



# **SAT** and **SMT** Solving

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# Definition (Theory of Linear Arithmetic over C)

• for variables  $x_1, \ldots, x_n$ , formulas built according to grammar

$$\varphi ::= \varphi \land \varphi \mid t = t \mid t < t \mid t \leqslant t$$

$$t ::= a_1 x_1 + \dots + a_n x_n + b \qquad \text{for } a_1, \dots, a_n, b \in \text{in carrier } C$$

- ▶ axioms are equality axioms plus calculation rules of arithmetic over C
- ▶ solution assigns values in C to  $x_1, ..., x_n$

## **Definitions**

- ► carrier Q: linear real arithmetic (LRA), DPLL(T) simplex algorithm is decision procedure
- ightharpoonup carrier  $\mathbb{Z}$ : linear integer arithmetic (LIA)

## Outline

- Summary of Last Week
- Cyclic Simplex Example
- Branch and Bound
- Fourier-Motzkin Elimination

DPLL(T) Simplex Algorithm (1)

- ▶ linear arithmetic constraint solving over real or rational variables
- $\blacktriangleright$   $x_1, \ldots, x_n$  are split into dependent variables  $\overline{x}_D$  and independent variables  $\overline{x}_I$

#### Input

constraints plus upper and lower bounds for  $x_1, \ldots, x_n$ :

$$A\,\overline{x}_I = \overline{x}_D$$
 with tableau  $A \in \mathbb{Q}^{|D| \times |I|}$  (1)

$$l_i \leqslant x_i \leqslant u_i \tag{2}$$

## Output

satisfying assignment or "unsatisfiable"

#### Invariant

(1) is satisfied and (2) holds for all independent variables  $x_i$ 

# DPLL(T) Simplex Algorithm (2)

$$A\overline{x}_I = \overline{x}_D \tag{1}$$

$$I_i \leqslant x_i \leqslant u_i \tag{2}$$

#### Method

- ▶ if (2) holds for all dependent variables, return current assignment
- otherwise select dependent variable  $x_i \in D$  which violates (2)
- ▶ select suitable independent variable  $x_j \in I$  such that  $x_i$  and  $x_j$  can be swapped in a pivoting step, resulting in new tableau

$$A' x_{I'} = x_{D'}$$

with  $I' = I \cup \{x_i\} - \{x_i\}$  and  $D' = D \cup \{x_i\} - \{x_i\}$ 

 $\blacktriangleright$  change value of  $x_i$  to  $l_i$  or  $u_i$ , update values of dependent variables accordingly

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# **DPLL**(*T*) Simplex Algorithm (4)

$$A\overline{x}_I = \overline{x}_D \tag{1}$$

$$I_i \leqslant x_i \leqslant u_i \tag{2}$$

## **Suitability**

- ightharpoonup dependent variable  $x_i$  violates lower and/or upper bound
- ightharpoonup pick independent variable  $x_i$  such that
  - if  $x_i < l_i$ :  $A_{ij} > 0$  and  $x_i < u_i$  or  $A_{ij} < 0$  and  $x_i > l_i$
  - if  $x_i > u_i$ :  $A_{ij} > 0$  and  $x_i > l_i$  or  $A_{ij} < 0$  and  $x_i < u_i$
- problem is unsatisfiable if no suitable pivot exists

#### Bland's Rule

- $\blacktriangleright$  pick lexicographically smallest (i,j) that is suitable pivot
- ▶ guarantees termination

# DPLL(T) Simplex Algorithm (3)

$$A\overline{x}_I = \overline{x}_D \tag{1}$$

$$I_i \leqslant x_i \leqslant u_i \tag{2}$$

## **Pivoting**

 $\triangleright$  swap dependent  $x_i$  and non-dependent  $x_i$ 

$$x_{i} = \sum_{x_{k} \in I} A_{ik} x_{k} \qquad \Longrightarrow \qquad x_{j} = \underbrace{\frac{1}{A_{ij}} (x_{i} - \sum_{x_{k} \in I - \{x_{j}\}} A_{ik} x_{k})}_{t} \qquad (\star$$

 $\qquad \text{new tableau $A'$ consists of ($\star$) and $x_m = A_{mj}t + \sum_{x_k \in I - \{x_j\}} A_{mk} x_k \ \ \, \forall x_m \in D - \{x_i\}$ 

## **Update**

- $\blacktriangleright$  assignment of  $x_i$  is updated to previously violated bound  $l_i$  or  $u_i$ ,
- ▶ assignment of  $x_k$  is updated using A' for all  $\forall x_k \in D \{x_i\}$

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## **Example**

$$-1 \leqslant x_1 \leqslant 0$$
  $-4 \leqslant x_2 \leqslant 0$   $-5 \leqslant x_3 \leqslant -4$   $-7 \leqslant x_4 \leqslant 1$ 

# trajectory of assignments $(x_1, x_2)$ $x_2 = 0$ 0 $x_3 = 0$ $x_4 = 0$ $x_4 = 0$ $x_5 = 0$ $x_7 = 0$ $x_8 = 0$ $x_1 = 0$ $x_1 = 0$ $x_2 = -4$

# **Example**

$$-1 \leqslant x_1 \leqslant 0$$
  $-4 \leqslant x_2 \leqslant 0$   $-5 \leqslant x_3 \leqslant -4$   $-7 \leqslant x_4 \leqslant 1$ 



## **Disclaimer**

if advice of Dr. Bland is neglected, no cure is guaranteed!

# How to Be Lazy

- Summary of Last Week
- Cyclic Simplex Example
- Branch and Bound
- Fourier-Motzkin Elimination

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# **Example**

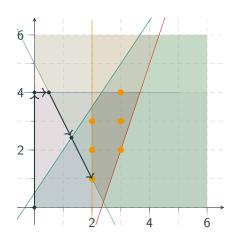
$$3x - 2y \geqslant -1$$

$$y \leqslant 4$$

$$2x + y \geqslant 5$$

$$3x - y \leqslant 7$$

- ▶ looking for solution in  $\mathbb{Z}^2$
- infinite  $\mathbb{Q}^2$  solution space, six solutions in  $\mathbb{Z}^2$
- ► Simplex returns  $(\frac{9}{7}, \frac{17}{7})$



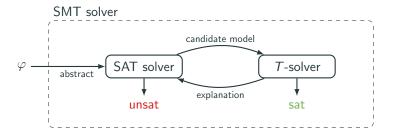
# Idea (Branch and Bound)

- $\blacktriangleright$  add constraints that exclude solution in  $\mathbb{Q}^2$  but do not change solutions in  $\mathbb{Z}^2$
- ▶ in current solution 1 < x < 2, so use Simplex on two augmented problems:
  - $ightharpoonup C \land x \leqslant 1$

unsatisfiable

 $ightharpoonup C \land x \geqslant 2$ 

satisfiable, Simplex can return (2,1)



Theory T

Pequality logic

Pequality + uninterpreted functions (EUF)

Popular real arithmetic (LRA)

Popular real arithmetic (LRA)

Popular real arithmetic (LIA)

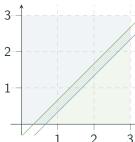
# **Algorithm** BranchAndBound( $\varphi$ )

```
LIA constraint \varphi
Input:
Output:
                 unsatisfiable, or satisfying assignment
   S \leftarrow \mathsf{decide} \ \varphi \ \mathsf{over} \ \mathbb{O}
                                                                              ⊳ e.g. by Simplex
  if S' = unsatisfiable then
       return unsatisfiable
   else if S is solution over \mathbb{Z} then
       return S
  else
       x \leftarrow \text{variable assigned non-integer value } q \text{ in } S
       S' = BranchAndBound(\varphi \land x \leqslant |q|)
       if S' \neq \text{unsatisfiable then}
            return S'
       else
            return BranchAndBound(\varphi \land x \geqslant \lceil q \rceil)
```

## **Definition**

 $\mathbb{Q}^2$ -solution space of linear arithmetic problem  $Ax \leq b$  is bounded if for all  $x_i$  there exist  $I_i, u_i \in \mathbb{Q}$  such that all  $\mathbb{Q}^2$ -solutions v satisfy  $I_i \leq v(x_i) \leq u_i$ 

# **Example**



- $\rightarrow$   $3x 3y \geqslant 1 \land 3x 3y \leqslant 2$
- unbounded problem
- ightharpoonup no solution in  $\mathbb{Z}^2$
- BranchAndBound keeps adding  $x \ge n$ ,  $y \ge m$  $x \le n$ ,  $y \le m$

## **Remarks**

- ▶ BranchAndBound might not terminate if solution space is unbounded
- methods exist to derive solution bounds from tableau, but bounds are often too high for efficient practical procedures
- ▶ use cutting planes to restrict solution space more efficiently

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# LIA Application: Finding Work Schedules

# **Example (Scheduling Problem)**

Is there a six-week cyclic work schedule for 22 employees who work 8-hour shifts, 24/7, 5 working days per week such that the following holds: In morning and afternoon shifts 6 employees are present, in night shifts 3. Joe does only morning shifts, Sally does not work on Sundays. Nobody works more than 6 days in a row.

## **Shift Schedule Requirements**

- ightharpoonup number of employees n
- ▶ set of shifts *A* (activities to be distributed)
- ▶ length of schedule (e.g. one week) and cyclicity
- requirement matrix R:  $R_{ii}$  is # employees required in shift i of day i
- ▶ prohibited shift sequences, maximal length of work blocks, ...

## LIA Encoding

- ▶ integer variable corresponding to employee for each activity
- ► cardinality constraints for requirement matrix

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## **Fourier-Motzkin Elimination**

#### Aim

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build theory solver for linear rational arithmetic (LRA): decide whether conjunction of linear (in)equalities  $\varphi$  is satisfiable over  $\mathbb Q$ 

Preprocessing: eliminate  $\neq$ 

 $(t_1 \neq t_2) \land \varphi$  is satisfiable iff  $(t_1 < t_2) \land \varphi$  or  $(t_1 > t_2) \land \varphi$  are satisfiable

## **Definition (Elimination step)**

• for variable x in  $\varphi$ , can write  $\varphi$  as

$$\bigwedge_{i}(x < U_{i}) \wedge \bigwedge_{j}(x \leqslant u_{j}) \wedge \bigwedge_{k}(L_{k} < x) \wedge \bigwedge_{m}(\ell_{m} \leqslant x) \wedge \psi$$

where  $U_i$ ,  $u_i$ ,  $L_k$ ,  $\ell_m$ ,  $\psi$  are without x



▶ let  $elim(\varphi, x)$  be conjunction of

$$\bigwedge_{i} \bigwedge_{k} (L_{k} < U_{i}) \quad \bigwedge_{i} \bigwedge_{m} (\ell_{m} < U_{i}) \quad \bigwedge_{j} \bigwedge_{k} (L_{k} < u_{j}) \quad \bigwedge_{j} \bigwedge_{m} (\ell_{m} \leqslant u_{j}) \quad \psi$$

#### Lemma

 $\varphi$  is LRA-satisfiable iff  $elim(\varphi, x)$  is LRA-satisfiable

## Observation

- ► can subsequently eliminate all variables
- checking satisfiability of formula without variables is easy
- so obtain decision procedure for LRA!

# **Example**

... on blackboard

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