



# Smarter Features, Simpler Learning?

Georg Moser and Sarah Winkler

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strategy/tool are machine learned from program characteristics

- $\blacktriangleright$  strategy/tool are machine learned from program characteristics
- ▶ model: SVMs

📄 Demyanova et al., Empirical Software Metrics for Benchmarking of Verification Tools, 2017.

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- ▶ model: SVMs
- ► features:
  - variable roles
  - loop patterns
  - ▶ control flow patterns

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- would have won SV-COMP in 3 consecutive years

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# Past/Current Work in Theorem Proving

models: naive Bayes, SVMs, random forests, ..., neural networks

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models: naive Bayes, SVMs, random forests, ..., neural networks features: plain input, term walks, symbol/clause count, ...



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# Past/Current Work in Theorem Proving



- strategy/tool are machine learned from program characteristics
- mode occurrence count for 27 roles: pointers, loop bounds, counters, ...
- features:
  - variable roles
  - loop patterns
  - control flow patterns
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# Past/Current Work in Theorem Proving



- strategy/tool are machine learned from program characteristics
- ▶ model: SVMs
  - features: occurrence count for 3 types depending on iteration estimate
    - variable roles
    - loop patterns
    - control flow patterns
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# Past/Current Work in Theorem Proving



strategy/tool are machine learned from program characteristics

basic blocks, indegree, (recursive) calls

- ▶ model: SVMs
- ▶ features:
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# Past/Current Work in Theorem Proving



variable roles = argument positions of function symbols:

# Example add $(0, x) \rightarrow x$ (1) mul $(0, y) \rightarrow 0$ (3) add $(s(x), y) \rightarrow s(add(x, y))$ (2) mul $(s(x), y) \rightarrow add(y, mul(x, y))$ (4)

- variable roles = argument positions of function symbols:
  - *i* is projection argument in rule  $f(t_1, \ldots, t_n) \rightarrow t_i$

# Example $add(0, \mathbf{x}) \rightarrow \mathbf{x} \qquad (1) \qquad mul(0, y) \rightarrow 0 \qquad (3)$ $add(s(x), y) \rightarrow s(add(x, y)) \qquad (2) \qquad mul(s(x), y) \rightarrow add(y, mul(x, y)) \qquad (4)$

- variable roles = argument positions of function symbols:
  - *i* is projection argument in rule  $f(t_1, \ldots, t_n) \rightarrow t_i$
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# Example add $(0, x) \rightarrow x$ (1) mul $(0, y) \rightarrow 0$ (3) add $(\mathbf{s}(x), y) \rightarrow \mathbf{s}(\operatorname{add}(\mathbf{x}, y))$ (2) mul $(\mathbf{s}(x), y) \rightarrow \operatorname{add}(y, \operatorname{mul}(x, y))$ (4)

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  - ▶ recursive positions: recursive calls to same function symbol

#### Example

 $\operatorname{add}(0, x) \to x$  (1)  $\operatorname{mul}(0, y) \to 0$  (3)

 $\operatorname{\mathsf{add}}(\operatorname{\mathsf{s}}(x),y) \to \operatorname{\mathsf{s}}(\operatorname{\mathsf{add}}(x,y))$  (2)  $\operatorname{\mathsf{mul}}(\operatorname{\mathsf{s}}(x),y) \to \operatorname{\mathsf{add}}(y,\operatorname{\mathsf{mul}}(x,y))$  (4)

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  - *i* is projection argument in rule  $f(t_1, \ldots, t_n) \rightarrow t_i$
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  - recursive positions: recursive calls to same function symbol
  - pattern matching positions distinguish different constructors

# Example add( $\mathbf{0}, x$ ) $\rightarrow x$ (1) mul( $\mathbf{0}, y$ ) $\rightarrow \mathbf{0}$ (3) add( $\mathbf{s}(x), y$ ) $\rightarrow \mathbf{s}(add(x, y))$ (2) mul( $\mathbf{s}(x), y$ ) $\rightarrow add(y, mul(x, y))$ (4)

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  - duplication positions contain variables which get duplicated

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- ▶ loop patterns = recursion patterns: tiering and safe recursion

# Example $add(0,x) \rightarrow x$ (1) $mul(0,y) \rightarrow 0$ (3) $add(s(x),y) \rightarrow s(add(x,y))$ (2) $mul(s(x),y) \rightarrow add(y,mul(x,y))$ (4)

<sup>📔</sup> Bellantoni and Cook, A new recursion-theoretic characterization of the polytime functions, 1992.

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- recursive positions: recursive calls to same function symbol
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- ▶ loop patterns = recursion patterns: tiering and safe recursion
- control flow = call graph analysis:

strongly connected components, in/out degree of nodes, edges between nodes of different root symbols, ...

### Example

 $\operatorname{add}(0,x) \to x$  (1)  $\operatorname{mul}(0,y) \to 0$  (3)

 $\operatorname{\mathsf{add}}(\operatorname{\mathsf{s}}(x),y) \to \operatorname{\mathsf{s}}(\operatorname{\mathsf{add}}(x,y))$  (2)  $\operatorname{\mathsf{mul}}(\operatorname{\mathsf{s}}(x),y) \to \operatorname{\mathsf{add}}(y,\operatorname{\mathsf{mul}}(x,y))$  (4)

$$\begin{array}{c} (2) \longrightarrow (4) \\ \uparrow & \uparrow \end{array}$$

consider machine learning of strategies applied to a given problem:



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can we preprocess characteristics from theorem proving problems which serve as useful features for learning?



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- ... or better rely on neural networks discovering relevant characteristics by themselves?



consider machine learning of strategies applied to a given problem:

- can we preprocess characteristics from theorem proving problems which serve as useful features for learning?
- ... or better rely on neural networks discovering relevant characteristics by themselves?
- how could such features look like?

