



# SAT and SMT Solving

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lecture 7 WS 2022

- Summary of Last Week
- Linear Arithmetic
- Simplex Algorithm

# Deciding the Theory of Equality

# Definition

- $\blacktriangleright$  equality logic formula  $\varphi_{\rm EQ}$  is set of equations and inequalities between variables
- write  $Var(\varphi_{EQ})$  for set of variables occurring in  $\varphi_{EQ}$

# Definition

equality graph for  $\varphi_{EQ}$  is undirected graph  $(V, E_{=}, E_{\neq})$  with two kinds of edges

- nodes  $V = \mathcal{V}ar(\varphi_{\mathsf{EQ}})$
- $(x, y) \in E_{=}$  iff x = y in  $\varphi_{EQ}$
- $(x, y) \in E_{\neq}$  iff  $x \neq y$  in  $\varphi_{EQ}$

equality edge inequality edge

# Definition (Contradictory cycle)

contradictory cycle is simple cycle in equality graph with one  $E_{\neq}$  edge and all others  $E_{=}$  edges

# Theorem

 $\varphi_{\rm EQ}$  is satisfiable iff its equality graph has no contradictory cycle

- $\blacktriangleright$  can assume that = is the only predicate in  $\varphi$
- can replace variables by constants (Skolemization)

# **Congruence Closure**

Input: set of equations E and equation s = t (without variables, only constants)

Output: s = t is implied ( $E \vDash_{EUF} s = t$ ) or not implied ( $E \nvDash_{EUF} s = t$ )

- build congruence classes
  - (a) put different subterms of terms in  $E \cup \{s pprox t\}$  in separate sets
  - (b) merge sets  $\{\ldots, t_1, \ldots\}$  and  $\{\ldots, t_2, \ldots\}$  for all  $t_1 \approx t_2$  in E
  - (c) merge sets  $\{\ldots, f(t_1, \ldots, t_n), \ldots\}$  and  $\{\ldots, f(u_1, \ldots, u_n), \ldots\}$

if  $t_i$  and  $u_i$  belong to same set for all  $1 \leq i \leq n$ , repeatedly

2 if s and t belong to same set then return *implied* else return *not implied* 

# Satisfiability Check for EUF

 $(\bigwedge P) \land (\bigwedge N)$  unsatisfiable  $\iff \exists s \neq t \text{ in } \widehat{N} \text{ such that } \bigwedge \widehat{P} \vDash_{EUF} s = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \vDash_{EUF} s = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \vDash_{EUF} s = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \vDash_{EUF} s = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \vDash_{EUF} s = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \vDash_{EUF} s = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{N} \text{ such that } \bigwedge \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq i = t \exists s \neq t \text{ or } \widehat{P} \underset{i=1}{\overset{i=1}{\longrightarrow}} i = t \exists s \neq i = t \exists s \neq$ 

# Correctness of DPLL(T)

# Definition (DPLL(T) systems)

- ▶ basic system  $\mathcal{B}$ : unit propagate, decide, fail, *T*-backjump, *T*-propagate
- ▶ full system  $\mathcal{F}$ :  $\mathcal{B}$  plus T-learn, T-forget, and restart

#### Theorem (Correctness)

For derivation with final state  $S_n$ :

$$\| F \implies_{\mathcal{F}} S_1 \implies_{\mathcal{F}} S_2 \implies_{\mathcal{F}} \ldots \implies_{\mathcal{F}} S_n$$

- if  $S_n$  = FailState then F is T-unsatisfiable
- ▶ if  $S_n = M \parallel F'$  and M is T-consistent then F is T-satisfiable and  $M \vDash_T F$

#### Theorem (Termination)

- $\Gamma \colon \quad \parallel F \Longrightarrow_{\mathcal{F}}^* S_0 \Longrightarrow_{\mathcal{F}}^* S_1 \Longrightarrow_{\mathcal{F}}^* \dots \text{ is finite if }$ 
  - ▶ there is no infinite sub-derivation of only *T*-learn and *T*-forget steps, and
  - ► for every sub-derivation  $S_i \stackrel{restart}{\Longrightarrow} S_{i+1} \implies^*_{\mathcal{F}} S_j \stackrel{restart}{\Longrightarrow} S_{j+1} \implies^*_{\mathcal{F}} S_k$ 
    - there are more  $\mathcal{B}$ -steps in  $S_j \Longrightarrow_{\mathcal{F}}^* S_k$  than in  $S_i \Longrightarrow_{\mathcal{F}}^* S_j$ , or

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 $\sim$  a clause is learned in  $S \longrightarrow * S$ , that is never forgetten in  $\Gamma$ 

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- ► signature
  - ▶ binary predicates < and =</p>
  - binary function +, unary function -, constants 0 and 1

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- ► axioms

$$\forall x. (x = x) \qquad \forall x y. (x = y \rightarrow y = x) \qquad \forall x y z. (x = y \land y = z \rightarrow x = z)$$

equality

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$$\forall x. (x = x) \qquad \forall x y. (x = y \rightarrow y = x)$$

 $\forall x. (x+0=x) \quad \forall x y. (x+y=y+x) \qquad \forall x y z. (x+(y+z)=(x+y)+z)$ 

$$\forall x \ y \ z. \ (x = y \land y = z \rightarrow x = z)$$

commutative group with +

$$\forall x. (x + (-x) = 0)$$

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$$\begin{aligned} \forall x. (x = x) & \forall x y. (x = y \rightarrow y = x) \\ \forall x. (x + 0 = x) & \forall x y. (x + y = y + x) \\ \forall x. \neg (x < x) & \forall x y. (x < y \lor y < x \lor x = y) \\ \forall x. (x + (-x) = 0) \end{aligned}$$

< is total order

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non-triviality

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+ and < are compatible

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discreteness

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division with remainder

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#### Theorem

 $\blacktriangleright$  Z with usual interpretations is model of LIA

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- $\blacktriangleright$   $\mathbb{Z}$  with usual interpretations is model of LIA
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i.e., same formulas hold

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# Example

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# Example

•  $x+y+z = 1+1 \land y < z \land -1 < y$  LIA-satisfiable, v(x) = v(y) = 0, v(z) = 2

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- $x+y+z = 1+1 \land y < z \land -1 < y$  LIA-satisfiable, v(x) = v(y) = 0, v(z) = 2
- $> x < 1 \land 1 < x + x$

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- $x < 1 \land 1 < x + x$

LIA-unsatisfiable

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#### Syntactic Sugar

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### Syntactic Sugar

▶ ≤ binary predicate
 > and ≥ binary predicates
 s ≤ t abbreviates ¬(t < s)</li>
 use s > t for t < s and s ≥ t for t ≤ s</li>

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**Example (LIA with syntactic sugar)**  $ightarrow x+y+z = 2 \land z > y \land y \ge 0$   $ightarrow x < 1 \land 2x > 1$  ightarrow 7x = 41

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# **Example (LIA with syntactic sugar)** $ightarrow x+y+z = 2 \land z > y \land y \ge 0$ $ightarrow x < 1 \land 2x > 1$ ightarrow 7x = 41

#### Theorem

LIA is decidable and NP-complete

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  - unary (division) functions (-/n) for all n > 1

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#### Theorem

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#### Theorem

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# Definition (Theory of Linear Arithmetic over $\mathbb{Q}$ (LRA))

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# Example (LRA with syntactic sugar) • $\frac{4}{5}x = 2 \land \frac{x}{7} = \frac{y}{2} + 1$ • $x < \frac{7}{8} \land 2x > \frac{5}{4}$ • 7.5x = 41.2

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#### **Theorem** LRA is decidable in polynomial time

1826 Fourier and Motzkin (1936) developed elimination algorithm for LRA

▶ takes doubly exponential time

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maximize  $c(\overline{x})$  such that  $A\overline{x} \leq b$  and  $\overline{x} \geq 0$ 

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**2000**- SMT solvers use DPLL(T) version to solve satisfiability problem

 $A\overline{x}\leqslant b$ 

- Summary of Last Week
- Linear Arithmetic
- Simplex Algorithm

# Aim

build theory solver for linear rational arithmetic (LRA): decide whether set of linear (in)equalities is satisfiable over  $\mathbb Q$ 

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### **Disclaimer: Effects and Side Effects**

- guaranteed to solve all your real arithmetic problems
- consuming Simplex can cause initial dizzyness
- ▶ in some cases solving systems of linear inequalities can become addictive

constraints  $x - y \ge -1$   $y \le 4$   $x + y \ge 6$   $3x - y \le 7$ 



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- solution space
- Simplex algorithm: improve assignment in 4 iterations
  - ► x = 0, y = 0
  - ► x = 0, y = 6
  - ► x = 2, y = 4
  - ► x = 3, y = 4



- variables  $x_1, \ldots, x_n$
- *m* equalities for  $a_{ij} \in \mathbb{Q}$

 $a_{11}x_1+\ldots a_{1n}x_n=0$ 

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set of LRA literals where all predicates are  $\leq$ ,  $\geq$ , or = can be turned into equisatisfiable general form

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•  $s_1, s_2, s_3, s_4$  are slack variables, x, y are problem variables

#### Representation

• represent equalities by  $m \times (n+m)$  matrix A such that  $A \cdot \left(\frac{\overline{X}}{\overline{S}}\right) = 0$  $\begin{array}{cccccccc} -x+y-s_1=0 & s_1\leqslant 1 \\ y-s_2=0 & s_2\leqslant 4 \\ -x-y-s_3=0 & s_3\leqslant -6 \\ 3x-y-s_4=0 & s_4\leqslant 7 \end{array} \implies \begin{pmatrix} -1 & 1-1 & 0 & 0 & 0 \\ 0 & 1 & 0-1 & 0 & 0 \\ -1-1 & 0 & 0 & -1 & 0 \\ 3-1 & 0 & 0 & 0 & -1 \end{pmatrix} \begin{array}{c} s_1\leqslant 1 \\ s_2\leqslant 4 \\ s_3\leqslant -6 \\ s_4\leqslant 7 \end{array}$ 

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simplified matrix presentation

$$\begin{array}{c} x \quad y \\ s_1 \\ s_2 \\ s_3 \\ s_4 \\ s_4 \\ s_4 \end{array} \begin{pmatrix} -1 & 1 \\ 0 & 1 \\ -1 & -1 \\ 3 & -1 \end{pmatrix}$$

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dependent variables  $\rightarrow$ 

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x \quad y \\
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s_2 \\
s_3 \\
s_4 \\
\end{array}
\begin{pmatrix}
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 $\leftarrow \textit{independent} \text{ variables}$ 

### Representation

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 $y - s_2 = 0$   $s_2 \le 4$  $-x - y - s_3 = 0$   $s_3 \le -6$  $3x - y - s_4 = 0$   $s_4 \le 7$ 

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matrix A such that 
$$A \cdot \begin{pmatrix} \hat{s} \\ \bar{s} \end{pmatrix} = 0$$
  

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### Notation

- simplified matrix is called tableau
- ▶ D is set of dependent (or basic) variables, in tableau listed on the left
- ► *I* is set of independent (or non-basic) variables, in tableau on top)

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- 7 perform pivot operation on x and y

(i.e., make x independent and y dependent)

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 $\begin{array}{cccc} tableau & bounds \\ & x & y \\ s_1 \\ s_2 \\ s_3 \\ s_4 \end{array} \begin{pmatrix} -1 & 1 \\ 0 & 1 \\ -1 & -1 \\ 3 & -1 \end{pmatrix} & \begin{array}{c} s_1 \leqslant 1 \\ s_2 \leqslant 4 \\ s_3 \leqslant -6 \\ s_4 \leqslant 7 \end{array}$ 





#### 1 Iteration 1

▶ *s*<sub>3</sub> violates its bounds



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$$s_3 = -6$$
  $y = 6$   
 $s_1 = 6$   $s_2 = 6$   $s_4 = -6$  17





#### 2 Iteration 2

▶ *s*<sub>2</sub> violates its bounds



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update assignment (to violated bound of s<sub>2</sub>)

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update assignment (to violated bound of s<sub>2</sub>)

$$s_2 = 4$$
  $x = 2$   
 $s_1 = 2$   $y = 4$   $s_4 = 2$  1



#### 3 Iteration 3

▶ *s*<sub>1</sub> violates its bounds



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- ▶ decreasing s<sub>1</sub> requires to decrease s<sub>2</sub> or s<sub>3</sub> because s<sub>1</sub> = 2s<sub>2</sub> + s<sub>3</sub>: both suitable since they have no lower bound



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update assignment (to violated bound of s<sub>1</sub>)

$$s_1 = 1$$



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update assignment (to violated bound of s<sub>1</sub>)

$$s_1 = 1$$
  $s_3 = -7$   
 $x = 3$   $y = 4$   $s_4 = 5$  1



#### 4 Iteration 4

all variables satisfy their bounds: satisfiable!

# Simplex, Visually

- constraints
  - $x y \ge -1$  $y \le 4$  $x + y \ge 6$  $3x y \le 7$
- solution space
- Simplex algorithm: improve assignment in 4 iterations
  - ► x = 0, y = 0
  - ► x = 0, y = 6
  - ► x = 2, y = 4
  - ► x = 3, y = 4


### DPLL(T) Simplex Algorithm

$$A\overline{x}_{I} = \overline{x}_{D}$$
(1)  
$$-\infty \leqslant l_{i} \leqslant x_{i} \leqslant u_{i} \leqslant +\infty$$
(2)

Invariant

▶ (1) is satisfied and (2) holds for all independent variables



#### Invariant

▶ (1) is satisfied and (2) holds for all independent variables

### Pivoting

▶ swap dependent  $x_i$  and independent  $x_i$ , so  $x_i \in D$  and  $x_i \in I$ 

 $(\star)$ 



#### Invariant

▶ (1) is satisfied and (2) holds for all independent variables

### Pivoting

▶ swap dependent  $x_i$  and independent  $x_j$ , so  $x_i \in D$  and  $x_j \in I$ 

$$x_i = \sum_{x_k \in I} A_{ik} x_k \tag{(\star)}$$



#### Pivoting

▶ swap dependent  $x_i$  and independent  $x_j$ , so  $x_i \in D$  and  $x_j \in I$ 

$$x_{i} = \sum_{x_{k} \in I} A_{ik} x_{k} \qquad \Longrightarrow \qquad x_{j} = \underbrace{\frac{1}{A_{ij}} (x_{i} - \sum_{x_{k} \in I - \{x_{j}\}} A_{ik} x_{k})}_{t} \qquad (\star)$$



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▶ new tableau A' consists of (\*) and  $x_m = A_{mj}t + \sum_{x_k \in I - \{x_j\}} A_{mk}x_k \quad \forall x_m \in D - \{x_i\}$ 



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- ▶ assignment of  $x_i$  is updated to previously violated bound  $l_i$  or  $u_i$ ,
- ▶ assignment of  $x_k$  is updated using A' for all  $\forall x_m \in D \{x_i\}$

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▶ suppose dependent variable *x<sub>i</sub>* violates lower and/or upper bound

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want to increase  $x_i$  need to decrease  $x_i$ 

 $A\overline{x}_{I} = \overline{x}_{D}$ (1)  $-\infty \leq l_{i} \leq x_{i} \leq u_{i} \leq +\infty$ (2)

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### Observation

selecting variables and pivots in unfortunate order may lead to non-termination

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# Bland's rule

select variable  $x_i$  in step 4 and  $x_j$  in step 5 such that  $(x_i, x_j)$  is minimal with respect to lexicographic extension of order on variables

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### Lemma

- ► Simplex terminates if pivot variables are selected according to Bland's rule
- problem is satisfiable iff Simplex returns satisfiable

### How to Deal With Strict Inequalities?

replace in LRA formula  $\varphi$  every strict inequality

 $a_1x_1 + \cdots + a_nx_n < b$ 

by non-strict inequality

$$a_1x_1 + \cdots + a_nx_n \leq b - \delta$$

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#### Lemma

 $\varphi$  is satisfiable  $\iff \exists$  rational number  $\delta > 0$  such that  $\varphi_{\delta}$  is satisfiable

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- robots needs to plan motions to place objects correctly
- ▶ instance of *constraint based planning*



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Neil T. Dantam, Zachary K. Kingston, Swarat Chaudhuri, and Lydia E. Kavraki. Incremental Task and Motion Planning: A Constraint-Based Approach. In: The International Journal of Robotics Research, 2018.

# (Almost) Everything is Better With Arithmetic

#### LRA and LIA admit more efficient encodings of

- ▶ *n*-queens
- Sudoku
- graph coloring
- Minesweeper
- travelling salesperson
- rabbit problem
- planning problems
- scheduling problems
- component configuration problems
- everything with cardinality constraints

...



Bruno Dutertre and Leonardo de Moura.

A Fast Linear-Arithmetic Solver for DPLL(T).

In Proc. of International Conference on Computer Aided Verification, pp. 81-94, 2006.

Bruno Dutertre and Leonardo de Moura **Integrating Simplex with DPLL(T)** Technical Report SRI–CSL–06–01, SRI International, 2006

### Test on December 2

- ► 50 minutes
- open (paper) book: bring arbitrary amount of printed paper, but use no electronic devices
- questions are like homework exercises:
   e.g., DPLL, implication graphs, give minimal unsatisfiable core of formula,
   equality graphs, congruence closure, DPLL(T), ... (no Simplex)