

Smarter Features, Simpler Learning?

Georg Moser and Sarah Winkler

Automated Reasoning: Challenges, Applications, Directions, Exemplary Achievements 26 August 2019, Natal

 \triangleright strategy/tool are machine learned from program characteristics

Demyanova et al., Empirical Software Metrics for Benchmarking of Verification Tools, 2017. 2

- \triangleright strategy/tool are machine learned from program characteristics
- \blacktriangleright model: SVMs

Demyanova et al., Empirical Software Metrics for Benchmarking of Verification Tools, 2017. 2

- \triangleright strategy/tool are machine learned from program characteristics
- \blacktriangleright model: SVMs
- \blacktriangleright features:
	- \blacktriangleright variable roles
	- \blacktriangleright loop patterns
	- \blacktriangleright control flow patterns

- \triangleright strategy/tool are machine learned from program characteristics
- model: SVMs
- \blacktriangleright features:
	- \blacktriangleright variable roles
	- \blacktriangleright loop patterns
	- \blacktriangleright control flow patterns
- ▶ would have won SV-COMP in 3 consecutive years

- \triangleright strategy/tool are machine learned from program characteristics
- model: SVMs
- \blacktriangleright features:
	- \blacktriangleright variable roles
	- \blacktriangleright loop patterns
	- \blacktriangleright control flow patterns
- \triangleright would have won SV-COMP in 3 consecutive years

Past/Current Work in Theorem Proving

models: naive Bayes, SVMs, random forests, . . . , neural networks

Demyanova et al., Empirical Software Metrics for Benchmarking of Verification Tools, 2017. 2

- \triangleright strategy/tool are machine learned from program characteristics
- model: SVMs
- \blacktriangleright features:
	- \blacktriangleright variable roles
	- \blacktriangleright loop patterns
	- \blacktriangleright control flow patterns
- \triangleright would have won SV-COMP in 3 consecutive years

Past/Current Work in Theorem Proving

Demyanova et al., Empirical Software Metrics for Benchmarking of Verification Tools, 2017. 2

- \triangleright strategy/tool are machine learned from program characteristics
- model: SVMs
- \blacktriangleright features:
	- \longrightarrow variable roles
	- \blacktriangleright loop patterns
	- \blacktriangleright control flow patterns
- \triangleright would have won SV-COMP in 3 consecutive years

Past/Current Work in Theorem Proving

- \triangleright strategy/tool are machine learned from program characteristics
- model: SVMs
- features:
	- \longrightarrow variable roles
	- \blacktriangleright loop patterns
	- \blacktriangleright control flow patterns
- ▶ would have won SV-COMP in 3 consecutive years

Past/Current Work in Theorem Proving

- \triangleright strategy/tool are machine learned from program characteristics
- model: SVMs
- features:
	- \longrightarrow variable roles
	- \blacktriangleright loop patterns
	- \blacktriangleright control flow patterns
- \triangleright would have won SV-COMP in 3 consecutive years

Past/Current Work in Theorem Proving

- strategy/tool are machine learned from program characteristics
- \triangleright mode $\overline{\text{occurrence count for 27 roles: pointers, loop bounds, counters, ...}}$
- features:
	- \triangleright variable roles
	- \blacktriangleright loop patterns
	- \blacktriangleright control flow patterns
- ▶ would have won SV-COMP in 3 consecutive years

Past/Current Work in Theorem Proving

- strategy/tool are machine learned from program characteristics
- model: SVMs
	- features: occurrence count for 3 types depending on iteration estimate
		- \triangleright variable roles
		- loop patterns
		- \blacktriangleright control flow patterns
- would have won SV-COMP in 3 consecutive years

Past/Current Work in Theorem Proving

strategy/tool are machine learned from program characteristics

basic blocks, indegree, (recursive) calls

- model: SVMs
- features:
	- \triangleright variable roles
	- \blacktriangleright loop patterns
	- \blacktriangleright control flow patterns
- ▶ would have won SV-COMP in 3 consecutive years

Past/Current Work in Theorem Proving

 \triangleright variable roles = argument positions of function symbols:

Example $add(0, x) \to x$ (1) $mul(0, y) \to 0$ (3) $add(s(x), y) \rightarrow s(add(x, y))$ (2) mul(s(x), y) $\rightarrow add(y, mul(x, y))$ (4)

- \triangleright variable roles = argument positions of function symbols:
	- is projection argument in rule $f(t_1, \ldots, t_n) \rightarrow t_i$

Example $add(0, x) \rightarrow x$ (1) mul $(0, y) \rightarrow 0$ (3) $add(s(x), y) \rightarrow s(add(x, y))$ (2) mul(s(x), y) $\rightarrow add(y, mul(x, y))$ (4)

- \triangleright variable roles $=$ argument positions of function symbols:
	- is projection argument in rule $f(t_1, \ldots, t_n) \rightarrow t_i$
	- \triangleright in is decreasing for rule $f(\ldots,s(t_i),\ldots)\to\mathcal{C}[f(\ldots,t_i,\ldots)]$

Example $add(0, x) \rightarrow x$ (1) $mul(0, y) \rightarrow 0$ (3) $\mathsf{add}(\mathsf{s}(x), y) \to \mathsf{s}(\mathsf{add}(x, y))$ (2) $\mathsf{mul}(\mathsf{s}(x), y) \to \mathsf{add}(y, \mathsf{mul}(x, y))$ (4)

- \triangleright variable roles $=$ argument positions of function symbols:
	- is projection argument in rule $f(t_1, \ldots, t_n) \rightarrow t_i$
	- \triangleright in station is decreasing for rule $f(\ldots,s(t_i),\ldots)\to\mathcal{C}[f(\ldots,t_i,\ldots)]$
	- recursive positions: recursive calls to same function symbol

Example

 $add(0, x) \rightarrow x$ (1) $mul(0, y) \rightarrow 0$ (3)

 $add(s(x), y) \rightarrow s(add(x, y))$ (2) mul(s(x), y) $\rightarrow add(y, mul(x, y))$ (4)

- \triangleright variable roles $=$ argument positions of function symbols:
	- is projection argument in rule $f(t_1, \ldots, t_n) \rightarrow t_i$
	- \triangleright in station is decreasing for rule $f(\ldots,s(t_i),\ldots)\to\mathcal{C}[f(\ldots,t_i,\ldots)]$
	- recursive positions: recursive calls to same function symbol
	- \triangleright pattern matching positions distinguish different constructors

Example $add(0, x) \rightarrow x$ (1) mul $(0, y) \rightarrow 0$ (3) $\text{add}(\textbf{s}(x), y) \to \textbf{s}(\text{add}(x, y))$ (2) mul $(\textbf{s}(x), y) \to \text{add}(y, \text{mul}(x, y))$ (4)

- \triangleright variable roles $=$ argument positions of function symbols:
	- is projection argument in rule $f(t_1, \ldots, t_n) \rightarrow t_i$
	- \triangleright in station is decreasing for rule $f(\ldots,s(t_i),\ldots)\to\mathcal{C}[f(\ldots,t_i,\ldots)]$
	- recursive positions: recursive calls to same function symbol
	- pattern matching positions distinguish different constructors
	- duplication positions contain variables which get duplicated

Example

 $\operatorname{add}(0,x) \to x$ (1) $\operatorname{mul}(0,y) \to 0$ (3)

 $\text{add}(s(x), y) \to s(\text{add}(x, y))$ (2) $\text{mul}(s(x), y) \to \text{add}(y, \text{mul}(x, y))$ (4)

- \triangleright variable roles $=$ argument positions of function symbols:
	- is projection argument in rule $f(t_1, \ldots, t_n) \rightarrow t_i$
	- \triangleright in station is decreasing for rule $f(\ldots,s(t_i),\ldots)\to\mathcal{C}[f(\ldots,t_i,\ldots)]$
	- recursive positions: recursive calls to same function symbol
	- pattern matching positions distinguish different constructors
	- duplication positions contain variables which get duplicated
- \triangleright loop patterns = recursion patterns: tiering and safe recursion

Example $add(0, x) \rightarrow x$ (1) $mul(0, y) \rightarrow 0$ (3) $add(s(x), y) \rightarrow s(add(x, y))$ (2) mul(s(x), y) $\rightarrow add(y, mul(x, y))$ (4)

Bellantoni and Cook, A new recursion-theoretic characterization of the polytime functions, 1992. 3

 \triangleright variable roles $=$ argument positions of function symbols:

- is projection argument in rule $f(t_1, \ldots, t_n) \rightarrow t_i$
- \triangleright in station is decreasing for rule $f(\ldots,s(t_i),\ldots)\to\mathcal{C}[f(\ldots,t_i,\ldots)]$
- recursive positions: recursive calls to same function symbol
- pattern matching positions distinguish different constructors
- duplication positions contain variables which get duplicated
- \triangleright loop patterns = recursion patterns: tiering and safe recursion
- \triangleright control flow = call graph analysis:

strongly connected components, in/out degree of nodes, edges between nodes of different root symbols, ...

Example

 $add(0, x) \rightarrow x$ (1) $mul(0, y) \rightarrow 0$ (3)

 $add(s(x), y) \rightarrow s(add(x, y))$ (2) mul(s(x), y) $\rightarrow add(y, mul(x, y))$ (4)

$$
\begin{array}{ccc}\n(2) & \longrightarrow & (4) \\
\uparrow & & \uparrow\n\end{array}
$$

consider machine learning of strategies applied to a given problem:

consider machine learning of strategies applied to a given problem:

 \triangleright can we preprocess characteristics from theorem proving problems which serve as useful features for learning?

consider machine learning of strategies applied to a given problem:

- can we preprocess characteristics from theorem proving problems which serve as useful features for learning?
- \triangleright ... or better rely on neural networks discovering relevant characteristics by themselves?

consider machine learning of strategies applied to a given problem:

- can we preprocess characteristics from theorem proving problems which serve as useful features for learning?
- I ... or better rely on neural networks discovering relevant characteristics by themselves?
- I how could such features look like?

