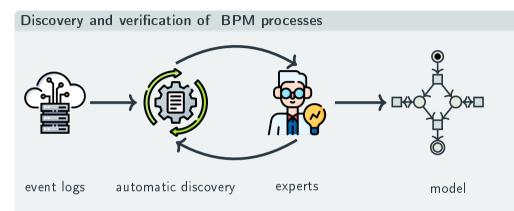
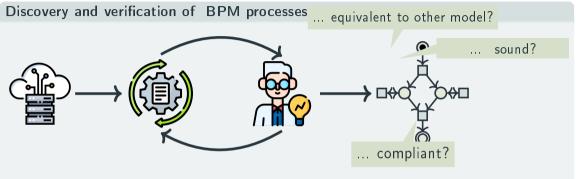
Using Logic to Escape the Jungle of Data-aware Process Verification

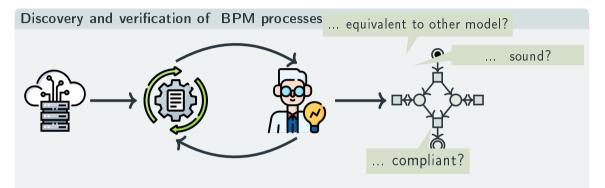
Sarah Winkler Free University of Bozen-Bolzano, Italy

seminar @ DTU Compute, 7.9.2023



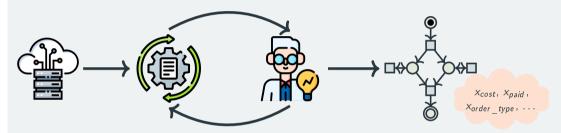


e.g. every order is eventually shipped



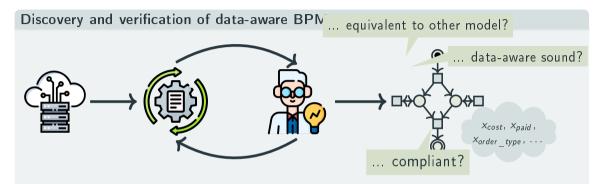
in Petri nets for typical BPM processes, verification tasks can be effectively decided

Discovery and verification of data-aware BPM processes



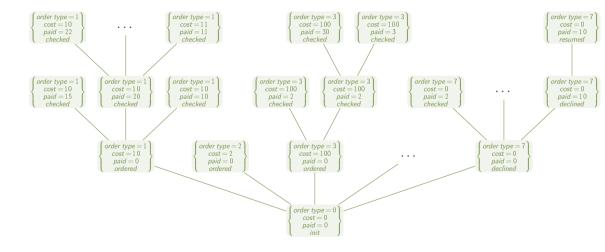
#### Assumption

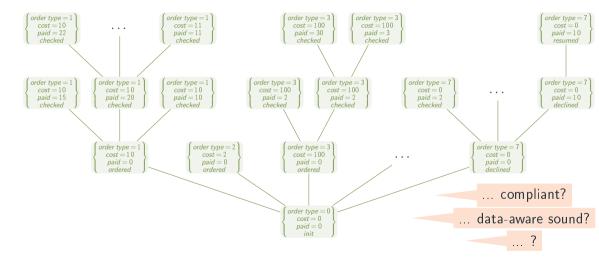
data is represented by numeric variables, can be read and written by transitions

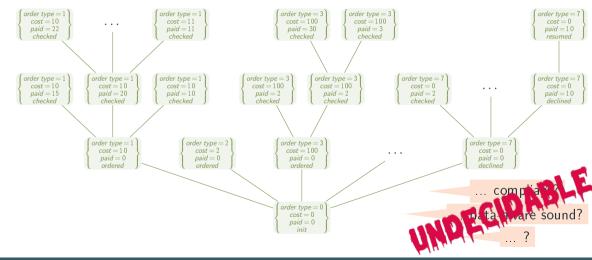


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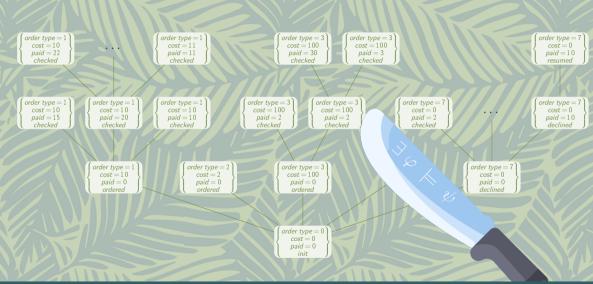
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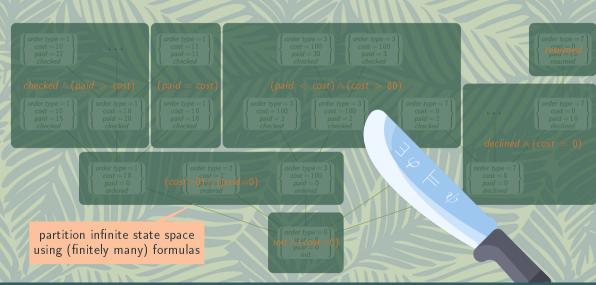


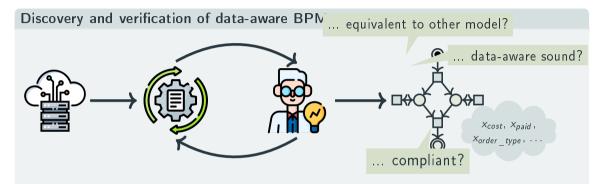








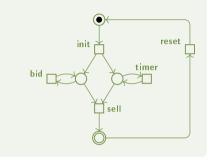




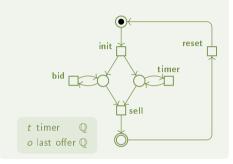
## This talk identify classes of data-aware models where verification tasks are decidable

# Outline

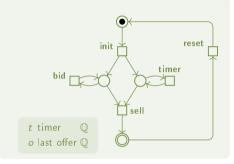
- ► based on Petri net
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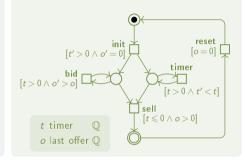
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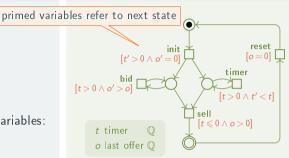
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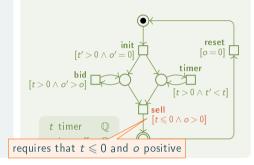
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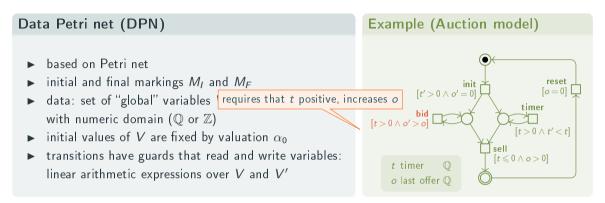


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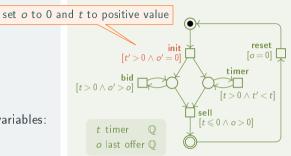


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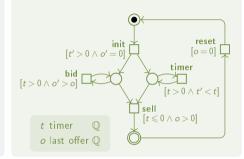


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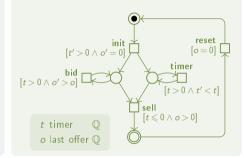


### **Background** logic

- ▶ propositional logic + theory of linear arithmetic over integers and rationals
- ▶ satisfiability is decidable (SMT solvers), quantifiers can be eliminated

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#### Remark

- DPNs can be mined automatically from data
- used to model BPM processes from various domains

[Mannhardt et al 2016, de Leoni 2013]

[Mannhardt et al 2016, Mannhardt 2018]

**Observation** if underlying Petri net is **bounded**, DPN has finite set of markings: can be **unfolded** 

if underlying Petri net is bounded, DPN has finite set of markings: can be unfolded

Data-aware Dynamic System with Arithmetic (DDSA)

if underlying Petri net is bounded, DPN has finite set of markings: can be unfolded

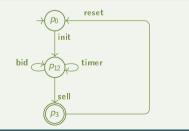
## Data-aware Dynamic System with Arithmetic (DDSA)

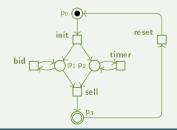
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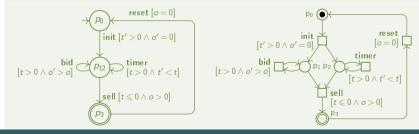
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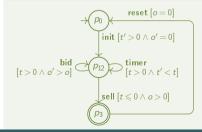
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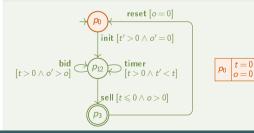
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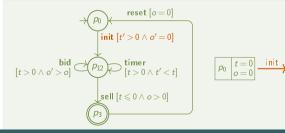
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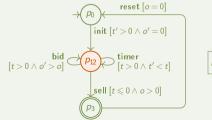
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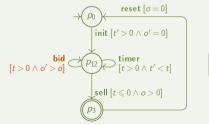


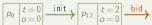
$\begin{array}{c c} P_0 & t = 0 \\ o = 0 \end{array} \xrightarrow{\text{init}} \begin{array}{c} P_{12} & t = 2 \\ o = 0 \end{array}$
--

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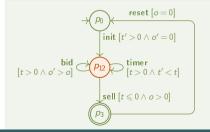


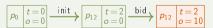


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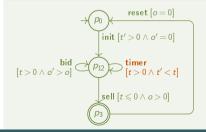


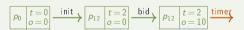


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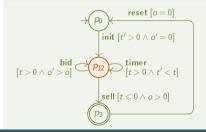




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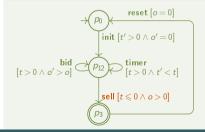




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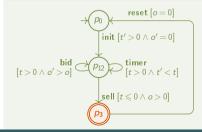




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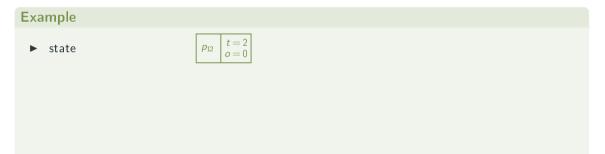
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## Example

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## Example

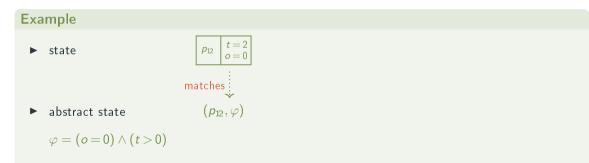
state



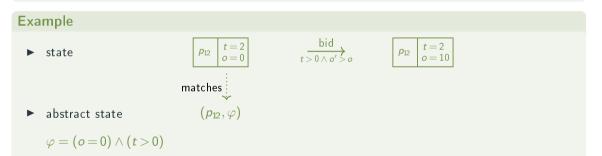
• abstract state  $(p_{12}, \varphi)$ 

 $\varphi = (o = 0) \land (t > 0)$ 

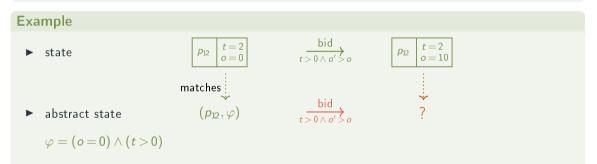
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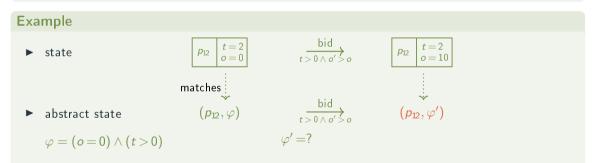
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for formula  $\varphi$  and transition  $\textbf{\textit{a}}$  in DDSA

 $update(\varphi, a) =$ 

describes how formula arphi changes after transition a

# **Definition (Update)** for formula $\varphi$ and transition a i rename variables in formula to auxiliary $\widehat{V} = \{\widehat{v} \mid v \in V\}$ $update(\varphi, a) = \varphi(\widehat{V})$

for formula  $\varphi$  and transition a in DDSA

sition *a* in DDSA guard must hold, propagate variables that are not written  

$$update(\varphi, a) = \varphi(\widehat{V}) \wedge guard_a(\widehat{V}, V) \wedge \widehat{V} = v$$

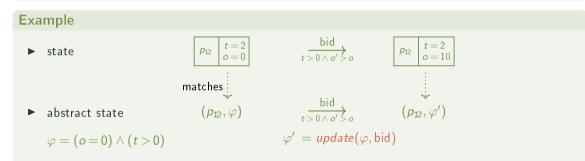
v∉write(a)

**Definition (Update)**  $\exists$  quantification to get formula with free variables Vfor formula  $\varphi$  and transition a in DDSA  $update(\varphi, a) = \exists \hat{V}. (\varphi(\hat{V}) \land guard_a(\hat{V}, V) \land \bigwedge_{v \notin write(a)} \hat{v} = v)$ 

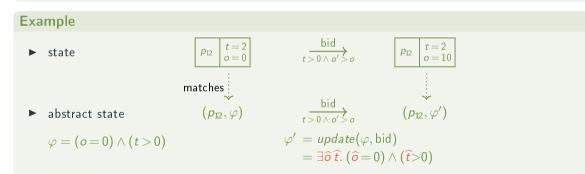
for formula  $\varphi$  and transition *a* in DDSA can get equivalent quantifier-free formula by quantifier elimination

$$up\,date(\varphi,a) = \exists \widehat{V}.\,(\varphi(\widehat{V}) \land guard_a(\widehat{V},V) \land \bigwedge_{v \notin write(a)} \widehat{v} = v)$$

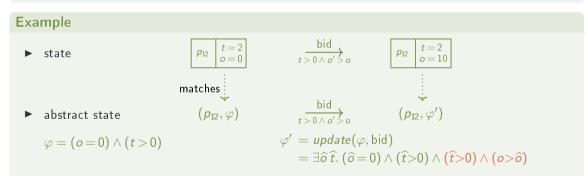
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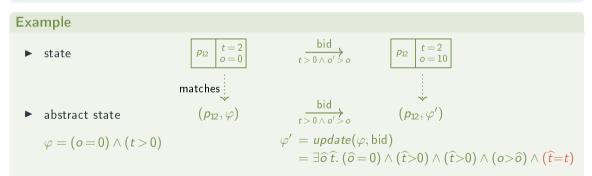
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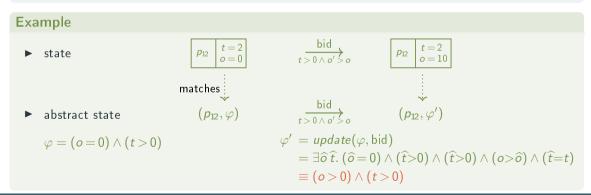
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$$update(\varphi, a) = \exists \widehat{V}. (\varphi(\widehat{V}) \land guard_{a}(\widehat{V}, V) \land \bigwedge_{v \notin write(a)} \widehat{v} = v)$$

# Definition (Constraint graph)

for formula  $\varphi$  and transition  $\textbf{\textit{a}}$  in DDSA

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# Definition (Constraint graph)

• initial node is 
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, with  $\varphi_0 = \bigwedge_{v \in V} v = \alpha_0(v)$ 

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## Definition (Constraint graph)

- initial node is  $(s_0, \varphi_0)$ , with  $\varphi_0 = \bigwedge_{v \in V} v = \alpha_0(v)$
- for every node  $(s, \varphi)$

for formula  $\varphi$  and transition a in DDSA

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- initial node is  $(s_0, \varphi_0)$ , with  $\varphi_0 = \bigwedge_{v \in V} v = \alpha_0(v)$
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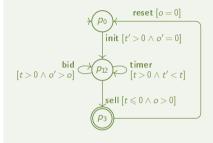
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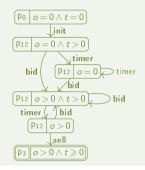
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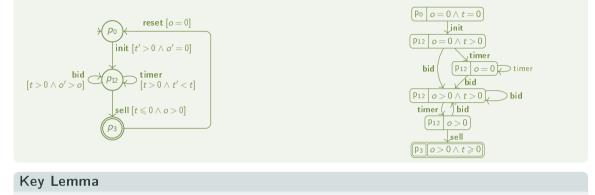
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- $(s,...) \in N$  is final if s is final in DDSA





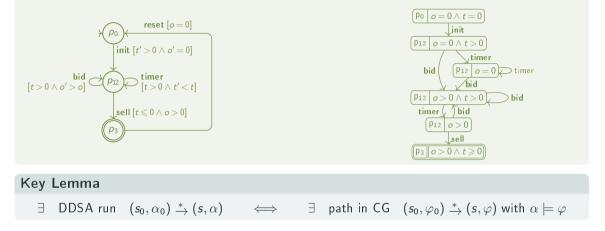


 $\exists DDSA run (s_0, \alpha_0) \xrightarrow{*} (s, \alpha) \iff \exists path in CG (s_0, \varphi_0) \xrightarrow{*} (s, \varphi) with \alpha \models \varphi$ 



Key Lemma

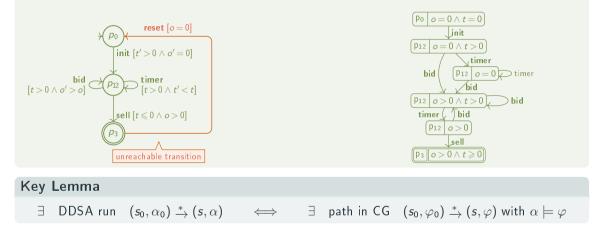
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#### Observation

control state or transition of DDSA are reachable iff they appear in the constraint graph

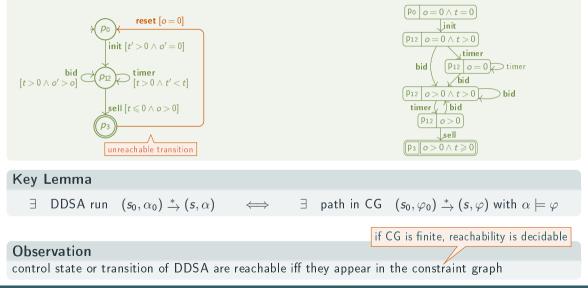
#### Example (Constraint graph for auction model)



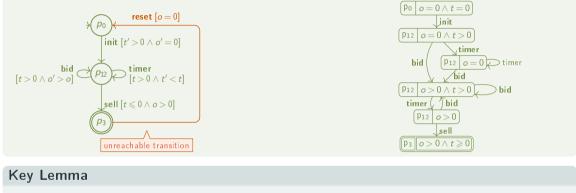
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#### Caveat

constraint graph can be infinite

formulas in CG are history constraints:

 $\exists \dots \exists$  (conjunctions of renamed transition guards)

### **Definition (Finite summary)**

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#### abstract decidability condition

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timer

 $[t \leq 0 \land o > 0]$ 

 $\begin{bmatrix} t > 0 \land t' < t \end{bmatrix}$ 

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[Felli, Montali & W, AAAI 2022]

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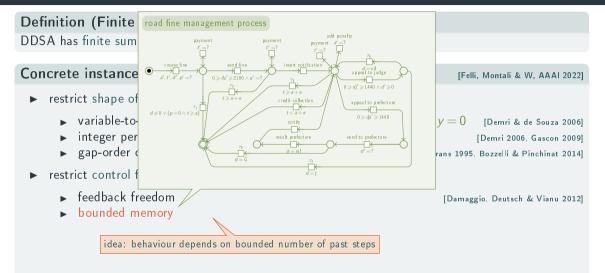
idea: behaviour depends on bounded number of past steps

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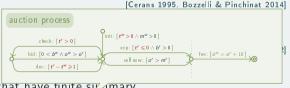
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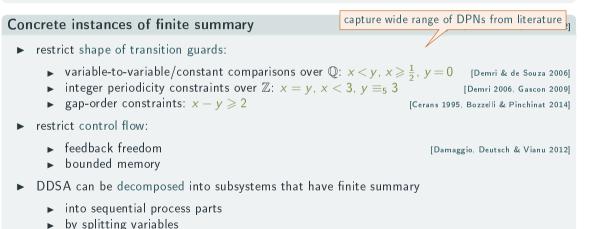


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## Outline

given DDSA and LTL<sub>f</sub> formula  $\psi$  with arithmetic constraints:

constraint | control state |  $\psi \land \psi$  |  $\psi \lor \psi$  |  $\langle action \rangle \psi$  | X  $\psi$  | F  $\psi$  | G  $\psi$  |  $\psi \lor \psi$ is there a witness run of DDSA that satisfies  $\psi$ ?

## Linear-Time Model Checking

evaluated over finite traces

## Verification problem: Compliance

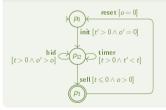
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 $\textit{constraint} \mid \textit{control state} \mid \psi \land \psi \mid \psi \lor \psi \mid \langle \textit{action} \rangle \psi \mid X \psi \mid F \psi \mid G \psi \mid \psi \cup \psi$  is there a witness run of DDSA that satisfies  $\psi$ ?

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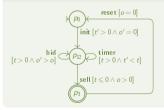


►  $F((o=100) \land G(p_3 \rightarrow o \neq 100))$ : witness exists it is possible that bid of  $100 \in$  does not win

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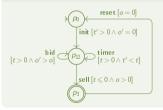


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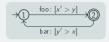
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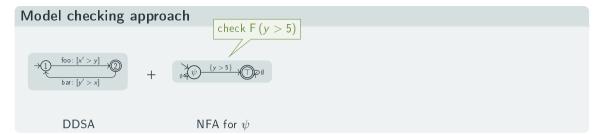
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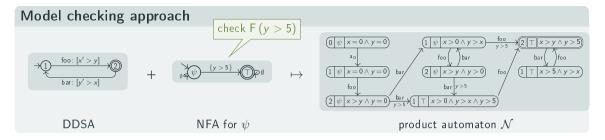
#### Fact

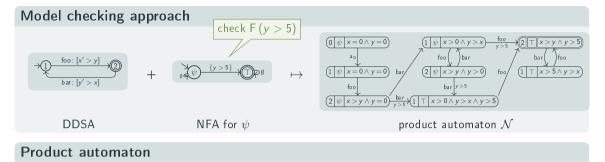
can construct finite automaton (NFA) accepting exactly those runs that satisfy  $LTL_f$  property



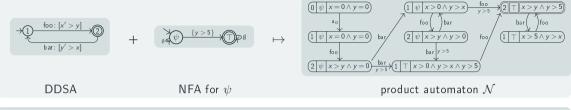
DDSA





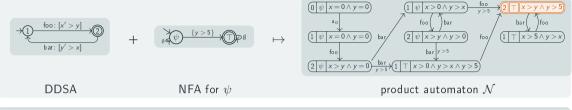


nodes are triples (DDSA state, NFA state, formula)



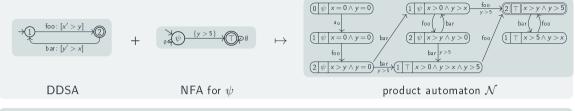
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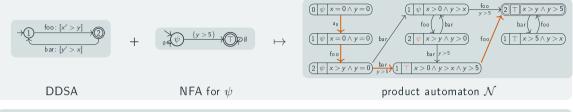


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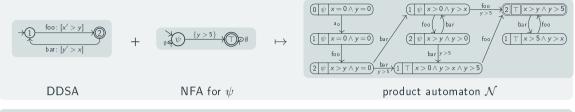
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can use SMT solver to extract witness from accepting path

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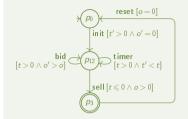
## Data-aware Soundness

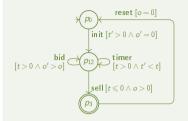
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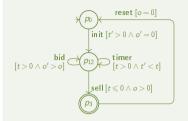
## Example (Auction)





not data-aware sound because

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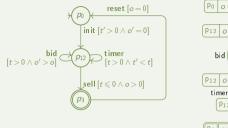
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if DDSA has finite summary, data-aware soundness is decidable

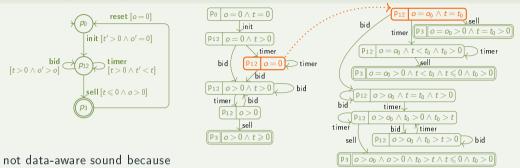


 $\begin{array}{c|c} \hline P0 & o = 0 \land t = 0 \\ \hline \\ \hline \\ p12 & o = 0 \land t > 0 \\ \hline \\ p12 & o = 0 \land t > 0 \\ \hline \\ p12 & o = 0 \land t > 0 \\ \hline \\ p12 & o > 0 \land t > 0 \\ \hline \\ p12 & o > 0$ 

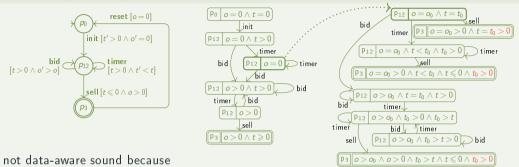
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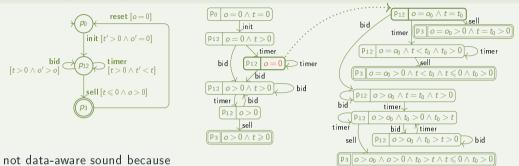
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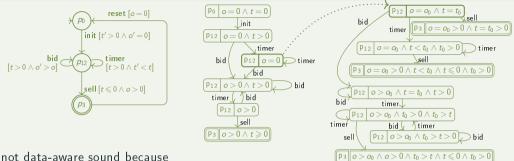


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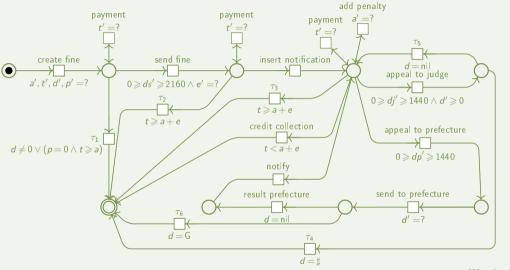
lot data-aware sound because

- transition reset is unreachable
- ► deadlocks exist, e.g. after  $|p_0| \stackrel{t=0}{\underset{o=0}{\overset{init}{\overset{o=0}{\overset{o}$

### Branching-time model checking

use similar approach to obtain CTL\* model checking procedure

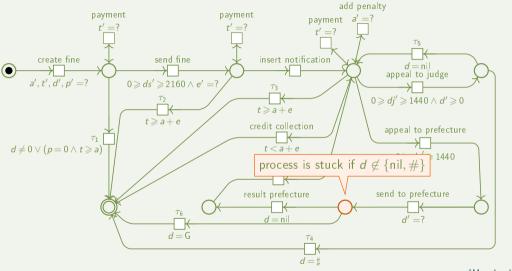
# Example (Road fine management process)



[Mannhardt et al 2016]

### Example (Road fine management process)

#### not data-aware sound

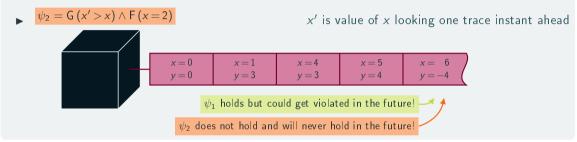


[Mannhardt et al 2016]

# Monitoring Arithmetic Temporal Properties

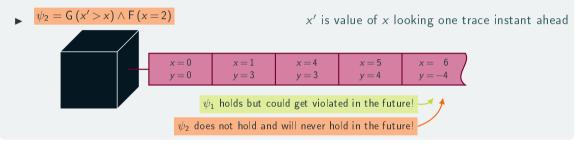
given a trace of values, check current and possible future satisfaction of  $LTL_f$  properties like

 $\psi_1 = (y \ge 0) \ \mathsf{U} \ (x > y \land \mathsf{G} \ (x > y))$ 



# Monitoring Arithmetic Temporal Properties

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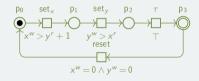
# Results

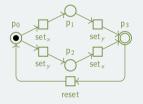
- developed monitoring procedure
- ▶ use finite summary approach to identify classes of properties where problem is decidable

[Felli, Montali, Patrizi & W, AAAI 2023]

Verification problem

given two DPNs, do they have the same sets of configurations, and/or the same language?





### Results

- can be determined using constraint graphs
- ► decidable for finite summary systems



# Implementation

# Arithmetic DDS Analyzer (ada)

- ▶ input DPN (+ LTL<sub>f</sub> or CTL<sub>f</sub> property)
- ► checks for decidability conditions, visualizes CG/product automaton
- ▶ performs  $LTL_f$ ,  $CTL_f^*$  model checking, soundness checking, and monitoring
- ▶ computes witness/counterexample
- written in Python, using Z3/Yices/CVC5 for SMT solving and quantifier elimination https://ltl.adatool.dev https://soundness.adatool.dev https://ctlstar.adatool.dev

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### Experiments

- ▶ about 60 DPNs (20 from literature, 40 artificial)
- ▶ all DPNs from literature are in some decidable class for  $LTL_f$  (but not  $CTL_f^*$ ) model checking

Implementati					- la slas	1121	
	process	property	sat	time	checks	$ \mathcal{B} $	$ \mathcal{N}_{\mathcal{B},b}^{\psi} $
	road fines (1)	no deadlock	×	7.0s	8161	9	2052
Arithmetic DD		$AG\ (p_7 \to E\ F\ end)$	<ul> <li>✓</li> </ul>	7.6s	7655		1987
Antimetic DD	road fines (2)	no deadlock	<ul> <li>✓</li> </ul>	15m27s	247563	9	4927
		$AG (p_7 \rightarrow EFend)$	$\checkmark$	16m7s	246813		4927
input DPN (	road fines (3)	no deadlock	×	9s	9179	9	1985
		$AG (p_7 \rightarrow EFend)$	$\checkmark$	6.6s	6382		1597
checks for d		$EF\left(dS\geqslant 2160\right)$	×	11.5s	17680		1280
	hospital billing	no deadlock	$\checkmark$	20m59s	1234928	17	23147
performs LT		$EF(p16 \land \neg \mathit{closed})$	$\checkmark$	10m20s	669379		10654
p ponorino En	sepsis (1)	no deadlock	$\checkmark$	1m36s	139	301	44939
computes w		$AG (sink \to t_{tr} < t_{ab})$	×	30.1s	170		22724
		$AG (sink \rightarrow t_{tr} + 60 \ge t_{ab})$	$\checkmark$	32s	153		22538
written in P	sepsis (2)	no deadlock	$\checkmark$	7m24	4524	301	161242
		A $(\neg lacticAcid \cup \langle diagnostic \rangle \top)$	$\checkmark$	3m53s	5734		74984
1	board: register	no deadlock	$\checkmark$	1.4s	12	7	27
	board: transfer	no deadlock	$\checkmark$	1.4s	27	7	51
	board: discharge	no deadlock	$\checkmark$	1.5s	25	6	67
	-	$AG\;(p_2\;\land\;o_{1}{=}207\;\rightarrow\;AG\;o_{1}{=}207)$	$\checkmark$	1.5s	94		91
		$AG(EF\langletra\rangle\top\wedgeEF\langlehis\rangle\top)$	$\checkmark$	1.5s	27		98
Experiments		$\neg E(F\langle tra \rangle \top \land F \langle his \rangle \top)$	$\checkmark$	1.4s	56		43
Experimento	credit approval	no deadlock	$\checkmark$	1.7s	470	6	230
		$AG \left( \langle openLoan \rangle \top \to \mathit{ver} \land \mathit{dec} \right)$	$\checkmark$	13.2s	14156		645
🔹 🕨 about 60 DF		$A\left(F\left(\mathit{ver} \land \mathit{dec}\right) \to F\left< openLoan \right> \top\right)$	×	3.7s	3128		316
	package handling	no deadlock	$\checkmark$	2.7ss	1025	16	693
all DPNs frd		no deadlock $( au_1)$	$\checkmark$	2.5s	1079		398
		$\psi_{k1} = EF \langle fetch  angle  op$	×	2.6s	850		343
		$\psi_{k2} = EF \langle \tau_{\boldsymbol{6}} \rangle \top$	×	2.4s	875		336
	auction	no deadlock	×	10.8s	1683	5	186
		$EF(sold\wedged>0\wedgeo\leqslant t)$	×	6.4s	1180		79
		$EF\;(b{=}1\wedgeo>t\wedgeF\;(sold\wedgeb>1))$	$\checkmark$	26.5s	4000		263

# Conclusion

# Summary

- for Data Petri nets with arithmetic constraints: verification procedures for LTL<sub>f</sub>, CTL<sub>f</sub>, data-aware soundness
- ► decision procedure if DPN satisfies finite summary property: new decidability results
- ▶ implemented and tested on processes from BPM

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# Take-home message

- ▶ finite constraint graphs are powerful tool for verification
- ▶ many relevant verification tasks are decidable for "practical" Data Petri nets

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# Take-home message

- finite constraint graphs are powerful tool for verification
- many relevant verification tasks are decidable for "practical" Data Petri nets

### Future work

- ▶ further SMT theories, e.g. allow guards to refer to database
- discover more expressive transition guards for DPNs :)

# ... all of this is the result of a fun collaboration with



Marco Montali Paolo Felli Fabio Patrizi

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