

Certifying Confluence of Almost Orthogonal CTRSs via Exact Tree Automata Completion*

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1st FSCD

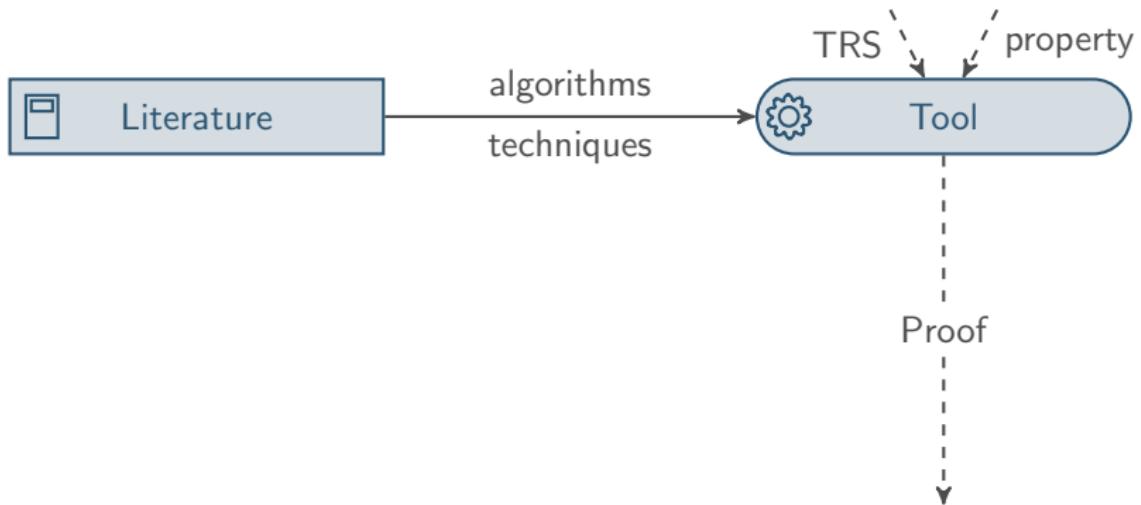
*Supported by the Austrian Science Fund (FWF): P27502

Outline

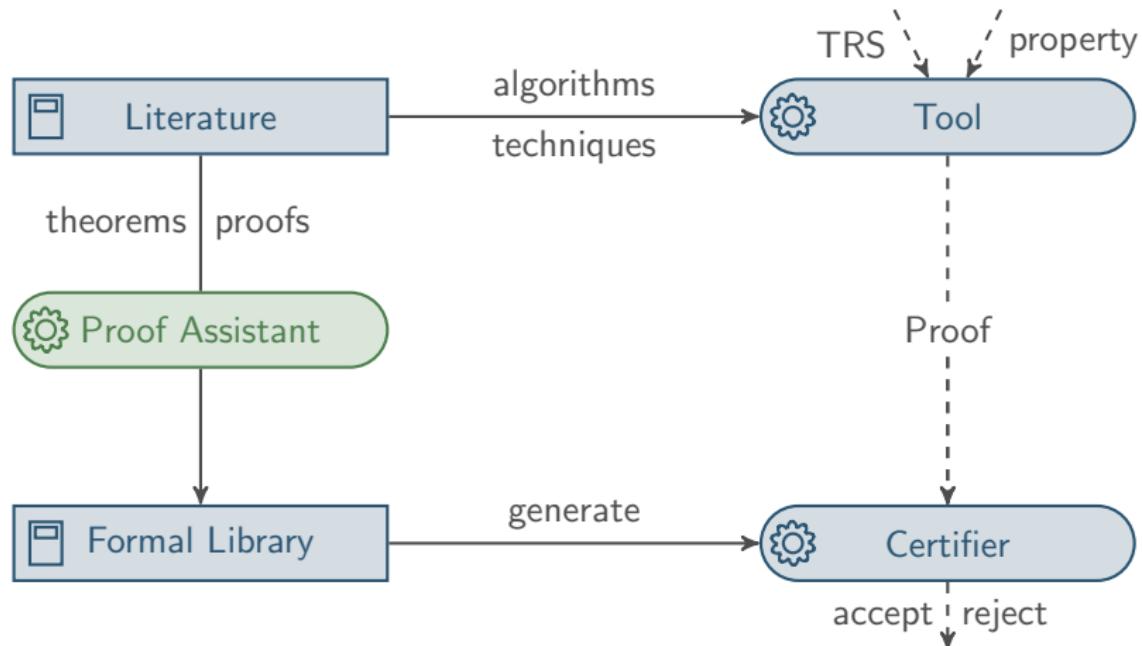
- The Big Picture
- Conditional Term Rewriting & Confluence
- Infeasibility & Tree Automata
- Certification
- Conclusion

The Big Picture

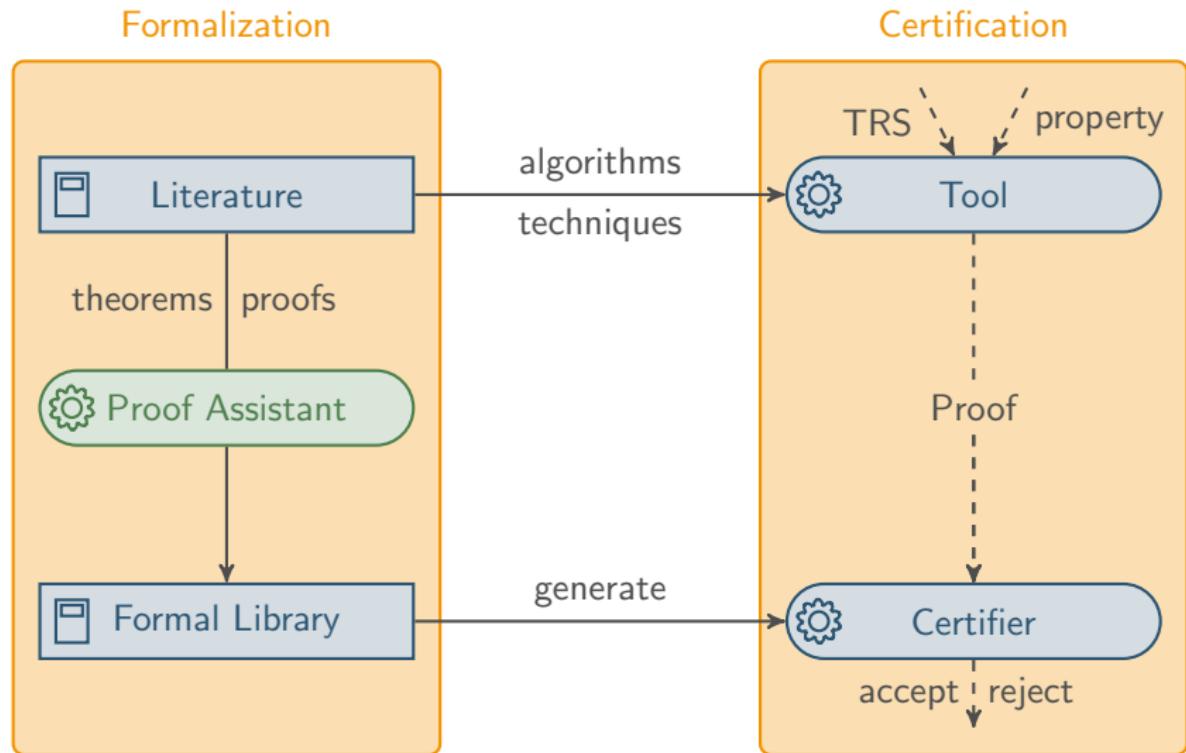
The State of the Art



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The Fruits of Formalization & Certification

- Understand, clarify, correct *literature*

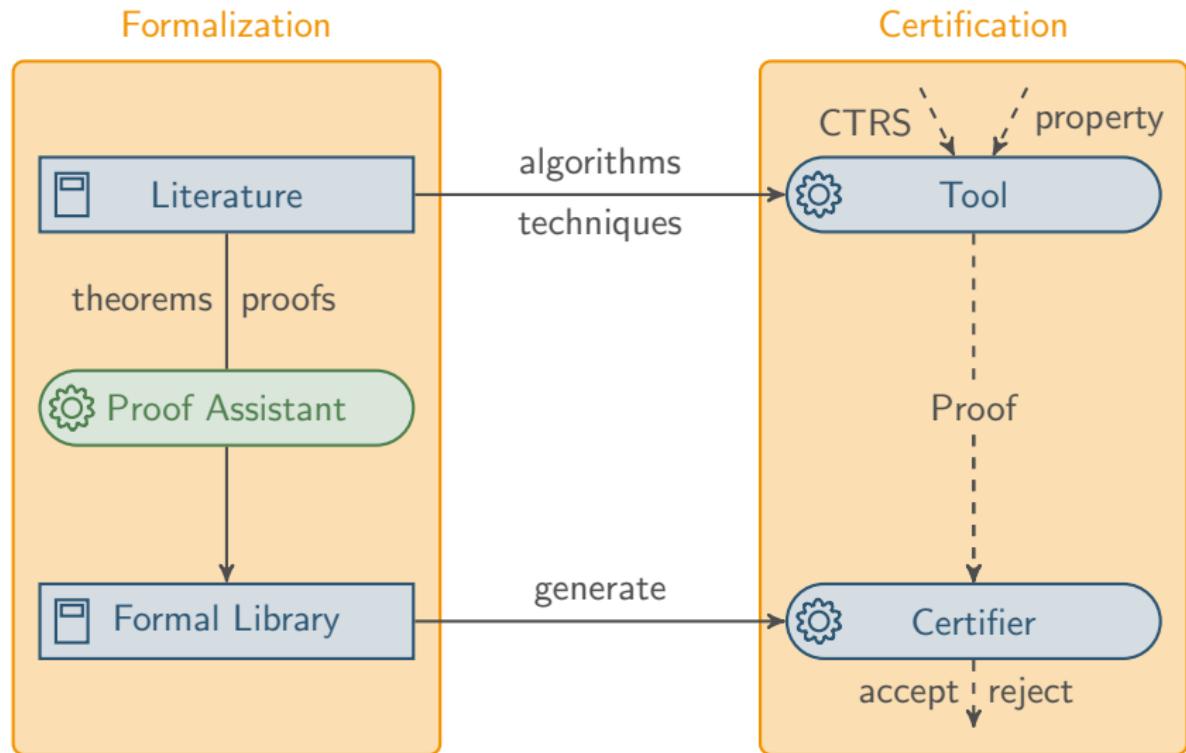
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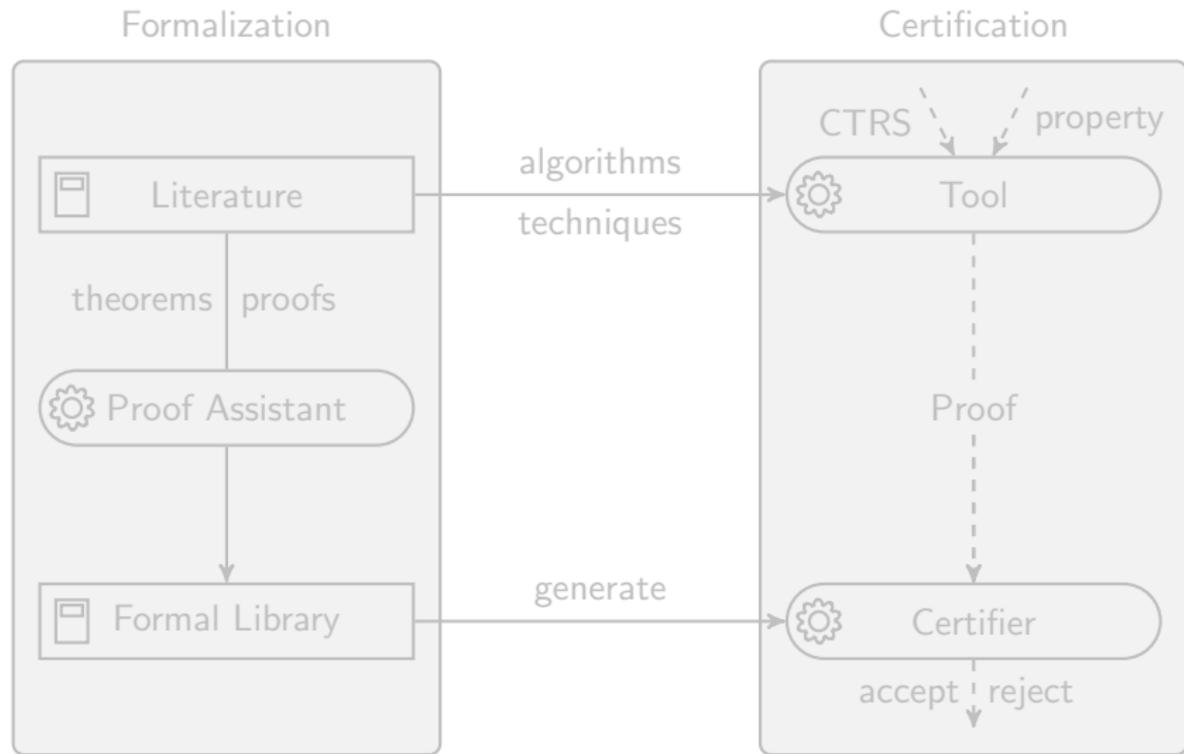
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- Expose errors and increase *reliability* of tools

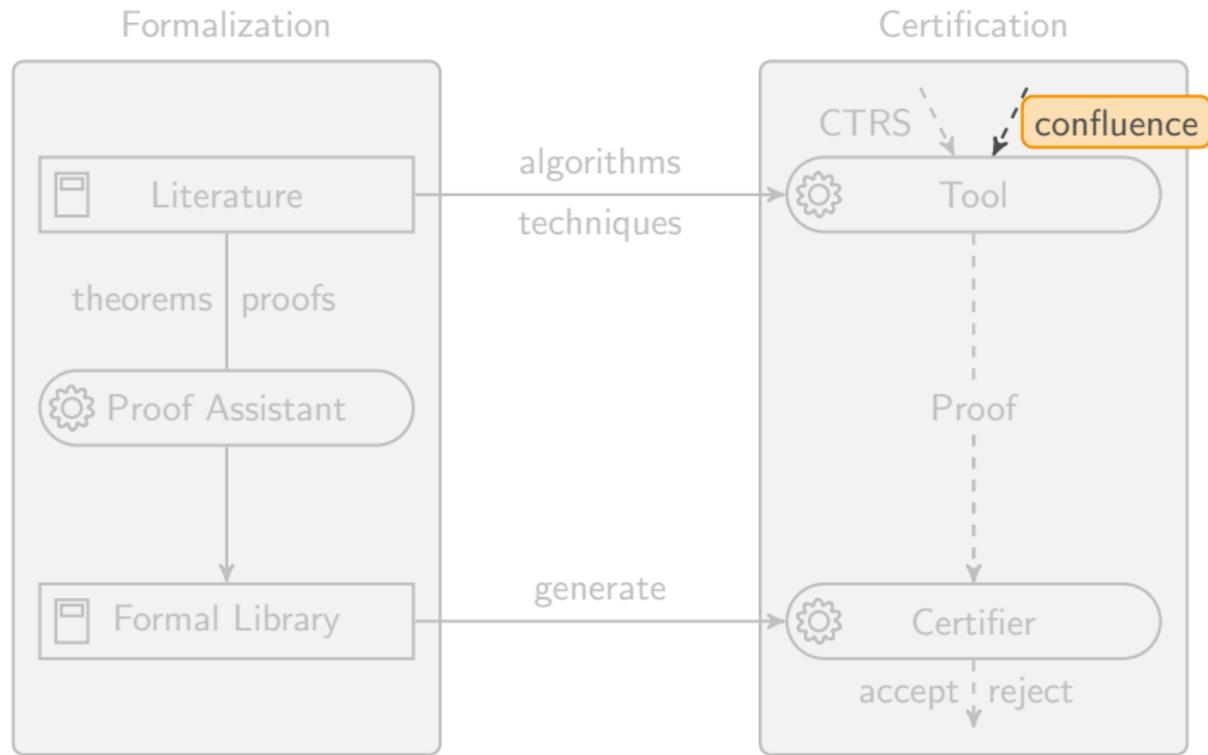
The Vision



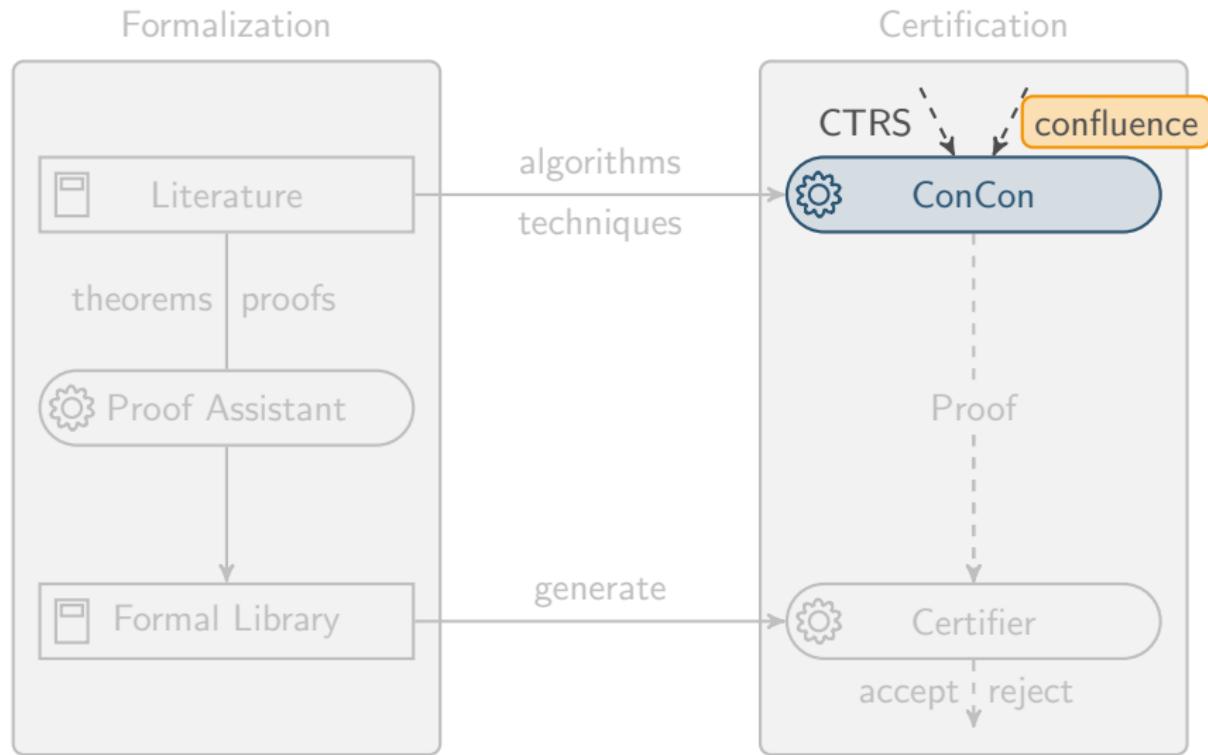
Our Contribution



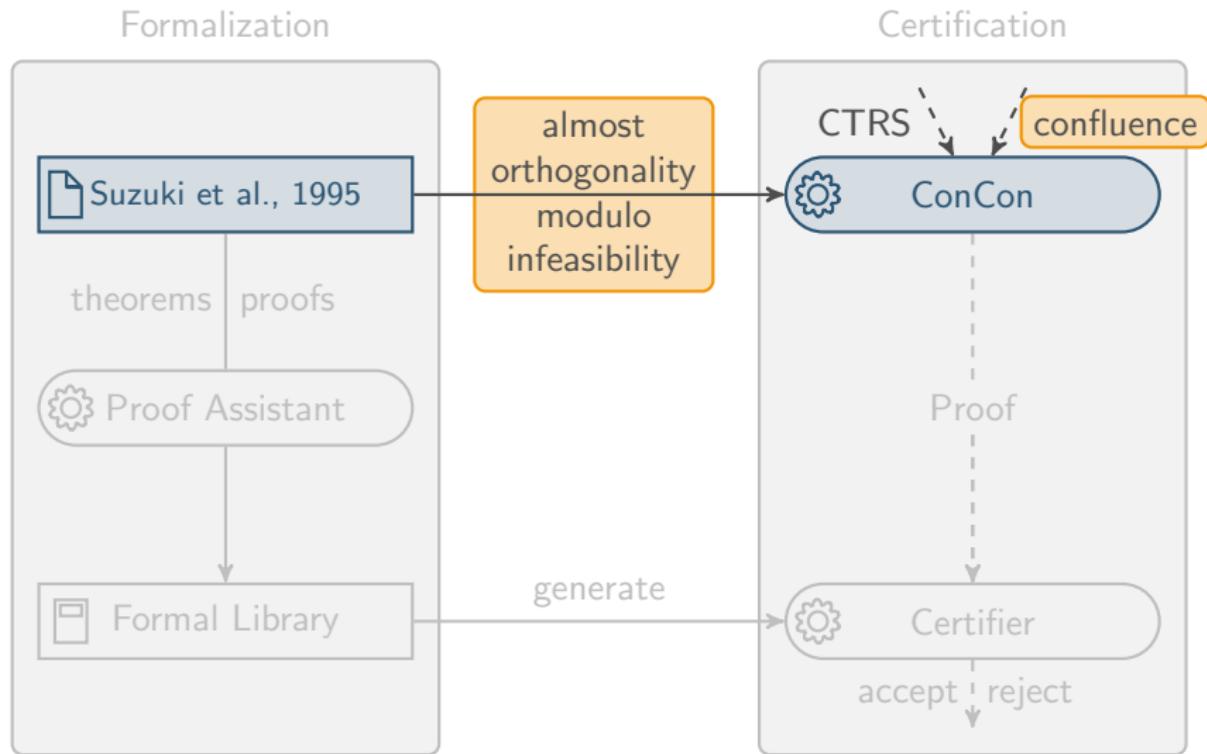
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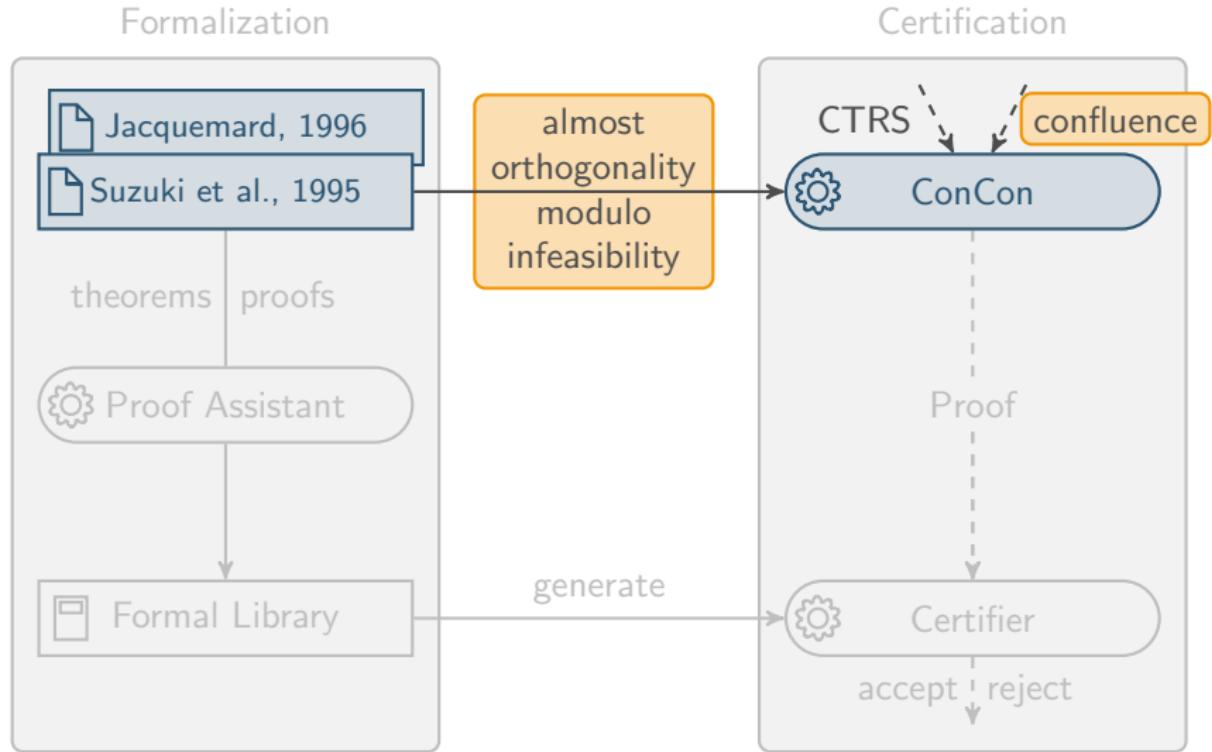
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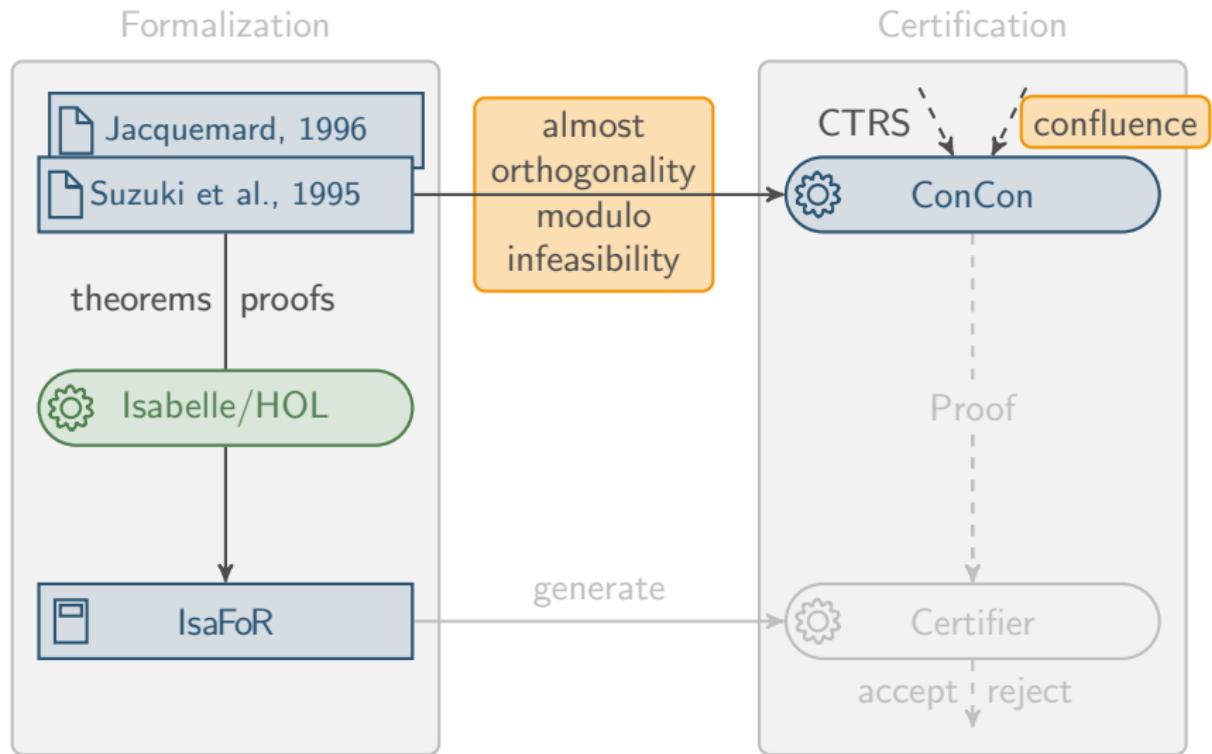
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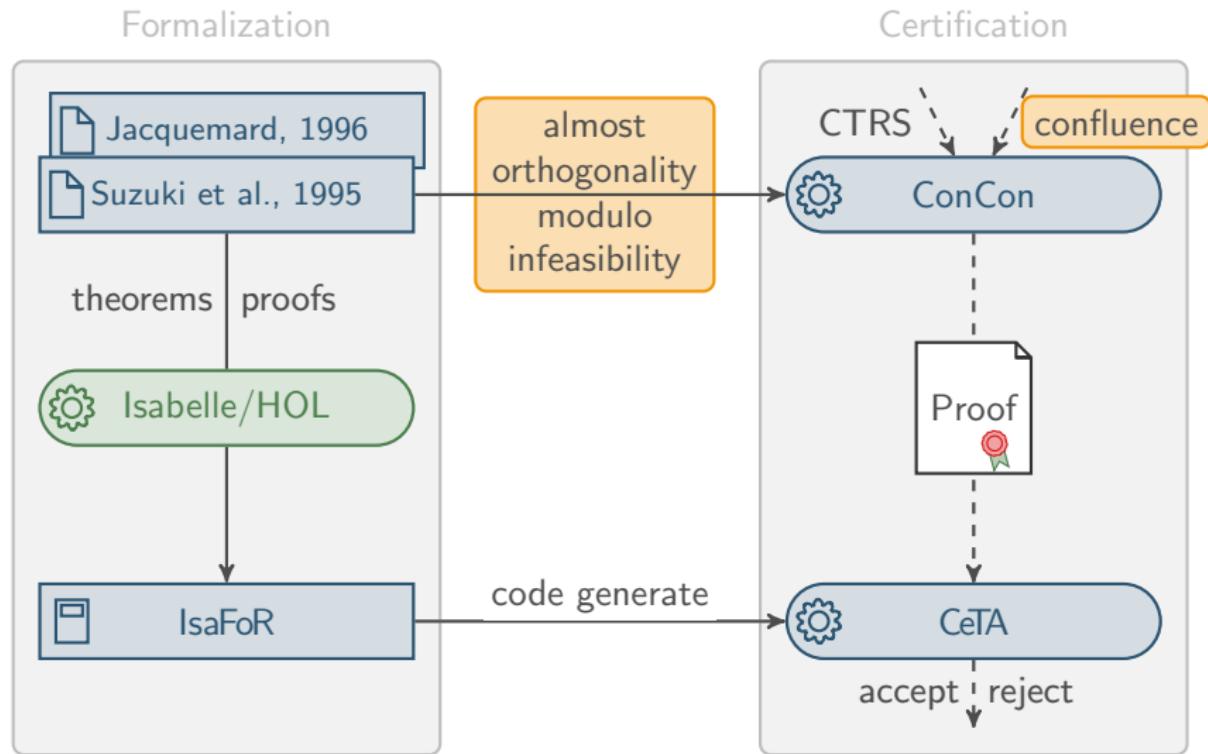
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Conditional Term Rewriting & Confluence

Conditional Term Rewriting

Basic definitions

- **conditional rewrite rule:** $\ell \rightarrow r \Leftarrow s_1 \approx t_1, \dots, s_n \approx t_n$

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- given CTRS \mathcal{R} , define TRS of level n , \mathcal{R}_n , inductively:
 $\mathcal{R}_0 = \emptyset$
 $\mathcal{R}_{n+1} = \{\ell\sigma \rightarrow r\sigma \mid \ell \rightarrow r \Leftarrow c \in \mathcal{R} \wedge \forall s \approx t \in c. s\sigma \rightarrow_{\mathcal{R}_n}^* t\sigma\}$

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- **conditional rewrite relation:** $s \rightarrow_{\mathcal{R}} t$ iff $s \rightarrow_{\mathcal{R}_n} t$ for some n

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Original Theorem from the Literature

Theorem [Suzuki, Middeldorp, Ida (RTA 1995)]

Oriented 3-CTRSs are level-confluent if they are

- Orthogonal,
- Properly Oriented, and
- Right-stable.

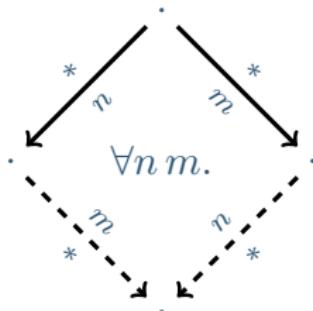
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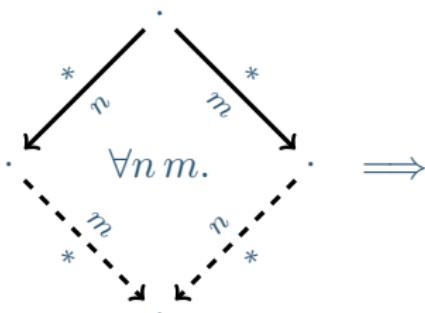
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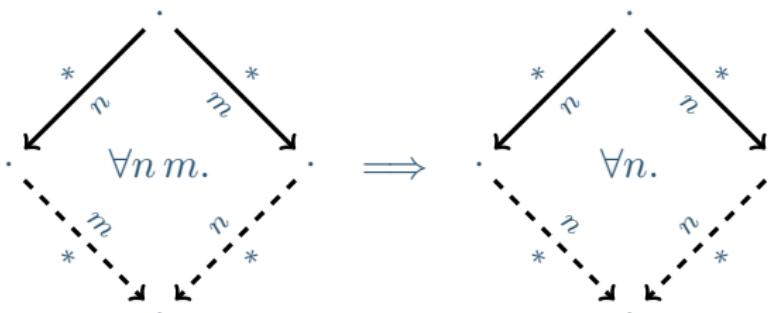
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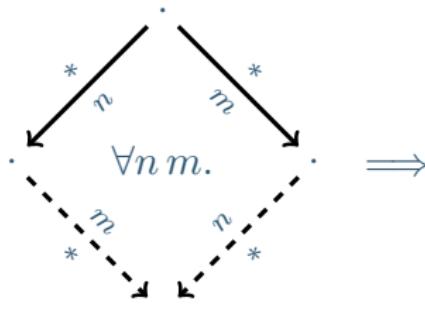
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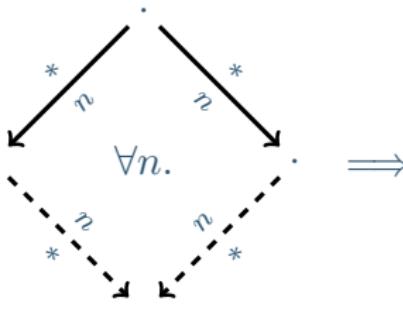
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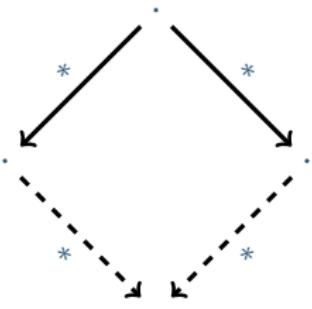
level-commutation



level-confluence



confluence



Orthogonality

Left-linear CTRS

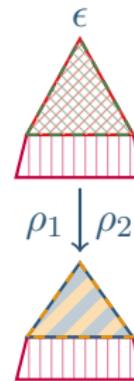
$$\rho_1 : l_1 \rightarrow r_1 \Leftarrow c_1$$

mgu
 μ



$$\rho_2 : l_2 \rightarrow r_2 \Leftarrow c_2$$

non-critical



ϵ

$\rho_1 \downarrow \rho_2$

Orthogonality

Left-linear CTRS

$$\rho_1 : \begin{array}{c} \text{red triangle} \\ l_1 \end{array} \rightarrow \begin{array}{c} \text{blue triangle} \\ r_1 \end{array} \Leftarrow c_1$$

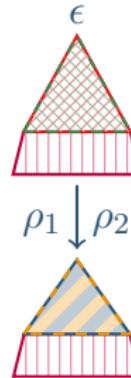
Example

$$f(x) \rightarrow g(y) \Leftarrow x \approx y$$

mgu
 μ


$$\rho_2 : \begin{array}{c} \text{green triangle} \\ l_2 \end{array} \rightarrow \begin{array}{c} \text{yellow triangle} \\ r_2 \end{array} \Leftarrow c_2$$

non-critical



Almost Orthogonality

Left-linear CTRS

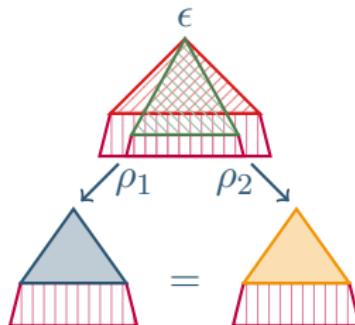
$$\rho_1 : l_1 \rightarrow r_1 \Leftarrow c_1$$

mgu
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$$\rho_2 : l_2 \rightarrow r_2 \Leftarrow c_2$$

trivial

$$\epsilon$$

$$\rho_1 \quad \rho_2$$
$$=$$

Almost Orthogonality

Left-linear CTRS

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Example

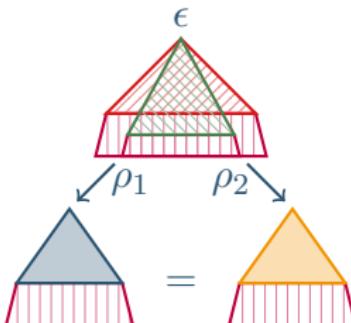
$$f(a, x) \rightarrow a$$

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$$f(a, a)$$

 $a \swarrow \quad \searrow a$

trivial



Almost Orthogonality modulo Infeasibility

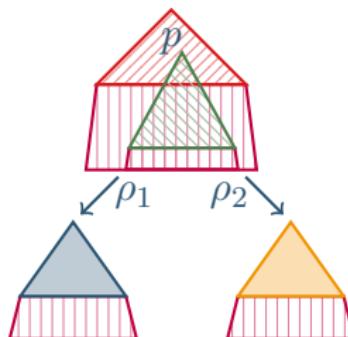
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infeasible



$$\nexists \sigma \text{ n. } n, \sigma \vdash c_1\mu, c_2\mu$$

Almost Orthogonality modulo Infeasibility

Left-linear CTRS

$$\rho_1 : \triangle{l_1} \rightarrow \triangle{r_1} \Leftarrow c_1$$

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 μ


$$\rho_2 : \triangle{l_2} \rightarrow \triangle{r_2} \Leftarrow c_2$$

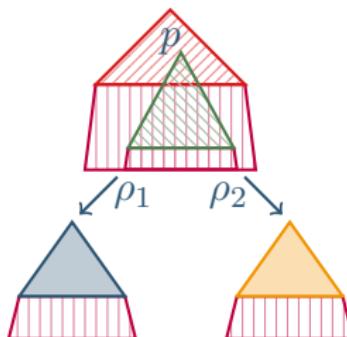
Example

$$f(x) \rightarrow a \Leftarrow x \approx a$$

$$f(x) \rightarrow b \Leftarrow x \approx b$$

$$\begin{array}{ccc} f(x) & & \\ \swarrow & & \searrow \\ a & & b \\ x \approx a, x \approx b & & \end{array}$$

infeasible



$$\nexists \sigma \ n. n, \sigma \vdash c_1 \mu, c_2 \mu$$

Almost Orthogonality modulo Infeasibility

Left-linear CTRS

$$\rho_1 : \triangle{l_1} \rightarrow \triangle{r_1} \Leftarrow c_1$$

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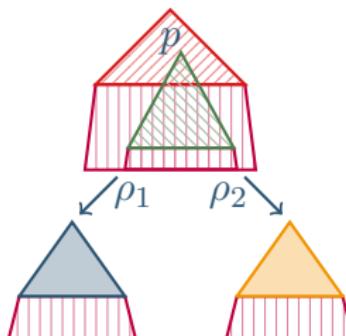
$$f(x) \rightarrow b \Leftarrow x \approx b$$

$$\begin{array}{ccc} f(x) & & \\ \swarrow & & \searrow \\ a & & b \end{array}$$

$$x \approx a, x \approx b$$

$$\forall m n. (\frac{\leftarrow^*}{m} \cdot \frac{*}{n} \subseteq \frac{*}{n} \cdot \frac{\leftarrow^*}{m}) \implies \nexists \sigma. m, \sigma \vdash c_1 \mu \wedge n, \sigma \vdash c_2 \mu)$$

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$$\nexists n \sigma. \text{cs}(x, x)\sigma \xrightarrow[n]{*} \text{cs}(a, b)\sigma \quad \text{tcap}(\text{cs}(x, x)) = \text{cs}(y, z) \sim \text{cs}(a, b)$$

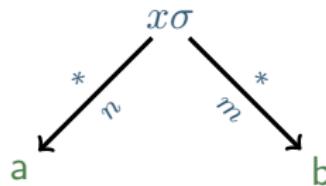
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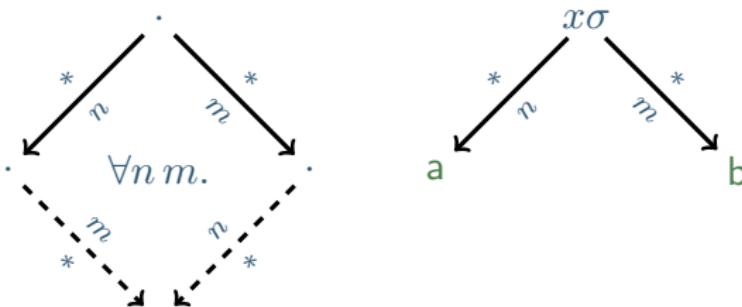
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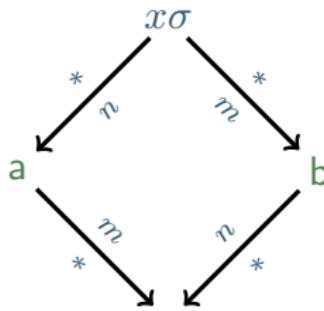
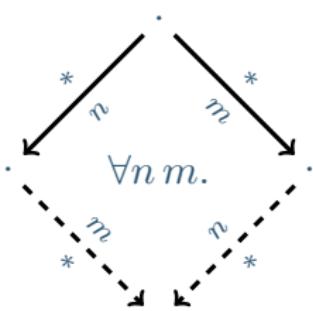
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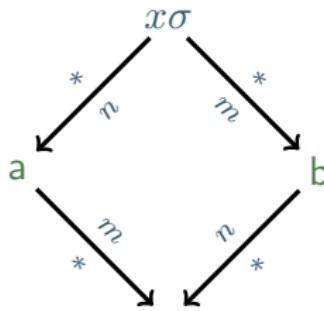
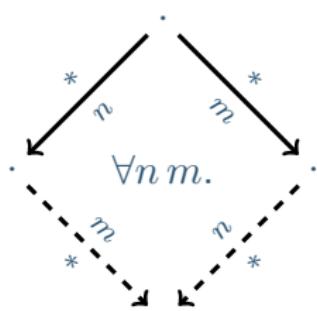
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$$\nexists \text{tcap}(a) \not\sim \text{tcap}(b)$$

Formalized Theorem

Theorem

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- Orthogonal,
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Formalized Theorem

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Oriented 3-CTRSs are confluent if they are

- Almost Orthogonal modulo infeasibility,
- Extended properly oriented, and
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Infeasibility & Tree Automata

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- Unification (tcap)
- Tree automata techniques

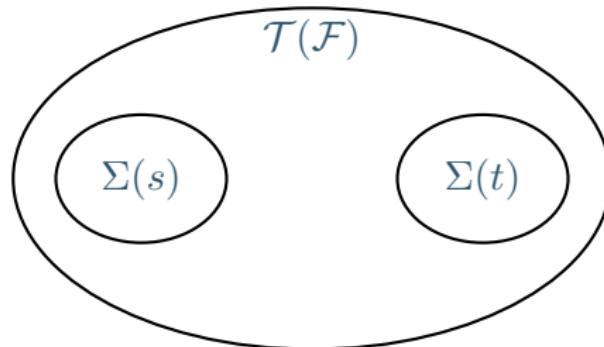
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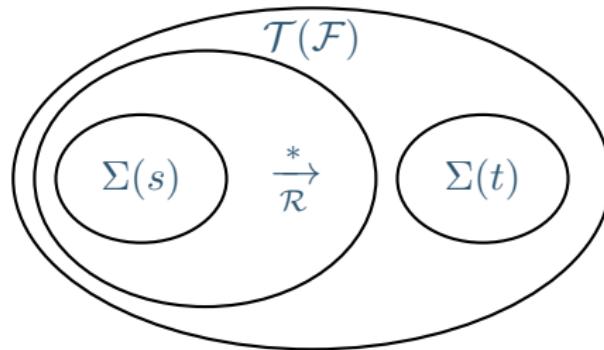
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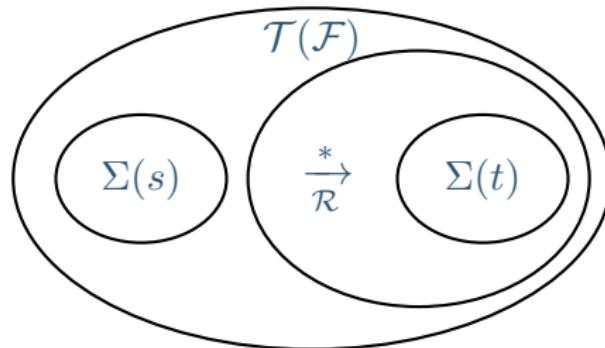
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- language: $L(\mathcal{A}) = \{t \in \mathcal{T}(\mathcal{F}) \mid \exists q \in Q_f. t \xrightarrow{\Delta}^* q\}$

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Example

$$f(\alpha) \rightarrow \alpha$$

$$a \rightarrow \alpha$$

$$L(\mathcal{A}) = f^n(a)$$

Ancestor Automaton

ground-instance transitions

states: $[x] = \square$, $[f(t_1, \dots, t_n)] = f([t_1], \dots, [t_n])$

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$$\Delta_t = \begin{cases} \{f([t_1], \dots, [t_n]) \rightarrow [t]\} \cup \bigcup_{1 \leq i \leq n} \Delta_{t_i} & \text{if } t = f(t_1, \dots, t_n) \\ \{f(\square, \dots, \square) \rightarrow \square \mid f \in \mathcal{F}\} & \text{otherwise} \end{cases}$$

Ancestor Automaton

ground-instance transitions

states: $[x] = \square$, $[f(t_1, \dots, t_n)] = f([t_1], \dots, [t_n])$

$$\Delta_t = \begin{cases} \{f([t_1], \dots, [t_n]) \rightarrow [t]\} \cup \bigcup_{1 \leq i \leq n} \Delta_{t_i} & \text{if } t = f(t_1, \dots, t_n) \\ \{f(\square, \dots, \square) \rightarrow \square \mid f \in \mathcal{F}\} & \text{otherwise} \end{cases}$$

$\text{anc}_{\mathcal{R}}(\mathcal{A})$

Given TA $\mathcal{A} = \langle \mathcal{F}, Q, Q_f, \Delta \rangle$ and linear, growing TRS \mathcal{R} :

Ancestor Automaton

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$$\Delta \cup \bigcup_{\ell \rightarrow r \in \mathcal{R}} \Delta_\ell \quad \frac{f(\ell_1, \dots, \ell_n) \rightarrow r \in \mathcal{R} \quad r\theta \rightarrow_{\Delta_k}^* q}{f(q_1, \dots, q_n) \rightarrow q \in \Delta_{k+1}} \quad (\dagger)$$

if $\ell_i \in \mathcal{V}(r)$ then $q_i = \ell_i\theta$ else $q_i = [\ell_i]$

Non-reachability via Ancestor Automaton

Theorem [cf. Jacquemard (RTA 1996)]

Given TA \mathcal{A} and linear, growing TRS \mathcal{R} the language of $\text{anc}_{\mathcal{R}}(\mathcal{A})$ is exactly the set of \mathcal{R} -ancestors of $L(\mathcal{A})$.

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Lemma (Non-reachability via $\text{anc}_{\mathcal{R}}(\mathcal{A})$)

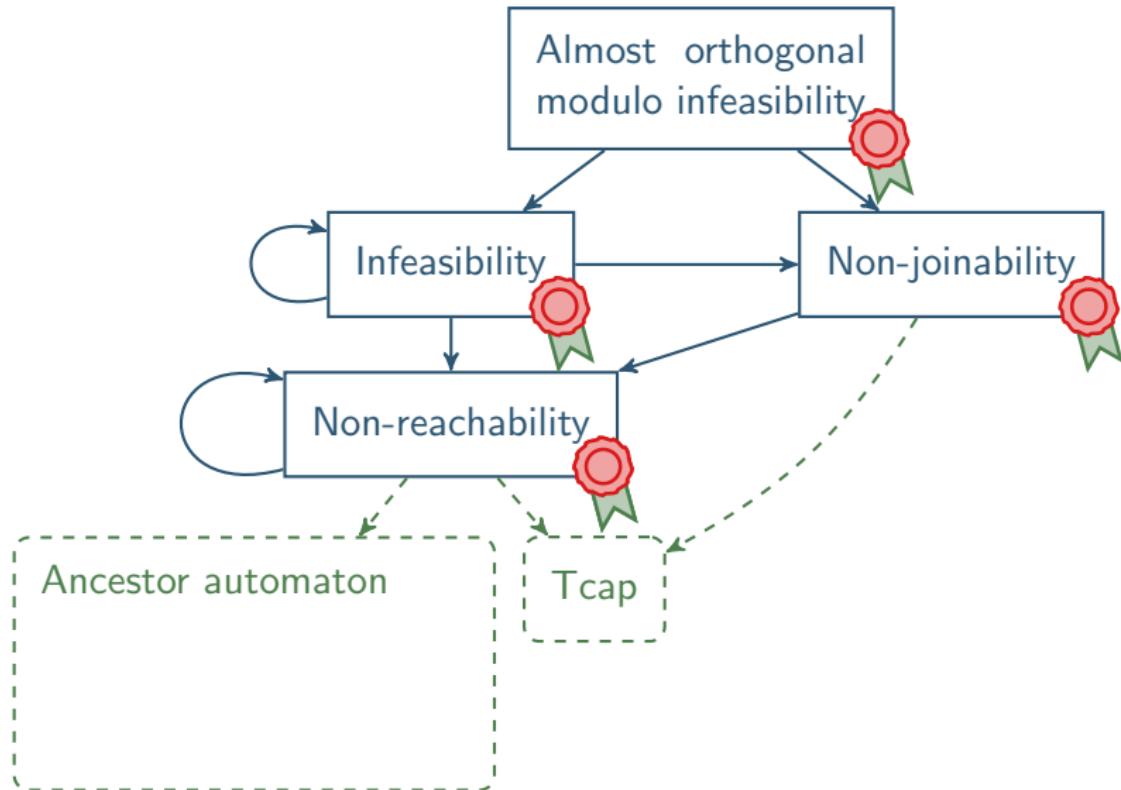
For linear, growing TRS \mathcal{R} if

$$L(\mathcal{A}_{\Sigma(s)} \cap \text{anc}_{\mathcal{R}}(\mathcal{A}_{\Sigma(t)})) = \emptyset$$

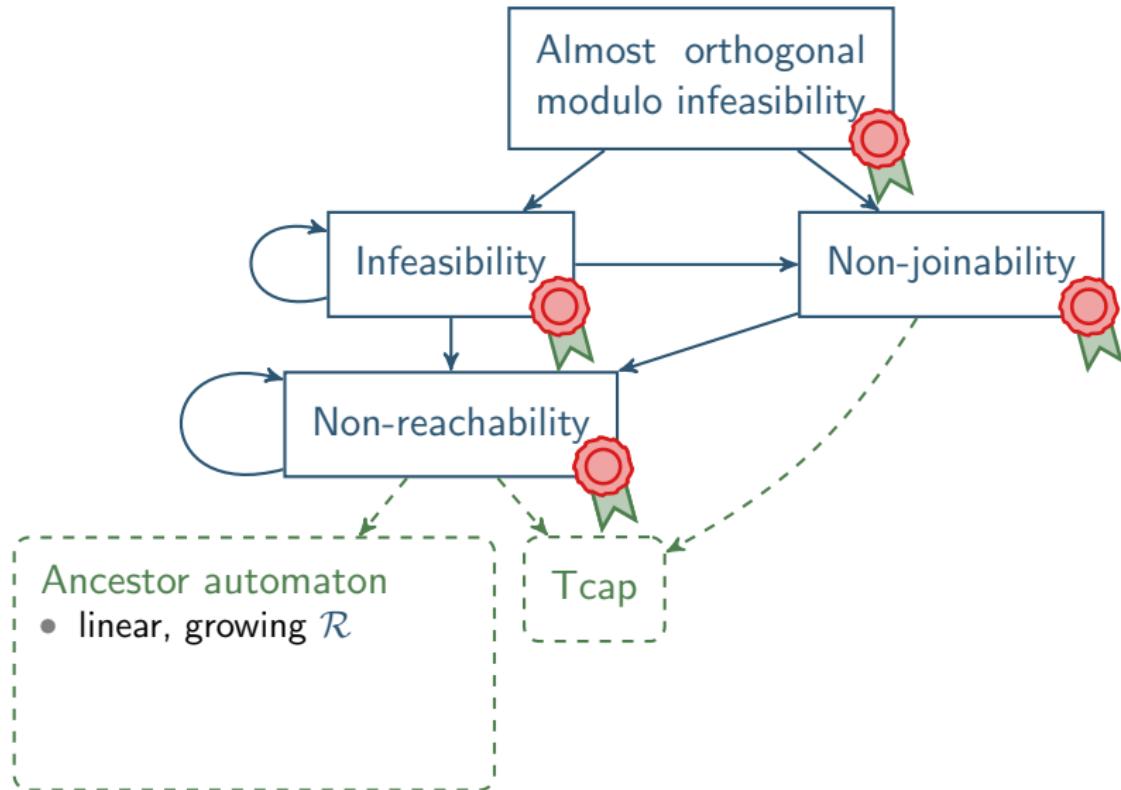
then $t\tau$ is not reachable from $s\sigma$ for any σ, τ .

Certification

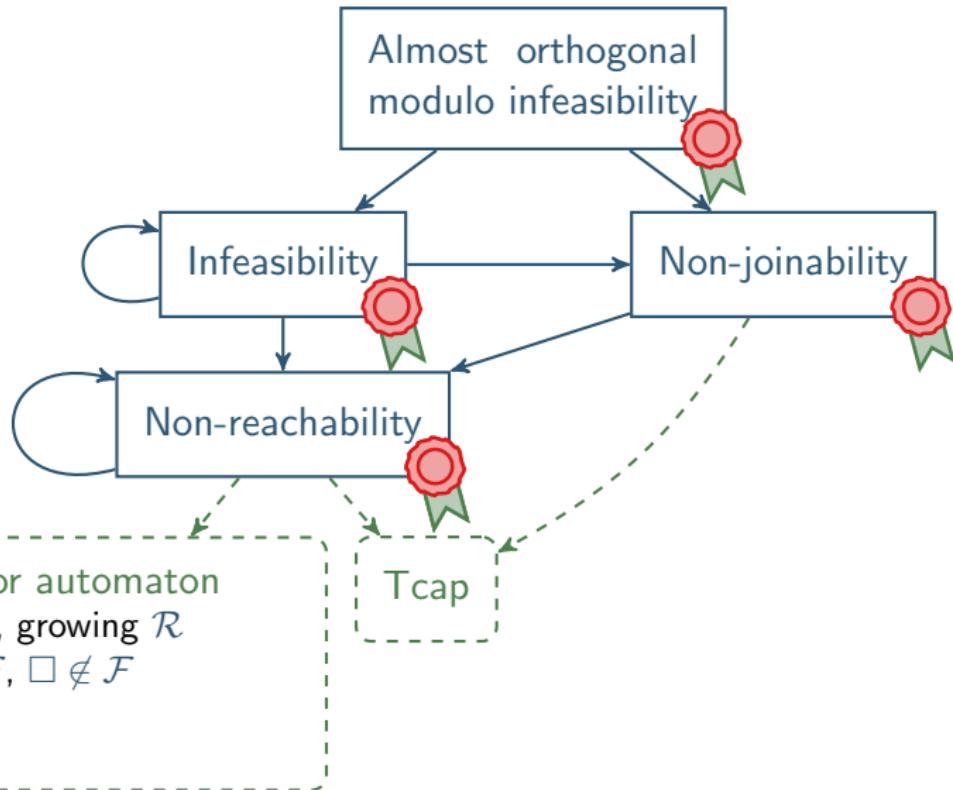
Certification Problem Format



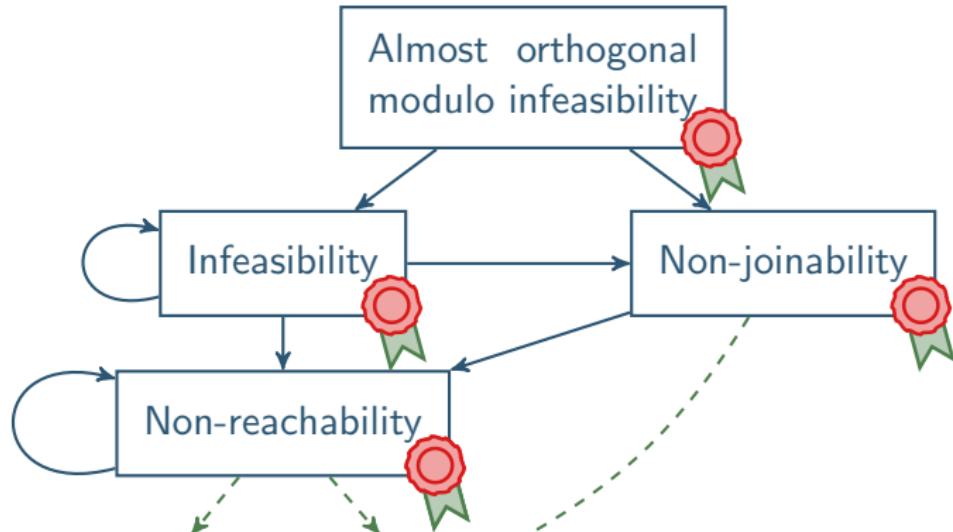
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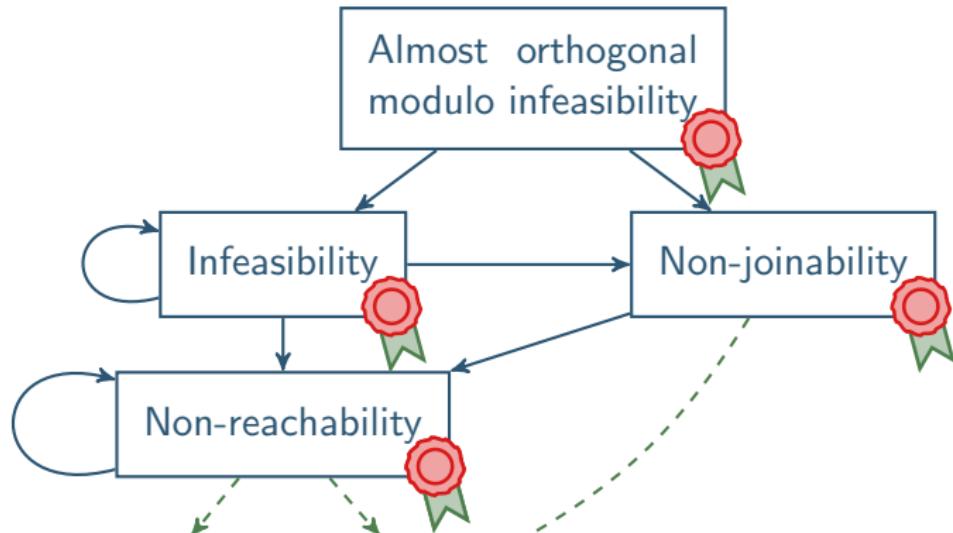
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Ancestor automaton

- linear, growing \mathcal{R}
- $a \in \mathcal{F}, \square \notin \mathcal{F}$
- $L(\text{anc}_{\mathcal{R}}(\mathcal{A}_{\Sigma(t)})) \subseteq L(\mathcal{A})$

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Conclusion

Summary & Future Work

- Confluence & non-reachability formalization in IsaFoR ($\sim 6,600$ LoI)
- Implemented techniques in ConCon
- Extended CPF format of CeTA

Summary & Future Work

Confluence (*82 CTRSs from Cops*)

	uncert	cert	2 cert	2+3	cert+
✓	47	23	32	35	
✗	15	-	-	-	
?	20	59	50	47	

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Non-reachability (412,829 potential dependency graph edges from TPDB)

	1s	3s	10s
✓	10,217	24,291	43,364

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