, $bs = [2]$

| | | | | |
|-------------|-------------|-------------|-------------|-------------|
| | [1, 0], [0] | [2, 0], [0] | [0, 1], [0] | [1, 1], [0] |
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- drop non-solutions

```
check as bs = filter (isSolution as bs)
```

Example

- equation $x_1 + x_2 = 2y_1$, $a = 2$, $b = 1$, $as = [1, 1]$, $bs = [2]$

$[2, 0], [1]$
 $[0, 2], [1]$

$[1, 1], [1]$

Phase 2 – Check

- drop non-solutions

```
check as bs = filter (isSolution as bs)
```

Phase 3 – Minimize

- `minimize [] = []`

```
minimize ((x,y):xs) =  
  (x,y) : filter (x ++ y <_v) (minimize xs)
```

Remark

if $x <_v y$ then $x <_{\text{rlex}} y$

Example

- equation $x_1 + x_2 = 2y_1$, $a = 2$, $b = 1$, $as = [1, 1]$, $bs = [2]$

$[0, 2], [1]$ $[2, 0], [1]$ $[1, 1], [1]$

A Simple Algorithm

solutions `as bs =`

`minimize (check as bs (generate a b as bs))`

`where`

`a = maximum bs`

`b = maximum as`

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algorithm is **sound** and **complete**, that is, solutions $a b = \mathcal{M}(a, b)$

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Examples

| a | b | #solutions | time (s) |
|-------|-----|------------|----------|
| [1,1] | [2] | 3 | 0.001 |

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Examples

| <i>a</i> | <i>b</i> | #solutions | time (s) |
|----------|----------|------------|----------|
| [1,1] | [2] | 3 | 0.001 |
| [1,1] | [3] | 4 | 0.001 |
| [1,1,1] | [3] | 10 | 0.001 |

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Examples

| <i>a</i> | <i>b</i> | #solutions | time (s) |
|-----------|--------------|------------|----------|
| [1, 1] | [2] | 3 | 0.001 |
| [1, 1] | [3] | 4 | 0.001 |
| [1, 1, 1] | [3] | 10 | 0.001 |
| [1, 2, 5] | [1, 2, 3, 4] | 39 | 0.2 |

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| [1, 2, 5] | [1, 2, 3, 4] | 39 | 0.2 |
| [1, 1, 1, 2, 3] | [1, 1, 2, 2] | 44 | 0.2 |

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| [1, 1, 1, 2, 3] | [1, 1, 2, 2] | 44 | 0.2 |
| [2, 5, 9] | [1, 2, 3, 7, 8] | 119 | 85.5 |

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| [1, 1] | [2] | 3 | 0.001 |
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| [2, 5, 9] | [1, 2, 3, 7, 8] | 119 | 85.5 |
| [2, 2, 2, 3, 3, 3] | [2, 2, 2, 3, 3, 3] | 138 | 125.4 |

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| [2, 2, 2, 3, 3, 3] | [2, 2, 2, 3, 3, 3] | 138 | 125.4 |
| [1, 2, 2, 5, 9] | [1, 2, 3, 7, 8] | timeout (after 20 min) | |

Special Solutions

- given i and j , unique **special solution** is

$$0 \cdots \text{lcm}(a_i, b_j)/a_i \cdots 0, 0 \cdots \text{lcm}(a_i, b_j)/b_j \cdots 0$$

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- only 1 non-zero x_i and y_j

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- all special solutions are minimal

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- all special solutions are minimal

Example

- equation $x_1 + x_2 = 2y_1$

- special solutions

$$\text{specialSolutions } [1, 1] \ [2] = [([2, 0], [1]), ([0, 2], [1])]$$

Special Solutions

- given i and j , unique special solution is

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- only 1 non-zero x_i and y_j
- all special solutions are minimal
- it remains to compute non-special solutions (that is, those minimal solutions that are not special)

Example

- equation $x_1 + x_2 = 2y_1$
- special solutions
`specialSolutions [1,1] [2] = [[2,0],[1]],([0,2],[1]]`

Non-Special Solutions

Lemma (Huet)

if (x, y) is non-special minimal solution then

- $y_j \leq \text{max}_y x_j$
- $\text{take } a \ k \bullet \text{take } x \ k \leq b \bullet y$
- $\text{take } b \ l \bullet \text{take } y \ l \leq a \bullet \text{map } (\text{max}_x (\text{take } y \ l)) [0..m - 1]$

where

$\text{max}_x y \ i = \text{if } i < m \wedge D_i y \neq 0 \text{ then } \min(D_i y) \text{ else } \max(b)$

$\text{max}_y x \ j = \text{if } j < n \wedge E_j x \neq 0 \text{ then } \min(E_j x) \text{ else } \max(a)$

$D_i y = \{\text{lcm}(a_i, b_j)/a_i - 1 \mid j < |y| \wedge y_j \geq \text{lcm}(a_i, b_j)/b_j\}$

$E_j x = \{\text{lcm}(a_i, b_j)/b_j - 1 \mid i < |x| \wedge x_i \geq \text{lcm}(a_i, b_j)/a_i\}$

Non-Special Solutions

Lemma (Huet)

if (x, y) is non-special minimal solution then

- $y_j \leq \max_x x_j$
- $\text{take } a \ k \bullet \text{take } x \ k \leq b \bullet y$
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where

$$\text{maxx } y \ i = \text{if } i < m \wedge D_i \ y \neq 0 \text{ then } \min(D_i \ y) \text{ else } \max(b)$$
$$\text{maxy } x \ j = \text{if } j < n \wedge E_j \ x \neq 0 \text{ then } \min(E_j \ x) \text{ else } \max(a)$$
$$D_i \ y = \{\text{lcm}(a_i, b_j) / a_i - 1 \mid j < |y| \wedge y_j \geq \text{lcm}(a_i, b_j) / b_j\}$$
$$E_j \ x = \{\text{lcm}(a_i, b_j) / b_j - 1 \mid i < |x| \wedge x_i \geq \text{lcm}(a_i, b_j) / a_i\}$$

Improved Bounds on Minimal Solutions

(Clausen and Fortenbacher)

if (x, y) is minimal solution then $x_i \leq \max^{≠0} y \ b$ and $y_j \leq \max^{≠0} x \ a$

Merging Generate and Check

- compute all vectors of length equal to `length cs` whose elements and “partial sums” satisfy `p`

```
inCs p c i (xs,s) =  
  if p (i:xs) t then (i:xs,t) : inCs p c (i+1) (xs,s)  
  else []  
where  
  t = s + c*i
```

```
genCheck p [] = [([],0)]  
genCheck p (c:cs) =  
  concat (map (inCs p c 0) (genCheck p cs))
```

Merging Generate and Check

- compute all vectors of length equal to `length cs` whose elements and “partial sums” satisfy `p`

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inCs p c i (xs,s) =  
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where  
  t = s + c*i
```

```
genCheck p [] = [([]),0]  
genCheck p (c:cs) =  
  concat (map (inCs p c 0) (genCheck p cs))
```

- compute potential solutions within bounds

```
generateCheck as bs =  
  tail [(x, y) | (y, _) <- genCheck q bs,  
                (x, _) <- genCheck (p y) as]  
where  
  p ys (x:_) s = s <= bs `dp` ys && x <= maxne0 ys bs  
  ...
```


An Improved Algorithm

- additional check phase

```
check' as bs = filter (\(xs, ys) ->
  all (<= maxne0 xs as) ys &&
  isSolution as bs xs ys &&
  all (\j -> ys !! j <= maxy xs j) [0..length bs - 1])
```

An Improved Algorithm

- additional check phase

```
check' as bs = filter (\(xs, ys) ->
  all (<= maxne0 xs as) ys &&
  isSolution as bs xs ys &&
  all (\j -> ys !! j <= maxy xs j) [0..length bs - 1])
```

- computing non-special solutions

```
nonSpecialSolutions as bs =
  minimize (check' as bs (generateCheck as bs))
```

An Improved Algorithm

- additional check phase

```
check' as bs = filter (\(xs, ys) ->
  all (<= maxne0 xs as) ys &&
  isSolution as bs xs ys &&
  all (\j -> ys !! j <= maxy xs j) [0..length bs - 1])
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- computing non-special solutions

```
nonSpecialSolutions as bs =
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```

- the algorithm

```
solutions' as bs =
  specialSolutions as bs ++ nonSpecialSolutions as bs
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An Improved Algorithm

- additional check phase

```
check' as bs = filter (\(xs, ys) ->
  all (<= maxne0 xs as) ys &&
  isSolution as bs xs ys &&
  all (\j -> ys !! j <= maxy xs j) [0..length bs - 1])
```

- computing non-special solutions

```
nonSpecialSolutions as bs =
  minimize (check' as bs (generateCheck as bs))
```

- the algorithm

```
solutions' as bs =
  specialSolutions as bs ++ nonSpecialSolutions as bs
```

Lemma

`solutions'` and `solutions` compute the same results

Example

```
generateCheck [1,1] [2]
```

```
nonSpecialSolutions [1,1] [2]
```

```
solutions' [1,1] [2]
```

Example

```
generateCheck [1,1] [2]
```

```
nonSpecialSolutions [1,1] [2]
```

```
solutions' [1,1] [2]  
= specialSolutions [1,1] [2] ++ nonSpecialSolutions ...
```

Example

```
generateCheck [1,1] [2]
```

```
nonSpecialSolutions [1,1] [2]  
  = minimize (check' [1,1] [2] (generateCheck [1,1] [2]))
```

```
solutions' [1,1] [2]  
  = specialSolutions [1,1] [2] ++ nonSpecialSolutions ...
```

Example

```
generateCheck [1,1] [2]
= tail [(x,y) | y <- genCheck q [2],
            x <- genCheck (p y) [1,1]]
```

```
nonSpecialSolutions [1,1] [2]
= minimize (check' [1,1] [2] (generateCheck [1,1] [2]))
```

```
solutions' [1,1] [2]
= specialSolutions [1,1] [2] ++ nonSpecialSolutions ...
```


Example

```
generateCheck [1,1] [2]
= tail [(x,y) | y <- genCheck q [2],
           x <- genCheck (p y) [1,1]]
= tail ([(x,[0]) | x <- genCheck (p [0]) [1,1]] ++ [(x,[1])
```

```
nonSpecialSolutions [1,1] [2]
= minimize (check' [1,1] [2] (generateCheck [1,1] [2]))
```

```
solutions' [1,1] [2]
= specialSolutions [1,1] [2] ++ nonSpecialSolutions ...
```

Example

```
generateCheck [1,1] [2]
= tail [(x,y) | y <- genCheck q [2],
           x <- genCheck (p y) [1,1]]
= tail ([(x,[0]) | x <- genCheck (p [0]) [1,1]] ++ [(x,[1])])
= tail ([(x,[0]) | x <- [[0,0]]] ++ [(x,[1]) | ...])
```

```
nonSpecialSolutions [1,1] [2]
= minimize (check' [1,1] [2] (generateCheck [1,1] [2]))
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```
solutions' [1,1] [2]
= specialSolutions [1,1] [2] ++ nonSpecialSolutions ...
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Example

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generateCheck [1,1] [2]
= tail [(x,y) | y <- genCheck q [2],
           x <- genCheck (p y) [1,1]]
= tail ([(x,[0]) | x <- genCheck (p [0]) [1,1]] ++ [(x,[1])])
= tail ([(x,[0]) | x <- [[0,0]]] ++ [(x,[1]) | ...])
= tail ([[0,0],[0]) : [(x,[1]) | ...])
```

```
nonSpecialSolutions [1,1] [2]
= minimize (check' [1,1] [2] (generateCheck [1,1] [2]))
```

```
solutions' [1,1] [2]
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generateCheck [1,1] [2]
= tail [(x,y) | y <- genCheck q [2],
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= tail ([(x,[0]) | x <- [[0,0]]] ++ [(x,[1]) | ...])
= tail (([0,0],[0]) : [(x,[1]) | ...])
= [(x,[1]) | x <- genCheck (p [1]) [1,1]]
```

```
nonSpecialSolutions [1,1] [2]
= minimize (check' [1,1] [2] (generateCheck [1,1] [2]))
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```
solutions' [1,1] [2]
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Example

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generateCheck [1,1] [2]
= tail [(x,y) | y <- genCheck q [2],
          x <- genCheck (p y) [1,1]]
= tail ([(x,[0]) | x <- genCheck (p [0]) [1,1]] ++ [(x,[1])])
= tail ([(x,[0]) | x <- [[0,0]]] ++ [(x,[1]) | ...])
= tail (([0,0],[0]) : [(x,[1]) | ...])
= [(x,[1]) | x <- genCheck (p [1]) [1,1]]
= [(x,[1]) | x <- [[0,0],[1,0],[2,0],[0,1],[1,1],[0,2]] ]
```

```
nonSpecialSolutions [1,1] [2]
= minimize (check' [1,1] [2] (generateCheck [1,1] [2]))
```

```
solutions' [1,1] [2]
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Example

```
generateCheck [1,1] [2]
= tail [(x,y) | y <- genCheck q [2],
           x <- genCheck (p y) [1,1]]
= tail ([(x,[0]) | x <- genCheck (p [0]) [1,1]] ++ [(x,[1])])
= tail ([(x,[0]) | x <- [[0,0]]] ++ [(x,[1]) | ...])
= tail (([0,0],[0]) : [(x,[1]) | ...])
= [(x,[1]) | x <- genCheck (p [1]) [1,1]]
= [(x,[1]) | x <- [[0,0],[1,0],[2,0],[0,1],[1,1],[0,2]] ]
= (([0,0],[1]),([1,0],[1]),([2,0],[1]),([0,1],[1]),
   ([1,1],[1]),([0,2],[1]))

nonSpecialSolutions [1,1] [2]
= minimize (check' [1,1] [2] (generateCheck [1,1] [2]))

solutions' [1,1] [2]
= specialSolutions [1,1] [2] ++ nonSpecialSolutions ...
```

Example

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= tail ([(x,[0]) | x <- [[0,0]]] ++ [(x,[1]) | ...])
= tail (([0,0],[0]) : [(x,[1]) | ...])
= [(x,[1]) | x <- genCheck (p [1]) [1,1]]
= [(x,[1]) | x <- [[0,0],[1,0],[2,0],[0,1],[1,1],[0,2]] ]
= ([([0,0],[1]),([1,0],[1]),([2,0],[1]),([0,1],[1]),
  ([1,1],[1]),([0,2],[1]))])

nonSpecialSolutions [1,1] [2]
= minimize (check' [1,1] [2] (generateCheck [1,1] [2]))
= minimize ([([1,1],[1]))])

solutions' [1,1] [2]
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Example

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generateCheck [1,1] [2]
= tail [(x,y) | y <- genCheck q [2],
           x <- genCheck (p y) [1,1]]
= tail ([(x,[0]) | x <- genCheck (p [0]) [1,1]] ++ [(x,[1])])
= tail ([(x,[0]) | x <- [[0,0]]] ++ [(x,[1]) | ...])
= tail (([0,0],[0]) : [(x,[1]) | ...])
= [(x,[1]) | x <- genCheck (p [1]) [1,1]]
= [(x,[1]) | x <- [[0,0],[1,0],[2,0],[0,1],[1,1],[0,2]] ]
= ([0,0],[1]),([1,0],[1]),([2,0],[1]),([0,1],[1]),
   ([1,1],[1]),([0,2],[1]))

nonSpecialSolutions [1,1] [2]
= minimize (check' [1,1] [2] (generateCheck [1,1] [2]))
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solutions' [1,1] [2]
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Example

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generateCheck [1,1] [2]
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= tail ([(x,[0]) | x <- [[0,0]]] ++ [(x,[1]) | ...])
= tail (([0,0],[0]) : [(x,[1]) | ...])
= [(x,[1]) | x <- genCheck (p [1]) [1,1]]
= [(x,[1]) | x <- [[0,0],[1,0],[2,0],[0,1],[1,1],[0,2]] ]
= (([0,0],[1]),([1,0],[1]),([2,0],[1]),([0,1],[1]),
  ([1,1],[1]),([0,2],[1]))
```

```
nonSpecialSolutions [1,1] [2]
= minimize (check' [1,1] [2] (generateCheck [1,1] [2]))
= minimize ([(1,1],[1)])
= ([(1,1],[1)])
```

```
solutions' [1,1] [2]
= specialSolutions [1,1] [2] ++ nonSpecialSolutions ...
= (([2,0],[1]),([0,2],[1])) ++ ([(1,1],[1)])
```

Examples

| <i>a</i> | <i>b</i> | #solutions | time (s) |
|--------------------|--------------------|------------------------|----------|
| [1, 1] | [2] | 3 | 0.001 |
| [1, 1] | [3] | 4 | 0.001 |
| [1, 1, 1] | [3] | 10 | 0.001 |
| [1, 2, 5] | [1, 2, 3, 4] | 39 | 0.1 |
| [1, 1, 1, 2, 3] | [1, 1, 2, 2] | 44 | 0.1 |
| [2, 5, 9] | [1, 2, 3, 7, 8] | 119 | 85.5 |
| [2, 2, 2, 3, 3, 3] | [2, 2, 2, 3, 3, 3] | 138 | 125.4 |
| [1, 2, 2, 5, 9] | [1, 2, 3, 7, 8] | timeout (after 20 min) | |

Examples

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|--------------------|--------------------|------------|----------|
| [1, 1] | [2] | 3 | 0.001 |
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| [1, 1, 1] | [3] | 10 | 0.001 |
| [1, 2, 5] | [1, 2, 3, 4] | 39 | 0.05 |
| [1, 1, 1, 2, 3] | [1, 1, 2, 2] | 44 | 0.01 |
| [2, 5, 9] | [1, 2, 3, 7, 8] | 119 | 8.6 |
| [2, 2, 2, 3, 3, 3] | [2, 2, 2, 3, 3, 3] | 138 | 0.06 |
| [1, 2, 2, 5, 9] | [1, 2, 3, 7, 8] | 345 | 517.4 |
| [1, 4, 4, 8, 12] | [3, 6, 9, 12, 20] | 232 | 67.4 |

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- basis for computing minimal complete sets of AC unifiers

Summary

- first formalization of HLDEs (we used Isabelle/HOL)
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- clear separation of 3 phases: generate, check, and minimize
- which greatly simplifies proofs
- basis for computing minimal complete sets of AC unifiers
- improved efficiency by partially merging generate and check phases