

## WS 2023 lecture 10



# **Computability Theory**

**Aart Middeldorp** 

## Outline

- **1. Summary of Previous Lecture**
- 2. Arithmetization
- 3. Second Fixed Point Theorem
- 4. Undecidability
- 5. Typing
- 6. Summary

- (many-step) strategy S for ARS  $A = \langle A, \rightarrow \rangle$  is relation  $\rightarrow_S$  on A such that  $\rightarrow_S \subseteq \rightarrow^+$  and  $NF(\rightarrow_S) = NF(A)$
- one-step strategy satisfies  $\rightarrow_{\mathcal{S}} \subseteq \rightarrow$
- ▶ strategy S is deterministic if a = b whenever  $a_S \leftarrow \cdot \rightarrow_S b$
- strategy S for ARS A is normalizing if every normalizing element is S-terminating
- ► strategy S for ARS A is hyper-normalizing if every normalizing element is terminating with respect to →\* · →<sub>S</sub> · →\*
- ▶ strategy  $S_{\bullet}$  for ARS A with Z property for  $\bullet$ :  $a \rightarrow b$  if  $a \notin NF(A)$  and  $b = a^{\bullet}$
- ► root reduction  $\stackrel{\epsilon}{\rightarrow}$ : It  $\stackrel{\epsilon}{\rightarrow}$ t Ktu  $\stackrel{\epsilon}{\rightarrow}$ t Stuv  $\stackrel{\epsilon}{\rightarrow}$ tv(uv)
- leftmost outermost reduction  $\xrightarrow{lo}$ :

$$\frac{t \stackrel{\text{\tiny lo}}{\longrightarrow} u}{t \stackrel{\text{\tiny lo}}{\longrightarrow} u} \qquad \frac{t \stackrel{\text{\tiny lo}}{\longrightarrow} u \quad t \, v \in \mathsf{NF}(\stackrel{\epsilon}{\longrightarrow})}{t \, v \stackrel{\text{\tiny lo}}{\longrightarrow} u \, v} \qquad \frac{t \stackrel{\text{\tiny lo}}{\longrightarrow} u \quad v \, t \in \mathsf{NF}(\stackrel{\epsilon}{\longrightarrow})}{v \, t \stackrel{\text{\tiny lo}}{\longrightarrow} v \, u}$$

•  $t \xrightarrow{\neg lo} u$  if  $t \rightarrow u$  but not  $t \xrightarrow{\neg lo} u$ 

#### Theorem

 $\mathcal{S}_{\bullet}$  is hyper–normalizing for every ARS with Z property for  $\bullet$ 

#### Theorem (Factorization)

$$\rightarrow^* \subseteq \xrightarrow{\mathsf{lo}}^* \cdot \xrightarrow{\neg\mathsf{lo}}^*$$

#### Normalization Theorem

leftmost outermost reduction is hyper-normalizing

#### Theorem

partial recursive functions are CL-representable by combinators in normal form



#### **Part I: Recursive Function Theory**

Ackermann function, bounded minimization, bounded recursion, course–of–values recursion, diagonalization, diophantine sets, elementary functions, fixed point theorem, Fibonacci numbers, Gödel numbering, Gödel's  $\beta$  function, Grzegorczyk hierarchy, loop programs, minimization, normal form theorem, partial recursive functions, primitive recursion, recursive enumerability, recursive inseparability, s–m–n theorem, total recursive functions, ...

#### Part II: Combinatory Logic and Lambda Calculus

 $\alpha$ -equivalence, abstraction, arithmetization,  $\beta$ -reduction, CL-representability, combinators, combinatorial completeness, Church numerals, Church-Rosser theorem, Curry-Howard isomorphism, de Bruijn notation,  $\eta$ -reduction, fixed point theorem, intuitionistic propositional logic,  $\lambda$ -definability, normalization theorem, termination, typing, undecidability, Z property, ...

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## function $\varphi$ is partial recursive $\iff \varphi$ is CL-representable

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#### Remark (Hindley and Seldin, CUP 2008)

The main theorem of this chapter will be that every partial recursive function can be represented in both  $\lambda$  and CL.

## function $\varphi$ is partial recursive $\iff \varphi$ is CL-representable

#### Remark (Hindley and Seldin, CUP 2008)

The main theorem of this chapter will be that every partial recursive function can be represented in both  $\lambda$  and CL.

The converse is also true, that every function representable in  $\lambda$  or CL is partial recursive. But its proof is too **boring** to include in this book.

Gödel number of CL-term is defined inductively:

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#### Definition

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#### Definition

predicates I(x), K(x), S(x), A(x), V(x), term(x) are defined inductively:

$$I(x) \iff seq(x) \land len(x) = 1 \land (x)_1 = 0$$

$$\mathsf{K}(x) \quad \Longleftrightarrow \quad \mathsf{seq}(x) \, \land \, \mathsf{len}(x) = \mathsf{1} \, \land \, (x)_{\mathsf{1}} = \mathsf{1}$$

$$S(x) \iff seq(x) \land len(x) = 1 \land (x)_1 = 2$$

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#### Definition

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 $\mathsf{term}(x) \iff \mathsf{I}(x) \lor \mathsf{K}(x) \lor \mathsf{S}(x) \lor \mathsf{A}(x) \lor \mathsf{V}(x)$ 

$$\frac{t}{|t \to t|} \qquad \frac{k \to u}{|t \to t|} \qquad \frac{t \to u}{|t \to v|} \qquad \frac{t \to u}{|t \to v|} \qquad \frac{t \to u}{|t \to v|}$$

predicate step(x, y) is inductively defined:

 $step(x,y) \iff term(x) \land term(y) \land A(x) \land$ 



$$\frac{t \to u}{|t \to t|} \qquad \frac{t \to u}{|t \to v|} \qquad \frac{t \to u}{|t \to v|} \qquad \frac{t \to u}{|t \to v|}$$

$$step(x,y) \iff term(x) \land term(y) \land A(x) \land$$

$$\begin{bmatrix} I((x)_2) \land (x)_3 = y \end{bmatrix}$$

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$$step(x, y) \iff term(x) \land term(y) \land A(x) \land$$

$$\begin{bmatrix} I((x)_2) \land (x)_3 = y \end{bmatrix}$$

$$\lor \begin{bmatrix} A((x)_2) \land K((x)_{2,2}) \land (x)_{2,3} = y \end{bmatrix}$$

$$\frac{t \to u}{|t \to t|} \qquad \frac{|t \to u|}{|t \to v|} \qquad \frac{|t \to u|}{|t \to v|} \qquad \frac{|t \to u|}{|t \to v|}$$

$$step(x,y) \iff term(x) \land term(y) \land A(x) \land \\ \begin{bmatrix} I((x)_2) \land (x)_3 = y \end{bmatrix} \\ \lor [A((x)_2) \land K((x)_{2,2}) \land (x)_{2,3} = y] \\ \lor [A((x)_2) \land A((x)_{2,2}) \land S((x)_{2,2,2}) \land A(y) \land A((y)_2) \land A((y)_3) \land \\ (x)_{2,2,3} = (y)_{2,2} \land (x)_{2,3} = (y)_{3,2} \land (x)_3 = (y)_{2,3} \land (x)_3 = (y)_{3,3}] \end{bmatrix}$$

$$\frac{t \to u}{\mathsf{I}t \to t} \qquad \frac{\mathsf{K}tu \to t}{\mathsf{K}tu \to t} \qquad \frac{\mathsf{T}uv \to \mathsf{T}v(uv)}{\mathsf{T}v \to uv} \qquad \frac{\mathsf{T}uv \to u}{\mathsf{T}v \to vu}$$

$$step(x,y) \iff term(x) \land term(y) \land A(x) \land \\ \begin{bmatrix} I((x)_2) \land (x)_3 = y \end{bmatrix} \\ \lor [A((x)_2) \land K((x)_{2,2}) \land (x)_{2,3} = y] \\ \lor [A((x)_2) \land A((x)_{2,2}) \land S((x)_{2,2,2}) \land A(y) \land A((y)_2) \land A((y)_3) \land \\ (x)_{2,2,3} = (y)_{2,2} \land (x)_{2,3} = (y)_{3,2} \land (x)_3 = (y)_{2,3} \land (x)_3 = (y)_{3,3}] \\ \lor [A(y) \land step((x)_2, (y)_2) \land (x)_3 = (y)_3]$$

$$\frac{t}{|t \to t|} \qquad \frac{k \to u}{|t \to t|} \qquad \frac{t \to u}{|t \to v|} \qquad \frac{t \to u}{|t \to v|} \qquad \frac{t \to u}{|t \to v|}$$

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predicates reduction(x) and conversion(x)

 $\mathsf{reduction}(x) \quad \Longleftrightarrow \quad \mathsf{seq}(x) \, \land \, (\forall \, i < \mathsf{len}(x) \dot{-} 1) \left[ \, \mathsf{step}((x)_i, (x)_{i+1}) \, \right]$ 

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 $\mathsf{conversion}(x) \quad \Longleftrightarrow \quad \mathsf{seq}(x) \land (\forall i < \mathsf{len}(x) \dot{-} 1) \left[ \mathsf{step}((x)_{i}, (x)_{i+1}) \lor \mathsf{step}((x)_{i+1}, (x)_{i}) \right]$ 

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predicates zero(x) and numeral(x)

 $\operatorname{zero}(x) \iff \operatorname{A}(x) \wedge \operatorname{K}((x)_2) \wedge \operatorname{I}((x)_3)$ 

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 $\operatorname{zero}(x) \iff A(x) \wedge K((x)_2) \wedge I((x)_3)$   $\operatorname{numeral}(x) \iff \operatorname{zero}(x) \vee \left[A(x) \wedge A((x)_2) \wedge S((x)_{2,2}) \wedge B((x)_{2,3}) \wedge \operatorname{numeral}((x)_3)\right]$  $\blacktriangleright \operatorname{enc}(n) = \mathfrak{g}(n)$ 

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#### **Example**

 $enc(0) = \mathfrak{g}(KI)$ 

predicates reduction(x) and conversion(x)

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▶ predicates zero(x) and numeral(x)

•  $\operatorname{enc}(n) = \mathfrak{g}(\underline{n})$ 

#### Example

 $enc(0) = \mathfrak{g}(KI) = \langle 3, \langle 1 \rangle, \langle 0 \rangle \rangle$ 

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#### **Example**

 $enc(0) = \mathfrak{g}(KI) = \langle 3, \langle 1 \rangle, \langle 0 \rangle \rangle = 18375000$ 

• function dec:  $\mathbb{N} \to \mathbb{N}$ 

$$dec(x) = \begin{cases} 0 & \text{if } zero(x) \\ dec((x)_3) + 1 & \text{if } numeral(x) \land \neg zero(x) \\ 0 & \text{otherwise} \end{cases}$$

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#### Theorem

CL-representable functions are partial recursive

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#### Theorem

CL-representable functions are partial recursive

$$first(x) = (x)_1$$
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#### Theorem

CL-representable functions are partial recursive

## Proof

$$first(x) = (x)_1$$
  $last(x) = (x)_{len(x)}$ 

reduction(i)  $\land$  first(i) =  $\mathfrak{g}(F x_1 \cdots x_n) \land$  numeral(last(i))

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# Proof

$$\mathsf{first}(x) = (x)_1 \quad \mathsf{last}(x) = (x)_{\mathsf{len}(x)} \quad \mathfrak{g}(F \underline{x_1} \cdots \underline{x_n}) = \langle \mathsf{3}, \dots \langle \mathsf{3}, \mathfrak{g}(F), \mathsf{enc}(x_1) \rangle, \dots \mathsf{enc}(x_n) \rangle$$

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CL-representable functions are partial recursive

## Proof

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$$\operatorname{irst}(x) = (x)_1 \quad \operatorname{last}(x) = (x)_{\operatorname{len}(x)} \quad \mathfrak{g}(F \underline{x_1} \cdots \underline{x_n}) = \langle 3, \dots \langle 3, \mathfrak{g}(F), \operatorname{enc}(x_1) \rangle, \dots \operatorname{enc}(x_n) \rangle$$
$$(\mu i) \left[ \operatorname{reduction}(i) \land \operatorname{first}(i) = \mathfrak{g}(F \underline{x_1} \cdots \underline{x_n}) \land \operatorname{numeral}(\operatorname{last}(i)) \right]$$

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#### Theorem

CL-representable functions are partial recursive

# Proof

$$\mathsf{first}(x) = (x)_1 \quad \mathsf{last}(x) = (x)_{\mathsf{len}(x)} \quad \mathfrak{g}(F \underline{x_1} \cdots \underline{x_n}) = \langle \mathsf{3}, \dots \langle \mathsf{3}, \mathfrak{g}(F), \mathsf{enc}(x_1) \rangle, \dots \mathsf{enc}(x_n) \rangle$$

 $f(x_1, \ldots, x_n) \simeq \text{dec}(\text{last}((\mu i) [ \text{reduction}(i) \land \text{first}(i) = \mathfrak{g}(F \underline{x_1} \cdots \underline{x_n}) \land \text{numeral}(\text{last}(i))]))$ 

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#### Theorem

 $\forall$  CL-term  $F \exists$  CL-term X such that  $F \ulcorner X \urcorner \leftrightarrow^* X$ 



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## Theorem

 $\forall$  CL-term  $F \exists$  CL-term X such that  $F \ulcorner X \urcorner \leftrightarrow^* X$ 

#### Proof

• primitive recursive function  $a(x,y) = \langle 3, x, y \rangle$ 

 $\lceil t \rceil = \mathfrak{g}(t)$  is Church numeral of Gödel number of CL–term t

## Theorem

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# Outline

- **1. Summary of Previous Lecture**
- 2. Arithmetization
- 3. Second Fixed Point Theorem

# 4. Undecidability

- 5. Typing
- 6. Summary

▶ sets *T* and *U* of CL-terms are recursively separable if  $\{g(t) | t \in T\}$  and  $\{g(u) | u \in U\}$  are recursively separable

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## **Proof (by contradiction)**

- non-empty conversion–closed sets T and U of CL–terms
- $\exists$  recursive function  $f \colon \mathbb{N} \to \{0, 1\}$  such that

$$t\in T \implies f(\mathfrak{g}(t))=0 \qquad \qquad t\in U \implies f(\mathfrak{g}(t))=1$$

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4. Undecidability

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#### Corollary

set of normalizing CL-terms is not recursive

non-trivial conversion-closed sets of CL-terms are not recursive

#### Proof

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#### Corollary

set of normalizing CL-terms is not recursive: decision problem

instance: CL-term t

question: is t normalizing?

is undecidable

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# Notation

- outermost parentheses are omitted
- $\rightarrow$  is right-associative:  $ho \rightarrow \sigma \rightarrow \tau$  stands for  $ho \rightarrow (\sigma \rightarrow \tau)$

• type assignment formula  $t: \tau$  with CL-term t and type  $\tau$ 

- ▶ type assignment formula  $t : \tau$  with CL-term t and type  $\tau$
- type assignment system TA

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$$\mathsf{I}: \sigma \to \sigma \qquad \mathsf{K}: \sigma \to \tau \to \sigma \qquad \mathsf{S}: (\rho \to \sigma \to \tau) \to (\rho \to \sigma) \to \rho \to \tau$$

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$$\frac{t: \sigma \to \tau \quad u: \sigma}{t\, u: \tau}$$

for all types  $\sigma$ ,  $\tau$ ,  $\rho$  and CL–terms t and u

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#### Notation

 $\Gamma \vdash t : \tau$  if  $t : \tau$  can be derived in TA from assumptions in  $\Gamma$ 

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## Example **2**

 $\boldsymbol{x}: \boldsymbol{\sigma} \to \boldsymbol{\tau}, \ \boldsymbol{y}: \boldsymbol{\sigma} \vdash \mathbf{K} \boldsymbol{x} \mathbf{I} \boldsymbol{y}: \boldsymbol{\tau}$ 

 $\vdash \ \mathbf{SKK}: \sigma \to \sigma \ \text{for all types} \ \sigma$ 

$$\frac{\mathsf{S}: (\sigma \to (\sigma \to \sigma) \to \sigma) \to (\sigma \to \sigma \to \sigma) \to \sigma \to \sigma \qquad \mathsf{K}: \sigma \to (\sigma \to \sigma) \to \sigma}{\mathsf{SK}: (\sigma \to \sigma \to \sigma) \to \sigma \to \sigma} \qquad \frac{\mathsf{K}: \sigma \to \sigma \to \sigma}{\mathsf{SKK}: \sigma \to \sigma}$$

## Example **2**

$$\mathbf{x}: \sigma \rightarrow \tau, \ \mathbf{y}: \sigma \vdash \mathbf{K} \mathbf{x} \mathbf{I} \mathbf{y}: \tau$$

$$\frac{\mathsf{K}: (\sigma \to \tau) \to (\rho \to \rho) \to \sigma \to \tau \qquad \mathsf{X}: \sigma \to \tau}{\frac{\mathsf{K}\mathsf{X}: (\rho \to \rho) \to \sigma \to \tau}{\frac{\mathsf{K}\mathsf{X}: \sigma \to \tau}{\mathsf{K}\mathsf{X}: \sigma \to \tau}} \qquad \mathsf{Y}: \sigma}{\mathsf{K}\mathsf{X}: \mathsf{Y}: \tau}$$

# if $\Gamma, x : \sigma \vdash t : \tau$ and $x \notin Var(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

# if $\Gamma, x : \sigma \vdash t : \tau$ and $x \notin Var(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

# Proof

induction on definition of [x]t

# if $\Gamma, x : \sigma \vdash t : \tau$ and $x \notin Var(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

# Proof

induction on definition of [x]t

1) t = x

# if $\Gamma, x : \sigma \vdash t : \tau$ and $x \notin \mathcal{V}ar(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

#### Proof

## induction on definition of [x]t

(1)  $t = x \implies [x]t = 1$ 

# if $\Gamma$ , $\mathbf{x} : \sigma \vdash \mathbf{t} : \tau$ and $\mathbf{x} \notin \mathcal{V}ar(\Gamma)$ then $\Gamma \vdash [\mathbf{x}]\mathbf{t} : \sigma \rightarrow \tau$

#### Proof

induction on definition of [x]t

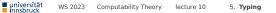
(1)  $t = x \implies [x]t = I \text{ and } \sigma = \tau$ 

# if $\Gamma, x : \sigma \vdash t : \tau$ and $x \notin \mathcal{V}ar(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

### Proof

induction on definition of [x]t

(1)  $t = x \implies [x]t = I$  and  $\sigma = \tau \implies \vdash I: \sigma \to \tau$ 

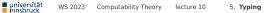


# if $\Gamma$ , $x : \sigma \vdash t : \tau$ and $x \notin Var(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

### Proof

induction on definition of [x]t

(1)  $t = x \implies [x]t = I \text{ and } \sigma = \tau \implies \vdash I: \sigma \to \tau \implies \Gamma \vdash I: \sigma \to \tau$ 



# if $\Gamma, x : \sigma \vdash t : \tau$ and $x \notin \mathcal{V}ar(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

### Proof

induction on definition of [x]t

① 
$$t = x \implies [x]t = I \text{ and } \sigma = \tau \implies \vdash I: \sigma \to \tau \implies \Gamma \vdash I: \sigma \to \tau$$

(2)  $x \notin Var(t) \implies [x]t = Kt$ 

# if $\Gamma$ , $\mathbf{x} : \sigma \vdash \mathbf{t} : \tau$ and $\mathbf{x} \notin \mathcal{V}ar(\Gamma)$ then $\Gamma \vdash [\mathbf{x}]\mathbf{t} : \sigma \rightarrow \tau$

### Proof

induction on definition of [x]t

① 
$$t = x \implies [x]t = I \text{ and } \sigma = \tau \implies \vdash I: \sigma \to \tau \implies \Gamma \vdash I: \sigma \to \tau$$

 $(2) x \notin \mathcal{V}ar(t) \implies [x]t = Kt \text{ and } \Gamma \vdash t : \tau$ 

# if $\Gamma, x : \sigma \vdash t : \tau$ and $x \notin Var(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

### Proof

induction on definition of [x]t

① 
$$t = x \implies [x]t = I \text{ and } \sigma = \tau \implies \vdash I: \sigma \to \tau \implies \Gamma \vdash I: \sigma \to \tau$$

(2)  $x \notin \mathcal{V}ar(t) \implies [x]t = Kt \text{ and } \Gamma \vdash t: \tau$ 

 $\vdash \mathbf{K}: \tau \to \sigma \to \tau$ 

# if $\Gamma, x : \sigma \vdash t : \tau$ and $x \notin \mathcal{V}ar(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

#### Proof

induction on definition of [x]t

① 
$$t = x \implies [x]t = I \text{ and } \sigma = \tau \implies \vdash I : \sigma \to \tau \implies \Gamma \vdash I : \sigma \to \tau$$

 $(2) x \notin \mathcal{V}ar(t) \implies [x]t = Kt \text{ and } \Gamma \vdash t: \tau$ 

 $\vdash \mathsf{K}: \tau \to \sigma \to \tau \implies \mathsf{\Gamma} \vdash \mathsf{K} t: \sigma \to \tau$ 

# if $\Gamma$ , $x : \sigma \vdash t : \tau$ and $x \notin Var(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

#### Proof

induction on definition of [x]t

① 
$$t = x \implies [x]t = I \text{ and } \sigma = \tau \implies \vdash I: \sigma \to \tau \implies \Gamma \vdash I: \sigma \to \tau$$

 $(2) x \notin \mathcal{V}ar(t) \implies [x]t = Kt \text{ and } \Gamma \vdash t : \tau$ 

$$\vdash \mathsf{K}: \tau \to \sigma \to \tau \implies \mathsf{\Gamma} \vdash \mathsf{K} t: \sigma \to \tau$$

**3**  $t = t_1 t_2 \implies [x]t = S([x]t_1)([x]t_2)$ 

# if $\Gamma$ , $x : \sigma \vdash t : \tau$ and $x \notin Var(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

#### Proof

induction on definition of [x]t

① 
$$t = x \implies [x]t = I \text{ and } \sigma = \tau \implies \vdash I: \sigma \to \tau \implies \Gamma \vdash I: \sigma \to \tau$$

 $(2) x \notin \mathcal{V}ar(t) \implies [x]t = Kt \text{ and } \Gamma \vdash t : \tau$ 

$$\vdash \mathsf{K}: \tau \to \sigma \to \tau \quad \Longrightarrow \quad \mathsf{\Gamma} \vdash \mathsf{K} t: \sigma \to \tau$$

 $(3) t = t_1 t_2 \implies [x]t = S([x]t_1)([x]t_2) \text{ and } \Gamma, x: \sigma \vdash t_1: \tau_1 \to \tau \text{ and } \Gamma, x: \sigma \vdash t_2: \tau_1$ 

# if $\Gamma, x : \sigma \vdash t : \tau$ and $x \notin Var(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

#### Proof

induction on definition of [x]t

① 
$$t = x \implies [x]t = I \text{ and } \sigma = \tau \implies \vdash I: \sigma \to \tau \implies \Gamma \vdash I: \sigma \to \tau$$

(2) 
$$x \notin Var(t) \implies [x]t = Kt$$
 and  $\Gamma \vdash t : \tau$ 

$$\vdash \mathsf{K}: \tau \to \sigma \to \tau \quad \Longrightarrow \quad \mathsf{\Gamma} \vdash \mathsf{K} t: \sigma \to \tau$$

(3)  $t = t_1 t_2 \implies [x]t = S([x]t_1)([x]t_2)$  and  $\Gamma, x : \sigma \vdash t_1 : \tau_1 \to \tau$  and  $\Gamma, x : \sigma \vdash t_2 : \tau_1$  $\Gamma \vdash [x]t_1 : \sigma \to \tau_1 \to \tau$  and  $\Gamma \vdash [x]t_2 : \sigma \to \tau_1$  by induction hypothesis

# if $\Gamma, x : \sigma \vdash t : \tau$ and $x \notin Var(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

#### Proof

induction on definition of [x]t

① 
$$t = x \implies [x]t = I \text{ and } \sigma = \tau \implies \vdash I: \sigma \to \tau \implies \Gamma \vdash I: \sigma \to \tau$$

$$(2) x \notin \mathcal{V}ar(t) \implies [x]t = Kt and \Gamma \vdash t : \tau$$

$$\vdash \mathsf{K}: \tau \to \sigma \to \tau \quad \Longrightarrow \quad \mathsf{\Gamma} \vdash \mathsf{K} t: \sigma \to \tau$$

(3)  $t = t_1 t_2 \implies [x]t = S([x]t_1)([x]t_2)$  and  $\Gamma, x : \sigma \vdash t_1 : \tau_1 \to \tau$  and  $\Gamma, x : \sigma \vdash t_2 : \tau_1$  $\Gamma \vdash [x]t_1 : \sigma \to \tau_1 \to \tau$  and  $\Gamma \vdash [x]t_2 : \sigma \to \tau_1$  by induction hypothesis  $\vdash S : (\sigma \to \tau_1 \to \tau) \to (\sigma \to \tau_1) \to \sigma \to \tau$ 

# if $\Gamma$ , $x : \sigma \vdash t : \tau$ and $x \notin Var(\Gamma)$ then $\Gamma \vdash [x]t : \sigma \rightarrow \tau$

#### Proof

induction on definition of [x]t

① 
$$t = x \implies [x]t = I \text{ and } \sigma = \tau \implies \vdash I: \sigma \to \tau \implies \Gamma \vdash I: \sigma \to \tau$$

$$(2) x \notin \mathcal{V}ar(t) \implies [x]t = Kt and \Gamma \vdash t:\tau$$

$$\vdash \mathsf{K}: \tau \to \sigma \to \tau \quad \Longrightarrow \quad \mathsf{\Gamma} \vdash \mathsf{K} t: \sigma \to \tau$$

(3)  $t = t_1 t_2 \implies [x]t = S([x]t_1)([x]t_2) \text{ and } \Gamma, x : \sigma \vdash t_1 : \tau_1 \to \tau \text{ and } \Gamma, x : \sigma \vdash t_2 : \tau_1$   $\Gamma \vdash [x]t_1 : \sigma \to \tau_1 \to \tau \text{ and } \Gamma \vdash [x]t_2 : \sigma \to \tau_1 \text{ by induction hypothesis}$  $\vdash S : (\sigma \to \tau_1 \to \tau) \to (\sigma \to \tau_1) \to \sigma \to \tau \implies \Gamma \vdash S([x]t_1)([x]t_2) : \sigma \to \tau$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

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if \Gamma \vdash t : \tau and t \rightarrow u then \Gamma \vdash u : \tau
```

(1) 
$$\mathbf{t} = |\mathbf{t_1} \to \mathbf{t_1} = \mathbf{u} \implies \vdash | : \sigma \to \tau \text{ and } \Gamma \vdash \mathbf{t_1} : \sigma$$



if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

(1) 
$$t = |t_1 \to t_1 = u \implies | \cdot | \cdot \sigma \to \tau$$
 and  $\Gamma \vdash t_1 : \sigma \implies \sigma = \tau$ 



if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

### Proof

### (1) $t = |t_1 \rightarrow t_1 = u \implies \vdash |: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1 : \sigma \implies \sigma = \tau \implies \Gamma \vdash u : \tau$



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if \Gamma \vdash t : \tau and t \rightarrow u then \Gamma \vdash u : \tau
```

### Proof

# (1) $t = It_1 \rightarrow t_1 = u \implies \vdash I: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \sigma \implies \sigma = \tau \implies \Gamma \vdash u: \tau$ (2) $t = Kt_1t_2 \rightarrow t_1 = u$



if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

- (1)  $t = |t_1 \to t_1 = u \implies \vdash |: \sigma \to \tau \text{ and } \Gamma \vdash t_1 : \sigma \implies \sigma = \tau \implies \Gamma \vdash u : \tau$
- (2)  $\mathbf{t} = \mathbf{K} \mathbf{t_1} \mathbf{t_2} \rightarrow \mathbf{t_1} = \mathbf{u} \implies \Gamma \vdash \mathbf{K} \mathbf{t_1} : \sigma \rightarrow \tau \text{ and } \Gamma \vdash \mathbf{t_2} : \sigma$

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

#### Proof

(1)  $t = |t_1 \to t_1 = u \implies \vdash |: \sigma \to \tau \text{ and } \Gamma \vdash t_1 : \sigma \implies \sigma = \tau \implies \Gamma \vdash u : \tau$ 

(2)  $t = K t_1 t_2 \rightarrow t_1 = u \implies \Gamma \vdash K t_1 : \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2 : \sigma$ 

 $\implies$   $\vdash$  K :  $\rho \rightarrow \sigma \rightarrow \tau$  and  $\Gamma \vdash t_1 : \rho$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

- (1)  $t = |t_1 \to t_1 = u \implies \vdash |: \sigma \to \tau \text{ and } \Gamma \vdash t_1 : \sigma \implies \sigma = \tau \implies \Gamma \vdash u : \tau$
- (2)  $t = K t_1 t_2 \rightarrow t_1 = u \implies \Gamma \vdash K t_1 : \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2 : \sigma$ 
  - $\implies$   $\vdash$  K :  $\rho \rightarrow \sigma \rightarrow \tau$  and  $\Gamma \vdash t_1 : \rho \implies \rho = \tau$

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

#### Proof

(1)  $t = |t_1 \to t_1 = u \implies \vdash |: \sigma \to \tau \text{ and } \Gamma \vdash t_1 : \sigma \implies \sigma = \tau \implies \Gamma \vdash u : \tau$ 

(2)  $t = K t_1 t_2 \rightarrow t_1 = u \implies \Gamma \vdash K t_1 : \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2 : \sigma$ 

 $\implies$   $\vdash$  K :  $\rho \rightarrow \sigma \rightarrow \tau$  and  $\Gamma \vdash t_1 : \rho \implies \rho = \tau \implies \Gamma \vdash u : \tau$ 



if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

### Proof

$$\textcircled{1} t = \mathsf{I} t_1 \to t_1 = u \quad \Longrightarrow \quad \vdash \mathsf{I} : \sigma \to \tau \text{ and } \Gamma \vdash t_1 : \sigma \quad \Longrightarrow \quad \sigma = \tau \quad \Longrightarrow \quad \Gamma \vdash u : \tau$$

(2) 
$$t = \mathsf{K} t_1 t_2 \rightarrow t_1 = u \implies \mathsf{\Gamma} \vdash \mathsf{K} t_1 : \sigma \rightarrow \tau \text{ and } \mathsf{\Gamma} \vdash t_2 : \sigma$$

$$\implies \vdash \mathsf{K}: \rho \to \sigma \to \tau \text{ and } \Gamma \vdash t_1: \rho \implies \rho = \tau \implies \Gamma \vdash u: \tau$$

**③**  $t = St_1t_2t_3 \rightarrow t_1t_3(t_2t_3) = u$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

$$\textcircled{1} t = \mathsf{I} t_1 \to t_1 = u \quad \Longrightarrow \quad \vdash \mathsf{I} : \sigma \to \tau \text{ and } \mathsf{\Gamma} \vdash t_1 : \sigma \quad \Longrightarrow \quad \sigma = \tau \quad \Longrightarrow \quad \mathsf{\Gamma} \vdash u : \tau$$

$$(2) t = \mathsf{K} t_1 t_2 \to t_1 = u \implies \mathsf{\Gamma} \vdash \mathsf{K} t_1 : \sigma \to \tau \text{ and } \mathsf{\Gamma} \vdash t_2 : \sigma$$

$$\implies \ \vdash \mathsf{K}: \rho \to \sigma \to \tau \text{ and } \mathsf{\Gamma} \vdash t_1: \rho \implies \rho = \tau \implies \mathsf{\Gamma} \vdash u: \tau$$

$$(3) t = \mathsf{S} t_1 t_2 t_3 \to t_1 t_3 (t_2 t_3) = u \implies \Gamma \vdash \mathsf{S} t_1 t_2 : \sigma \to \tau \text{ and } \Gamma \vdash t_3 : \sigma$$

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

$$\textcircled{1} t = \mathsf{I} t_1 \to t_1 = u \quad \Longrightarrow \quad \vdash \mathsf{I} : \sigma \to \tau \text{ and } \mathsf{\Gamma} \vdash t_1 : \sigma \quad \Longrightarrow \quad \sigma = \tau \quad \Longrightarrow \quad \mathsf{\Gamma} \vdash u : \tau$$

(2) 
$$t = K t_1 t_2 \rightarrow t_1 = u \implies \Gamma \vdash K t_1 : \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2 : \sigma$$

$$\implies \ \vdash \mathsf{K}: \rho \to \sigma \to \tau \text{ and } \mathsf{\Gamma} \vdash t_1: \rho \implies \rho = \tau \implies \mathsf{\Gamma} \vdash u: \tau$$

(3) 
$$t = \mathsf{S} t_1 t_2 t_3 \to t_1 t_3 (t_2 t_3) = u \implies \Gamma \vdash \mathsf{S} t_1 t_2 : \sigma \to \tau \text{ and } \Gamma \vdash t_3 : \sigma$$

$$\implies$$
  $\Gamma \vdash \mathsf{S} t_1 : \rho \rightarrow \sigma \rightarrow \tau$  and  $\Gamma \vdash t_2 : \rho$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

#### Proof

$$(1) t = |t_1 \to t_1 = u \implies \vdash |: \sigma \to \tau \text{ and } \Gamma \vdash t_1 : \sigma \implies \sigma = \tau \implies \Gamma \vdash u : \tau$$

2 
$$t = Kt_1t_2 \rightarrow t_1 = u \implies \Gamma \vdash Kt_1 : \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2 : \sigma$$

$$\implies \ \vdash \mathsf{K}: \rho \to \sigma \to \tau \text{ and } \mathsf{\Gamma} \vdash t_1: \rho \implies \rho = \tau \implies \mathsf{\Gamma} \vdash u: \tau$$

(3) 
$$t = \mathsf{S} t_1 t_2 t_3 \rightarrow t_1 t_3 (t_2 t_3) = u \implies \Gamma \vdash \mathsf{S} t_1 t_2 : \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_3 : \sigma$$

 $\implies \ \ \Gamma \vdash \mathsf{S} \, t_1: \rho \to \sigma \to \tau \text{ and } \Gamma \vdash t_2: \rho \quad \Longrightarrow \quad \vdash \mathsf{S}: \mu \to \rho \to \sigma \to \tau \text{ and } \Gamma \vdash t_1: \mu$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

(1) 
$$t = It_1 \rightarrow t_1 = u \implies \vdash I: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \sigma \implies \sigma = \tau \implies \Gamma \vdash u: \tau$$
  
(2)  $t = Kt_1t_2 \rightarrow t_1 = u \implies \Gamma \vdash Kt_1: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \sigma$   
 $\implies \vdash K: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \rho \implies \rho = \tau \implies \Gamma \vdash u: \tau$   
(3)  $t = St_1t_2t_3 \rightarrow t_1t_3(t_2t_3) = u \implies \Gamma \vdash St_1t_2: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_3: \sigma$   
 $\implies \Gamma \vdash St_1: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \rho \implies \vdash S: \mu \rightarrow \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \mu$   
 $\implies \rho = \sigma \rightarrow \rho_1 \text{ and } \mu = \sigma \rightarrow \rho_1 \rightarrow \tau$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

(1) 
$$t = It_1 \rightarrow t_1 = u \implies \vdash I: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \sigma \implies \sigma = \tau \implies \Gamma \vdash u: \tau$$
  
(2)  $t = Kt_1t_2 \rightarrow t_1 = u \implies \Gamma \vdash Kt_1: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \sigma$   
 $\implies \vdash K: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \rho \implies \rho = \tau \implies \Gamma \vdash u: \tau$   
(3)  $t = St_1t_2t_3 \rightarrow t_1t_3(t_2t_3) = u \implies \Gamma \vdash St_1t_2: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_3: \sigma$   
 $\implies \Gamma \vdash St_1: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \rho \implies \vdash S: \mu \rightarrow \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \mu$   
 $\implies \rho = \sigma \rightarrow \rho_1 \text{ and } \mu = \sigma \rightarrow \rho_1 \rightarrow \tau \implies \Gamma \vdash t_1t_3: \rho_1 \rightarrow \tau$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

(1) 
$$t = It_1 \rightarrow t_1 = u \implies \vdash I: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \sigma \implies \sigma = \tau \implies \Gamma \vdash u: \tau$$
  
(2)  $t = Kt_1t_2 \rightarrow t_1 = u \implies \Gamma \vdash Kt_1: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \sigma$   
 $\implies \vdash K: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \rho \implies \rho = \tau \implies \Gamma \vdash u: \tau$   
(3)  $t = St_1t_2t_3 \rightarrow t_1t_3(t_2t_3) = u \implies \Gamma \vdash St_1t_2: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_3: \sigma$   
 $\implies \Gamma \vdash St_1: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \rho \implies \vdash S: \mu \rightarrow \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \mu$   
 $\implies \rho = \sigma \rightarrow \rho_1 \text{ and } \mu = \sigma \rightarrow \rho_1 \rightarrow \tau \implies \Gamma \vdash t_1t_3: \rho_1 \rightarrow \tau \text{ and } \Gamma \vdash t_2t_3: \rho_1$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

(1) 
$$t = It_1 \rightarrow t_1 = u \implies \vdash I: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \sigma \implies \sigma = \tau \implies \Gamma \vdash u: \tau$$
  
(2)  $t = Kt_1t_2 \rightarrow t_1 = u \implies \Gamma \vdash Kt_1: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \sigma$   
 $\implies \vdash K: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \rho \implies \rho = \tau \implies \Gamma \vdash u: \tau$   
(3)  $t = St_1t_2t_3 \rightarrow t_1t_3(t_2t_3) = u \implies \Gamma \vdash St_1t_2: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_3: \sigma$   
 $\implies \Gamma \vdash St_1: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \rho \implies \vdash S: \mu \rightarrow \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \mu$   
 $\implies \rho = \sigma \rightarrow \rho_1 \text{ and } \mu = \sigma \rightarrow \rho_1 \rightarrow \tau \implies \Gamma \vdash t_1t_3: \rho_1 \rightarrow \tau \text{ and } \Gamma \vdash t_2t_3: \rho_1$   
 $\implies \Gamma \vdash u: \tau$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

(1) 
$$t = It_1 \rightarrow t_1 = u \implies \vdash I: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \sigma \implies \sigma = \tau \implies \Gamma \vdash u: \tau$$
  
(2)  $t = Kt_1t_2 \rightarrow t_1 = u \implies \Gamma \vdash Kt_1: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \sigma$   
 $\implies \vdash K: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \rho \implies \rho = \tau \implies \Gamma \vdash u: \tau$   
(3)  $t = St_1t_2t_3 \rightarrow t_1t_3(t_2t_3) = u \implies \Gamma \vdash St_1t_2: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_3: \sigma$   
 $\implies \Gamma \vdash St_1: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \rho \implies \vdash S: \mu \rightarrow \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \mu$   
 $\implies \rho = \sigma \rightarrow \rho_1 \text{ and } \mu = \sigma \rightarrow \rho_1 \rightarrow \tau \implies \Gamma \vdash t_1t_3: \rho_1 \rightarrow \tau \text{ and } \Gamma \vdash t_2t_3: \rho_1$   
 $\implies \Gamma \vdash u: \tau$ 

(4) 
$$t = t_1 t_2 \rightarrow u_1 t_2 = u$$
 with  $t_1 \rightarrow u_1$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

(1) 
$$t = |t_1 \to t_1 = u \implies \exists H : \sigma \to \tau \text{ and } \Gamma \vdash t_1 : \sigma \implies \sigma = \tau \implies \Gamma \vdash u : \tau$$
  
(2)  $t = \mathsf{K}t_1t_2 \to t_1 = u \implies \Gamma \vdash \mathsf{K}t_1 : \sigma \to \tau \text{ and } \Gamma \vdash t_2 : \sigma$   
 $\implies \vdash \mathsf{K} : \rho \to \sigma \to \tau \text{ and } \Gamma \vdash t_1 : \rho \implies \rho = \tau \implies \Gamma \vdash u : \tau$   
(3)  $t = \mathsf{S}t_1t_2t_3 \to t_1t_3(t_2t_3) = u \implies \Gamma \vdash \mathsf{S}t_1t_2 : \sigma \to \tau \text{ and } \Gamma \vdash t_3 : \sigma$   
 $\implies \Gamma \vdash \mathsf{S}t_1 : \rho \to \sigma \to \tau \text{ and } \Gamma \vdash t_2 : \rho \implies \vdash \mathsf{S} : \mu \to \rho \to \sigma \to \tau \text{ and } \Gamma \vdash t_1 : \mu$   
 $\implies \rho = \sigma \to \rho_1 \text{ and } \mu = \sigma \to \rho_1 \to \tau \implies \Gamma \vdash t_1t_3 : \rho_1 \to \tau \text{ and } \Gamma \vdash t_2t_3 : \rho_1$   
 $\implies \Gamma \vdash u : \tau$   
(4)  $t = t_1t_2 \to u_1t_2 = u \text{ with } t_1 \to u_1 \implies \Gamma \vdash t_1 : \sigma \to \tau \text{ and } \Gamma \vdash t_2 : \sigma$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

### Proof

(1) 
$$t = It_1 \rightarrow t_1 = u \implies \vdash I: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \sigma \implies \sigma = \tau \implies \Gamma \vdash u: \tau$$
  
(2)  $t = Kt_1t_2 \rightarrow t_1 = u \implies \Gamma \vdash Kt_1: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \sigma$   
 $\implies \vdash K: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \rho \implies \rho = \tau \implies \Gamma \vdash u: \tau$   
(3)  $t = St_1t_2t_3 \rightarrow t_1t_3(t_2t_3) = u \implies \Gamma \vdash St_1t_2: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_3: \sigma$   
 $\implies \Gamma \vdash St_1: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \rho \implies \vdash S: \mu \rightarrow \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \mu$   
 $\implies \rho = \sigma \rightarrow \rho_1 \text{ and } \mu = \sigma \rightarrow \rho_1 \rightarrow \tau \implies \Gamma \vdash t_1t_3: \rho_1 \rightarrow \tau \text{ and } \Gamma \vdash t_2t_3: \rho_1$   
 $\implies \Gamma \vdash u: \tau$   
(4)  $t = t_1t_2 \rightarrow u_1t_2 = u \text{ with } t_1 \rightarrow u_1 \implies \Gamma \vdash t_1: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \sigma$ 

 $\implies$   $\Gamma \vdash u_1 : \sigma \rightarrow \tau$  by induction hypothesis

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

(1) 
$$t = It_1 \rightarrow t_1 = u \implies \vdash I: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \sigma \implies \sigma = \tau \implies \Gamma \vdash u: \tau$$
  
(2)  $t = Kt_1t_2 \rightarrow t_1 = u \implies \Gamma \vdash Kt_1: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \sigma$   
 $\implies \vdash K: \rho \rightarrow \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_1: \rho \implies \rho = \tau \implies \Gamma \vdash u: \tau$   
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 $\implies \rho = \sigma \rightarrow \rho_1 \text{ and } \mu = \sigma \rightarrow \rho_1 \rightarrow \tau \implies \Gamma \vdash t_1t_3: \rho_1 \rightarrow \tau \text{ and } \Gamma \vdash t_2t_3: \rho_1$   
 $\implies \Gamma \vdash u: \tau$   
(4)  $t = t_1t_2 \rightarrow u_1t_2 = u \text{ with } t_1 \rightarrow u_1 \implies \Gamma \vdash t_1: \sigma \rightarrow \tau \text{ and } \Gamma \vdash t_2: \sigma$   
 $\implies \Gamma \vdash u: \tau$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

# Proof (cont'd)

(5)  $t = t_1 t_2 \rightarrow t_1 u_2 = u$  with  $t_2 \rightarrow u_2$ 



if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

## Proof (cont'd)

**(5)** 
$$\mathbf{t} = \mathbf{t_1}\mathbf{t_2} \to \mathbf{t_1}u_2 = u$$
 with  $\mathbf{t_2} \to u_2 \implies \Gamma \vdash \mathbf{t_1} : \sigma \to \tau$  and  $\Gamma \vdash \mathbf{t_2} : \sigma$ 

```
if \Gamma \vdash t : \tau and t \rightarrow u then \Gamma \vdash u : \tau
```

### Proof (cont'd)

**(5)**  $t = t_1 t_2 \rightarrow t_1 u_2 = u$  with  $t_2 \rightarrow u_2 \implies \Gamma \vdash t_1 : \sigma \rightarrow \tau$  and  $\Gamma \vdash t_2 : \sigma$ 

 $\implies$   $\Gamma \vdash u_2 : \sigma$  by induction hypothesis

```
if \Gamma \vdash t : \tau and t \rightarrow u then \Gamma \vdash u : \tau
```

### Proof (cont'd)

**(5)**  $t = t_1 t_2 \rightarrow t_1 u_2 = u$  with  $t_2 \rightarrow u_2 \implies \Gamma \vdash t_1 : \sigma \rightarrow \tau$  and  $\Gamma \vdash t_2 : \sigma$ 

 $\implies$   $\Gamma \vdash u_2 : \sigma$  by induction hypothesis  $\implies$   $\Gamma \vdash u : \tau$ 

if  $\Gamma \vdash t : \tau$  and  $t \rightarrow u$  then  $\Gamma \vdash u : \tau$ 

### Proof (cont'd)

**(5)**  $t = t_1 t_2 \rightarrow t_1 u_2 = u$  with  $t_2 \rightarrow u_2 \implies \Gamma \vdash t_1 : \sigma \rightarrow \tau$  and  $\Gamma \vdash t_2 : \sigma$ 

 $\implies$   $\Gamma \vdash u_2 : \sigma$  by induction hypothesis  $\implies$   $\Gamma \vdash u : \tau$ 

#### Definition

CL-term t with  $Var(t) = \{x_1, \ldots, x_n\}$  is typable if

 $x_1: \rho_1, \ldots, x_n: \rho_n \vdash t: \tau$ 

for some types  $\rho_1, \ldots, \rho_n, \tau$ 

# Outline

- **1. Summary of Previous Lecture**
- 2. Arithmetization
- 3. Second Fixed Point Theorem
- 4. Undecidability
- 5. Typing
- 6. Summary

### **Important Concepts**

- ▶ *「t* ¬
- arithmetization
- ► C
- conversion-closed
- ▶ dec(n)
- ▶ enc(n)

- $\blacktriangleright \ \Gamma \vdash t : \tau$
- ▶ g(t)
- Gödel number
- recursive separability
- SN
- subject reduction

- ► T
- ► TA
- type
- type assignment
- type constant
- $\triangleright$  V

### Important Concepts

- ▶ *「t* ¬
- arithmetization
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- $\triangleright$  V

# homework for December 11