

SAT Solving for Termination Analysis with Polynomial Interpretations*

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1 Termination of TRSs and Polynomial Interpretations

Most termination methods for TRSs transform the termination problem into a set of inequalities between terms. For example, a classical approach is to generate inequalities $\ell \succ r$ for all rules $\ell \rightarrow r$ or, if one uses the dependency (DP) framework [1, 3, 5], then one generates strict inequalities for the DPs and non-strict ones for the usable rules. Consider the following example for subtraction.

$$\begin{array}{ll} \mathfrak{p}(0) \rightarrow 0 & \text{minus}(x, 0) \rightarrow x \\ \mathfrak{p}(\mathfrak{s}(x)) \rightarrow x & \text{minus}(x, \mathfrak{s}(y)) \rightarrow \text{minus}(\mathfrak{p}(x), y) \end{array}$$

For the DP of the recursive `minus`-call we get the following constraints. Here, M is the tuple-symbol of `minus`.

$$\mathfrak{p}(0) \succsim 0 \quad (1) \quad \mathfrak{p}(\mathfrak{s}(x)) \succsim x \quad (2) \quad M(x, \mathfrak{s}(y)) \succ M(\mathfrak{p}(x), y) \quad (3)$$

A popular method to search for relations \succ and \succsim automatically are *polynomial interpretations* [8]. A polynomial interpretation \mathcal{Pol} maps each n -ary function symbol f to a polynomial $f_{\mathcal{Pol}}$ over n variables x_1, \dots, x_n with coefficients from $\mathbb{N} = \{0, 1, 2, \dots\}$. It is extended to a mapping $[\cdot]_{\mathcal{Pol}}$ on terms where $[x]_{\mathcal{Pol}} = x$ for variables x and $[f(t_1, \dots, t_n)]_{\mathcal{Pol}} = f_{\mathcal{Pol}}\{x_1/[t_1]_{\mathcal{Pol}}, \dots, x_n/[t_n]_{\mathcal{Pol}}\}$. We often write $[\cdot]$ if \mathcal{Pol} is clear from the context. Now a term u is greater (resp. greater-equal) than v iff $[u] \geq [v] + 1$ (resp. $[u] \geq [v]$) holds for all instantiations of the variables with natural numbers. For instance, the constraints of the example are satisfied using the polynomial interpretation \mathcal{Pol}_1 with $M_{\mathcal{Pol}_1} = x_2$, $\mathfrak{p}_{\mathcal{Pol}_1} = x_1$, $\mathfrak{s}_{\mathcal{Pol}_1} = x_1 + 1$, and $0_{\mathcal{Pol}_1} = 0$. Thus, termination of the example is proved.

To find such interpretations automatically, one starts with an *abstract* polynomial interpretation. In the linear case we obtain

$$f_{\mathcal{Pol}} = f_0 + f_1x_1 + \dots + f_nx_n \quad \text{for each } f \text{ with arity } n \quad (4)$$

where the coefficients f_i are left open. Then one translates the term constraints into polynomial constraints. In the example we obtain

$$\mathfrak{p}_0 + \mathfrak{p}_1 0_0 \geq 0_0 \quad (5) \quad (\mathfrak{p}_0 + \mathfrak{p}_1 \mathfrak{s}_0) + (\mathfrak{p}_1 \mathfrak{s}_1) * x \geq x \quad (6)$$

$$(\mathfrak{M}_0 + \mathfrak{M}_2 \mathfrak{s}_0) + \mathfrak{M}_1 * x + \mathfrak{M}_2 \mathfrak{s}_1 * y \geq (\mathfrak{M}_0 + \mathfrak{M}_1 \mathfrak{p}_0 + 1) + \mathfrak{M}_1 \mathfrak{p}_1 * x + \mathfrak{M}_2 * y \quad (7)$$

Next one simplifies these constraints by deleting the variables x, y, \dots that are

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(implicitly) universally quantified. To this end, instead of an inequality between polynomials we only compare the respective coefficients (“absolute positiveness” [7]). In the example, the resulting constraints are (5), (8) and (9) (using $x = 0 + 1 * x$), and (10) – (12).

$$\begin{aligned} p_0 + p_1 s_0 &\geq 0 & (8) & & p_1 s_1 &\geq 1 & (9) \\ M_2 s_0 &\geq M_1 p_0 + 1 & (10) & & M_1 &\geq M_1 p_1 & (11) & & M_2 s_1 &\geq M_2 & (12) \end{aligned}$$

Now to prove termination one has to show the *satisfiability* of such *Diophantine constraints* over the naturals. In the example, a solution of the constraints is $0_0 = p_0 = M_0 = M_1 = 0$ and $p_1 = s_0 = s_1 = M_2 = 1$. In this way, the abstract interpretation is turned into the polynomial interpretation \mathcal{Pol}_1 .

In the next section, we show how to check this satisfiability using SAT solvers.

2 Encoding Diophantine Constraints to SAT

To encode Diophantine constraints into SAT we first present a mapping $\|\cdot\|$ from polynomials to tuples of propositional formulas which are interpreted as *binary representations* of the polynomials. We restrict the search to coefficients in the range $\{0, \dots, 2^k - 1\}$ for a fixed k . Then each coefficient f is encoded into $\|f\| = \langle f^{k-1}, \dots, f^0 \rangle$ where f^0, \dots, f^{k-1} are propositional variables. Similarly, a natural number $n = b_\ell * 2^\ell + \dots + b_1 * 2^1 + b_0$ is encoded into $\|n\| = \langle b_\ell, \dots, b_1, b_0 \rangle$ where 0 and 1 are identified with *false* and *true*. So if $k = 2$ then $\|s_0\| = \langle s_0^1, s_0^0 \rangle$ and $\|6\| = \langle 1, 1, 0 \rangle$. For addition and multiplication, we introduce operations B^+ and B^* on tuples of propositional formulas and define

$$\|p + q\| = B^+(\|p\|, \|q\|) \quad \text{and} \quad \|p * q\| = B^*(\|p\|, \|q\|)$$

for all polynomials p and q . For B^+ we essentially use the idea of a ripple-carry-adder. The details are presented in [2]. For example $\|s_0 + 6\| = \langle s_0^1, \neg s_0^1, \neg s_0^1, s_0^0 \rangle$. We encode multiplication by summing up partial products as follows:

- $B^*(\langle \varphi_1, \dots, \varphi_n \rangle, \langle \psi \rangle) = \langle \varphi_1 \wedge \psi, \dots, \varphi_n \wedge \psi \rangle$ $\overbrace{\hspace{1.5cm}}^{m-1 \text{ times}}$
- $B^*(\langle \varphi_1, \dots, \varphi_n \rangle, \langle \psi_1, \dots, \psi_m \rangle) = B^+(\langle \varphi_1 \wedge \psi_1, \dots, \varphi_n \wedge \psi_1, \underbrace{0, \dots, 0}_{m-1 \text{ times}} \rangle, B^*(\langle \varphi_1, \dots, \varphi_n \rangle, \langle \psi_2, \dots, \psi_m \rangle))$ if $m \geq 2$.

Now we extend $\|\cdot\|$ to map each Diophantine constraint to a formula (not to a tuple). To this end, we define the operation B^\geq which encodes comparisons.

$$\|p \geq q\| = B^\geq(\|p\|, \|q\|)$$

For B^\geq we apply zero-padding and compare tuples lexicographically:

- $B^\geq(\langle \varphi \rangle, \langle \psi \rangle) = \psi \rightarrow \varphi$
- $B^\geq(\langle \varphi_1, \dots, \varphi_n \rangle, \langle \psi_1, \dots, \psi_n \rangle) = (\varphi_1 \wedge \neg \psi_1) \vee ((\varphi_1 \leftrightarrow \psi_1) \wedge B^\geq(\langle \varphi_2, \dots, \varphi_n \rangle, \langle \psi_2, \dots, \psi_n \rangle))$ if $n \geq 2$.

So to determine the satisfiability of a set of Diophantine constraints $p_i \geq q_i$ with coefficients from $\{0, \dots, 2^k - 1\}$, we encode it as a conjunction $\bigwedge_i \|p_i \geq q_i\|$ of propositional formulas. Then we use a SAT solver to find an assignment for the

coefficients. Note that the space complexity of our encoding is polynomial. More precisely, whenever all numbers in “ $p \geq q$ ” are smaller than $2^k - 1$, then the size of $\|p \geq q\|$ is in $\mathcal{O}(\|p \geq q\|^2 * k^2)$.

3 Polynomials with Negative Constant

Now we regard polynomials $f_{\mathcal{P}ol}$ which may have a negative constant coefficient (i.e., in (4) one may have $f_0 < 0$). All other coefficients still have to be natural numbers. This is needed if we replace the recursive minus-rule by $\text{minus}(x, s(y)) \rightarrow \text{minus}(p(x), p(s(y)))$. Then the constraints are (1), (2), and

$$M(x, s(y)) \succ M(p(x), p(s(y))), \quad (13)$$

which cannot be satisfied using non-negative polynomial interpretations. Thus, we use a polynomial interpretation $\mathcal{P}ol_2$ with $\mathbf{p}_{\mathcal{P}ol_2} = x_1 - 1$. To avoid that terms are mapped to negative integers (which would violate well-foundedness), [6] modified the interpretation of terms $[\cdot]$. Now one defines $\mathbf{p}(x) = \max(x-1, 0)$.

The problem is that with these interpretations, inequalities like $u \succsim v$ are transformed into $[u] \geq [v]$ where $[u]$ and $[v]$ are no polynomials anymore, as they contain “max”. To solve this problem, let us first regard *concrete* polynomial interpretations (where the coefficients are actual numbers). Here, [6] presented an approach to transform inequalities like $[u] \geq [v]$ into ordinary polynomial inequalities without “max”. The idea is to define an under-approximation $[\cdot]^{left}$ and an over-approximation $[\cdot]^{right}$ which do not contain “max” anymore. Then instead of $[u] \geq [v]$ one requires $[u]^{left} \geq [v]^{right}$.

Definition 1 ($[\cdot]^{left}$ [6]). *For every polynomial q we denote its constant part by $con(q)$. For any term t , we define the polynomial $[t]^{left}$ as follows:*³

$$[t]^{left} = \begin{cases} t & \text{if } t \text{ is a variable} \\ 0 & \text{if } t = f(t_1, \dots, t_n), q - con(q) = 0, \text{ and } 0 > con(q) \\ q & \text{if } t = f(t_1, \dots, t_n), \text{ otherwise} \end{cases}$$

where $q = f_{\mathcal{P}ol}([t_1]^{left}, \dots, [t_n]^{left})$.

For example, using $\mathcal{P}ol_2$ we obtain $\mathbf{p}(x)^{left} = x - 1 \leq \max(x - 1, 0) = \mathbf{p}(x)$. The reason is that $q = \mathbf{p}_{\mathcal{P}ol_2}(x) = x - 1$ and thus $con(q) = -1$ and $q - con(q) = x$. If $\mathcal{P}ol_2$ is defined like our previous interpretation $\mathcal{P}ol_1$ on all remaining function symbols except \mathbf{p} , then the constraints (1), (2), and (13) are satisfied and termination of our modified example is proved.

The disadvantage of Def. 1 is that one can only compute $[t]^{left}$ and $[t]^{right}$ for concrete polynomial interpretations, since otherwise q contains coefficients and it depends on the assignment whether $q - con(q) = 0$ and $0 > con(q)$ is valid.

For example, we would use an abstract interpretation with $\mathbf{p}_{\mathcal{P}ol} = \mathbf{p}_0 + \mathbf{p}_1 x_1$. Here, \mathbf{p}_1 may only be instantiated by natural numbers, whereas a coefficient like \mathbf{p}_0 (written in **bold** face) may be instantiated by integers.

The idea is to introduce new coefficients \mathbf{b}_t^{left} and \mathbf{b}_t^{right} for any term t and to

³ The definition of $[\cdot]^{right}$ is similar to $[\cdot]^{left}$, see [2, 6] for details.

create additional Diophantine constraints α_t^{left} and α_t^{right} which guarantee that \mathbf{b}_t^{left} and \mathbf{b}_t^{right} are instantiated correctly, depending on the possible values for the other coefficients. To this end, we express the conditions $q - con(q) = 0$ and $0 > con(q)$ from Def. 1 as Diophantine constraints and one can encode $u \succsim v$ by

$$\alpha_t^{left} \wedge \alpha_t^{right} \wedge [u]^{left} \geq [v]^{right}.$$

Here, $[\cdot]^{left}$ and $[\cdot]^{right}$ interpret terms with the help of the additional coefficients \mathbf{b}_t^{left} and \mathbf{b}_t^{right} . For example, $\mathbf{p}(x) \succsim x$ is transformed into:

$$\begin{aligned} (\mathbf{p}_1 = 0 \wedge 0 > \mathbf{p}_0) \rightarrow \mathbf{b}_{\mathbf{p}(x)}^{left} = 0 & \quad \wedge \\ \neg(\mathbf{p}_1 = 0 \wedge 0 > \mathbf{p}_0) \rightarrow \mathbf{b}_{\mathbf{p}(x)}^{left} = \mathbf{p}_0 & \quad \wedge \quad \mathbf{p}_1 x + \mathbf{b}_{\mathbf{p}(x)}^{left} \geq x \end{aligned}$$

So we obtain polynomial constraints containing **bold** coefficients like \mathbf{p}_0 and $\mathbf{b}_{\mathbf{p}(x)}^{left}$ which may be instantiated by *integers*. In [2] it is shown how to remove these coefficients in order to apply our SAT encoding afterwards.

4 Implementation, Experiments, and Conclusion

We implemented our new SAT-based approach for polynomial interpretations in the termination prover AProVE [4] and used state-of-the art SAT solvers for the experiments. The SAT-based search for polynomial interpretations is by orders of magnitude faster than other non-SAT-based search algorithms. This holds in particular if one considers polynomials with higher coefficients or degrees. For details on the experiments and for the full paper [2] we refer to our evaluation web site at <http://aprove.informatik.rwth-aachen.de/eval/SATP0L0>.

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