

Refined Resource Analysis Based on Cost Relations

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Static Resource Analysis

The Goal

Statically obtain a bound on the resource consumption of a program
(amount of resources required to execute it) on **any** input data

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- ▶ Execution steps (execution time)
- ▶ Number of visits to a program point
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Good Reasons for Having It

- ▶ Performance evaluation, avoid performance bugs
- ▶ Code documentation and certification
- ▶ Real cost estimation in virtual environments, provisioning

Classic Approach to Resource Analysis

Most early work on resource analysis based on extracting and solving recurrence relations

- ▶ [Wegbreit, 1975] (Lisp programs)
- ▶ [Debray and Lin, 1993] (Logic programs)
- ▶ [Vasconcelos and Hammond, 2004] (Functional programs)



Limitations of Approach Based on Recurrence Relations

Extracting as well as solving of recurrence relations from programs is challenging and leads to highly complex and/or sub-optimal solutions

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while (i<n) {  
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        i=rnd(n-1);  
        r--;  
    } else  
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}
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while (i<n) {  
    if (r>0) {  
p1:     i=rnd(n-1);  
p1:     r--;  
    } else  
p2:     i++;  
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- ▶ Multiple paths:
Systems of recurrence relations?
Abstract into a worst case path?

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 - Abstract into a worst case path?
- ▶ Non-determinism:
 - Abstract to the worst case? What is the worst case?
 - Cost does not have monotonic behavior!

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```

Cost depends on i, n, r

- ▶ Multiple paths:
Systems of recurrence relations?
Abstract into a worst case path?
- ▶ Non-determinism:
Abstract to the worst case? What is the worst case?
Cost does not have monotonic behavior!
- ▶ Cost can depend on multiple variables:
Pre-analysis, counter instrumentation, ...

Cost Relations

Extract and solve cost relations instead [Albert et al., 2007]

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```
while ( $i < n$ ) {
    if ( $r > 0$ ) {
         $i = \text{rnd}(n - 1)$ ;
         $r--$ ; 1 :  $wh(i, n, r) = 0$  { $i \geq n$ }
    } else
         $i++$ ; 2 :  $wh(i, n, r) = 1 + wh(i', n, r')$  { $i < n, r > 0, 0 \leq i' < n, r' = r - 1$ }
    }
    3 :  $wh(i, n, r) = 1 + wh(i', n, r)$  { $i < n, r \leq 0, i' = i + 1$ }
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         $r--$ ;  
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- ▶ Cost relations similar to recurrence relations with linear constraints

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- ▶ Cost relations similar to recurrence relations with linear constraints
- ▶ One **cost equation** per loop path

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```
p2:while ( $i < n$ ) {  
p2: if ( $r > 0$ ) {  
p2:    $i = \text{rnd}(n - 1)$ ; 1 :  $wh(i, n, r) = 0$     $\{i \geq n\}$   
p2:    $r--$ ;  
} else          2 :  $wh(i, n, r) = 1 + wh(i', n, r')$   $\{i < n, r > 0, 0 \leq i' < n, r' = r - 1\}$   
     $i++$ ;  
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```
p3:while (i<n) {  
p3: if (r>0) {  
    i=rnd(n-1); 1 : wh(i, n, r) = 0   {i ≥ n}  
    r--;  
} else          2 : wh(i, n, r) = 1 + wh(i', n, r') {i < n, r > 0, 0 ≤ i' < n, r' = r - 1}  
p3: i++;  
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 - applicability conditions for each cost equation
 - input/output behavior (possibly non-deterministic)

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```
while (i<n) {  
    if (r>0 && a[r]) {  
        i=rnd(n-1); 1 : wh(i, n, r) = 0 {i ≥ n}  
        r--;  
    } else 2 : wh(i, n, r) = 1 + wh(i', n, r') {i < n, r > 0, 0 ≤ i' < n, r' = r - 1}  
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```

CE 2 and 3 can interleave

- ▶ Cost relations similar to recurrence relations with linear constraints
- ▶ One **cost equation** per loop path
- ▶ Each cost equation defines a cost
- ▶ The constraints represent:
 - applicability conditions for each cost equation
 - input/output behavior (possibly non-deterministic)
- ▶ Not necessarily mutually exclusive

Properties of Cost Relations

Cost relations \approx subclass of constraint logic program

- ▶ Easy to extract
- ▶ Uniform treatment of loops and recursion
- ▶ Language independent (frontends for many higher PLs)
- ▶ Good for incremental solving (one loop/function at a time)

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Address main limitations in **solving** process

- ▶ Multi-phase loops
- ▶ Loops with resets
- ▶ Amortized cost

Two phases

① Control Flow Refinement

- Break down the control flow of each cost relation into a set of possible execution patterns (called chains)
- Prove termination
- Compute invariants and summaries for each pattern

② Bound Computation

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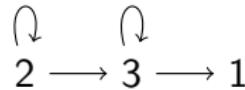
Control Flow Refinement: Phases and Chains

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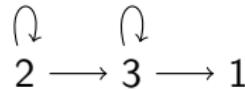
- Generate dependency (call) graph among the cost equations using their constraint sets (e.g., 2 $\not\rightarrow$ 1)



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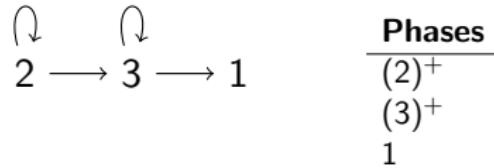
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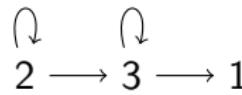
- ▶ Generate **dependency** (call) **graph** among the cost equations using their constraint sets (e.g., 2 $\not\rightarrow$ 1)
- ▶ Enumerate possible **execution patterns**
 - Each SCC forms a **phase**
iterative (e.g., $(2)^+$) or non-iterative (e.g., 1)



Control Flow Refinement: Phases and Chains

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```

- ▶ Generate **dependency** (call) **graph** among the cost equations using their constraint sets (e.g., 2 $\not\rightarrow$ 1)
- ▶ Enumerate possible **execution patterns**
 - Each SCC forms a **phase**
iterative (e.g., $(2)^+$) or non-iterative (e.g., 1)
 - **Chains** are possible sequences of phases in the dependency graph



Phases
$(2)^+$
$(3)^+$
1

Chains	
Non-terminating	Terminating
$(2)^+(3)^+$	$(2)^+(3)^+1$
$(3)^+$	$(3)^+1$
$(2)^+$	1

Control Flow Refinement: Termination

```
while (i<n) {   1 : wh(i, n, r) = 0   {i ≥ n}
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```

- ▶ Attempt to prove termination of each iterative phase with (lexicographic) ranking function

Phases	Ranking function	Chains	
		Non-terminating	Terminating
(3) ⁺	$n - i$	(2) ⁺ (3) ⁺	(2) ⁺ (3) ⁺ 1
(2) ⁺	r	(3) ⁺	(3) ⁺ 1
1	—	(2) ⁺	1

Control Flow Refinement: Termination

```
while (i < n) {   1 : wh(i, n, r) = 0   {i ≥ n}
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- ▶ Discard all non-terminating chains ending in a non-terminating phase

Phases	Ranking function	Chains	
		Non-terminating	Terminating
(3) ⁺	$n - i$	$\cancel{(2)^+ (3)^+}$	$(2)^+ (3)^{+1}$
(2) ⁺	r	$\cancel{(3)^+}$	$(3)^{+1}$
1	—	$\cancel{(2)^+}$	1

Control Flow Refinement: Termination

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while (i<n) { 1 : wh(i, n, r) = 0 {i ≥ n}
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Phases	Ranking function	Chains	
(3) ⁺	$n - i$	(2)⁺(3)⁺	
(2) ⁺	r	(3)⁺	
1	—	(2)⁺	1

Remaining chains describe all possible behavior

Propagate Information Forward and Backward along each Chain

Compute polyhedral invariants

- ▶ Backward propagation: necessary precondition for each chain
- ▶ Precondition permits further refinement of other cost equations
(example later)

Control Flow Refinement: Invariants and Propagation

Propagate Information Forward and Backward along each Chain

Compute polyhedral invariants

- ▶ Backward propagation: necessary precondition for each chain
- ▶ Precondition permits further refinement of other cost equations (example later)

Chains	Preconditions
$(2)^+(3)^+1$	$i < n \wedge r > 0$
$(3)^+1$	$i < n \wedge r \leq 0$
1	$i \geq n$

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② Bound Computation

- Bottom-up incremental approach
- Represent cost with data structure called cost structure
- Can infer and compose costs precisely and efficiently

Chain Evaluation Schema

$$\mathbf{1} : \text{wh}(i, n, r) = 0 \quad \{i \geq n\}$$

$$\mathbf{2} : \text{wh}(i, n, r) = 1 + \text{wh}(i', n, r') \quad \{i < n, r > 0, 0 \leq i' < n, r' = r - 1\}$$

$$\mathbf{3} : \text{wh}(i, n, r) = 1 + \text{wh}(i', n, r) \quad \{i < n, r \leq 0, i' = i + 1\}$$

Chain: $\mathbf{(2)}^+ \mathbf{(3)}^+ \mathbf{1}$

$$\text{wh}(i, n, r)$$

Chain Evaluation Schema

$$1 : wh(i, n, r) = 0 \quad \{i \geq n\}$$

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Chain: $(2)^+(3)^+ 1$

$$\underline{wh(i, n, r)}$$

→ CE 2

$$1 + wh(i_2, n_2, r_2)$$

Chain Evaluation Schema

$$1 : wh(i, n, r) = 0 \quad \{i \geq n\}$$

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$$1 + wh(i_2, n_2, r_2)$$

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$$1 + wh(i_j, n_j, r_j)$$

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Chain: $(2)^+(3)^+ 1$

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\rightarrow CE 2

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\rightarrow CE 2

\dots \rightarrow CE 2

$$1 + wh(i_j, n_j, r_j)$$

\rightarrow CE 2

$$1 + wh(i_f, n_f, r_f)$$

Chain Evaluation Schema

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$$1 + wh(i_f, n_f, r_f)$$

\rightarrow CE 3

\dots \rightarrow CE 3

$$1 + wh(i_{f_3}, n_{f_3}, r_{f_3})$$

Chain Evaluation Schema

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Chain: $(2)^+(3)^+ 1$

$$\frac{}{wh(i, n, r)}$$

\rightarrow CE 2

$$1 + wh(i_2, n_2, r_2)$$

\rightarrow CE 2
...

\rightarrow CE 2

$$1 + wh(i_j, n_j, r_j)$$

\rightarrow CE 2

$$1 + wh(i_f, n_f, r_f)$$

\rightarrow CE 3
...

\rightarrow CE 3

$$1 + wh(i_{f_3}, n_{f_3}, r_{f_3})$$

\rightarrow CE 1
0

Bound Computation Strategy

Bottom-up incremental approach

Chain: $(2)^+(3)^+1$

$wh(i, n, r)$

→ CE 2

$1 + wh(i_2, n_2, r_2)$

→ CE 2
...

→ CE 2

$1 + wh(i_j, n_j, r_j)$

→ CE 2

$1 + wh(i_f, n_f, r_f)$

→ CE 3
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→ CE 3

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→ CE 1
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Bound Computation Strategy

Bottom-up incremental approach

- ① Compute bound per cost equation without considering recursive calls

Chain: $(2)^+(3)^+1$

$\underline{wh(i, n, r)}$

$C_2 \rightarrow CE\ 2$

$C_2 - wh(i_2, n_2, r_2)$

$C_2 \rightarrow CE\ 2$

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$C_2 - wh(i_j, n_j, r_j)$

$C_2 \rightarrow CE\ 2$

$C_2 - wh(i_f, n_f, r_f)$

$\rightarrow CE\ 3$

$C_3 \rightarrow CE\ 3$

$\rightarrow CE\ 3$

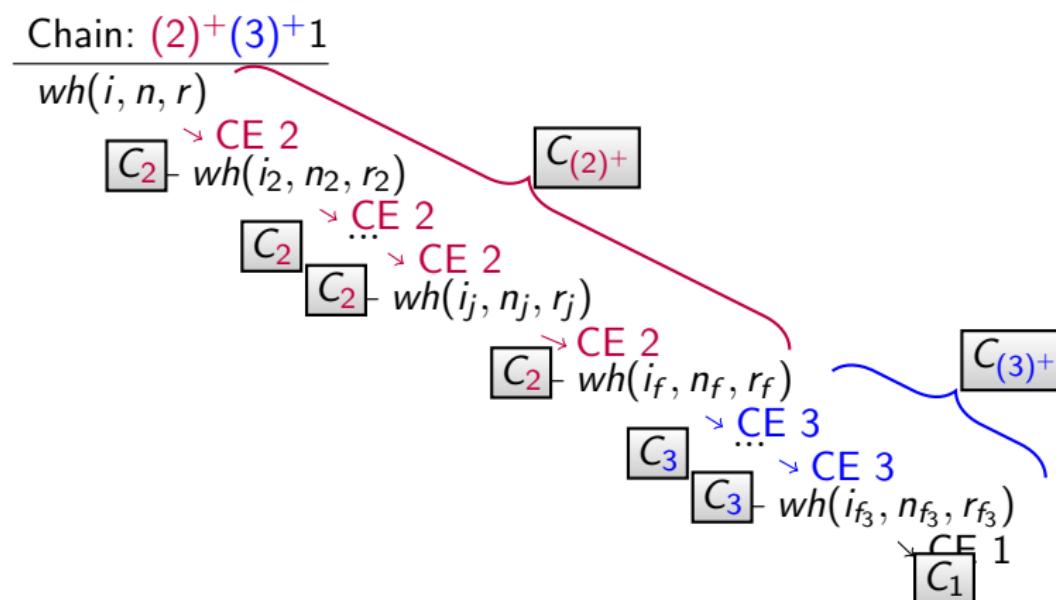
$C_3 - wh(i_{f_3}, n_{f_3}, r_{f_3})$

$\rightarrow CE\ 1$

Bound Computation Strategy

Bottom-up incremental approach

- ① Compute bound per cost equation without considering recursive calls
- ② Compute cost of each phase by composing the cost of their CEs

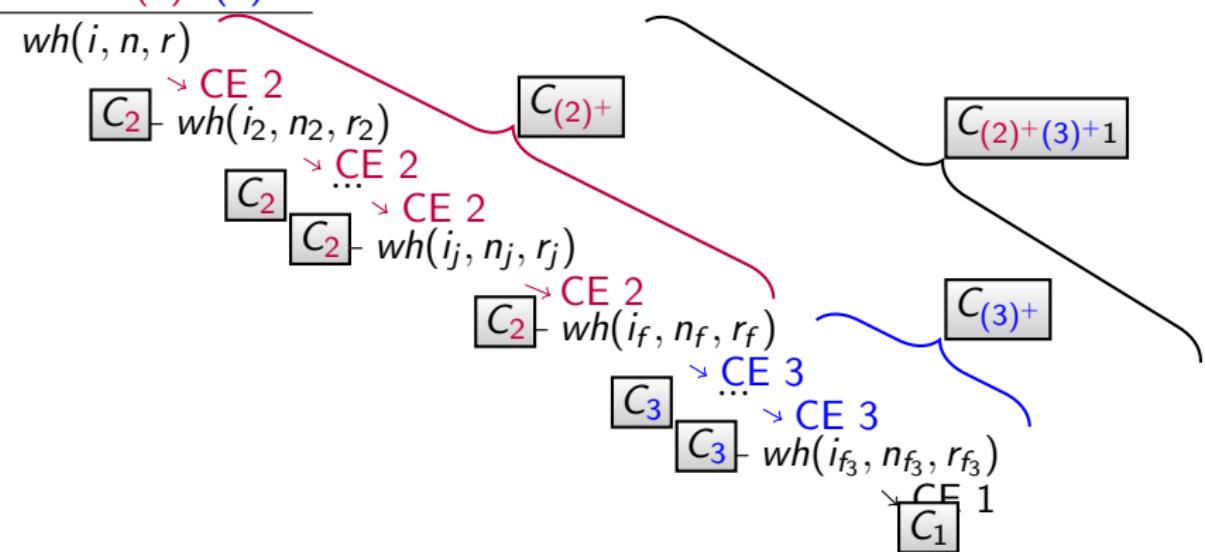


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Bottom-up incremental approach

- ① Compute bound per cost equation without considering recursive calls
- ② Compute cost of each phase by composing the cost of their CEs
- ③ Compose cost of phases to obtain the cost of whole chain

Chain: $(2)^+(3)^+1$



Cost Representation: Separation of Concerns

Decompose Symbolic Cost Expressions

- ① Simple expressions over (auxiliary) **intermediate variables (iv)**
- ② Constraints that bind intermediate variables to program/cost relation variables

```
while (i<n) {  
    if (r>0) {  
        i=rnd(n-1);  
        r--;  
    } else  
        i++;  
}
```

To represent the upper bound $|r| + |n|$:

- ① $\mathbf{iv}_1 + \mathbf{iv}_2$ ② $\{\mathbf{iv}_1 \leq |r|, \mathbf{iv}_2 \leq |n|\}$

$|x|$ abbreviates $\max(x, 0)$

Cost Representation: Separation of Concerns

Decompose Symbolic Cost Expressions

- ① Simple expressions over (auxiliary) **intermediate variables (iv)**
- ② Constraints that bind intermediate variables to program/cost relation variables

Advantages:

- ▶ Consider multiple bound candidates

```
while (x>0 && y>0) {  
    x--;  
    y--;  
}
```

$$\boxed{\mathbf{iv}_1 \quad \{ \mathbf{iv}_1 \leq |x|, \mathbf{iv}_1 \leq |y| \}}$$

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- ② Constraints that bind intermediate variables to program/cost relation variables

Advantages:

- ▶ Consider multiple bound candidates
- ▶ Facilitates incremental bound inference and composition

```
while (x>0 && *)  
    x--;  
    //exit value x'  
while (x>0)  
    x--;
```

Cost of first loop:

$$\mathbf{iv}_1 \quad \{\mathbf{iv}_1 \leq |x - x'|\}$$

Total cost:

$$\mathbf{iv}_1 + \mathbf{iv}_2 \quad \{\mathbf{iv}_1 + \mathbf{iv}_2 \leq |x|\}$$

Cost of second loop:

$$\mathbf{iv}_2 \quad \{\mathbf{iv}_2 \leq |x'|\}$$

Cost Representation: Cost Structures

Represent cost with **cost structures** $\langle E, IC, FC \rangle$

- ▶ E is the **main cost expression**
 - Linear expression over **intermediate variables** (**iv**)

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IC (**intermediate**) **non-final constraints** bind sums of intermediate variables to expressions over other intermediate variables

- can be non-linear and contain max and min
- permit to represent non-linear bounds, e.g.:

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We will not use non-final constraints in this presentation

Computing Cost Structures: Cost Equations

$$1 : wh(i, n, r) = 0 \quad \{i \geq n\}$$

$$2 : wh(i, n, r) = 1 + wh(i', n, r') \quad \{i < n, r > 0, 0 \leq i' < n, r' = r - 1\}$$

$$3 : wh(i, n, r) = 1 + wh(i', n, r) \quad \{i < n, r \leq 0, i' = i + 1\}$$

- ▶ Do not take into account the cost of recursive calls
- ▶ Use cost equation definition

$$C_2 : \langle \mathbf{iv}_1, \emptyset, \{\mathbf{iv}_1 \leq 1\} \rangle$$

$$C_3 : \langle \mathbf{iv}_2, \emptyset, \{\mathbf{iv}_2 \leq 1\} \rangle$$

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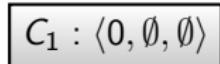
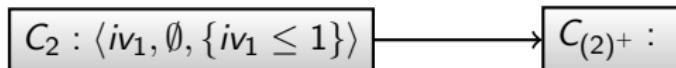
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- ▶ Assume CE 2 is evaluated $\#c_2$ times in phase $(2)^+$



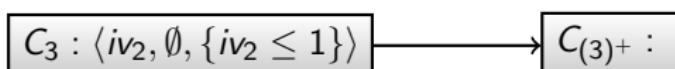
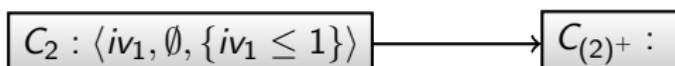
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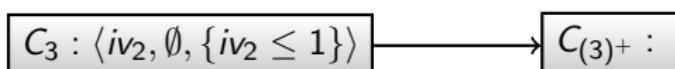
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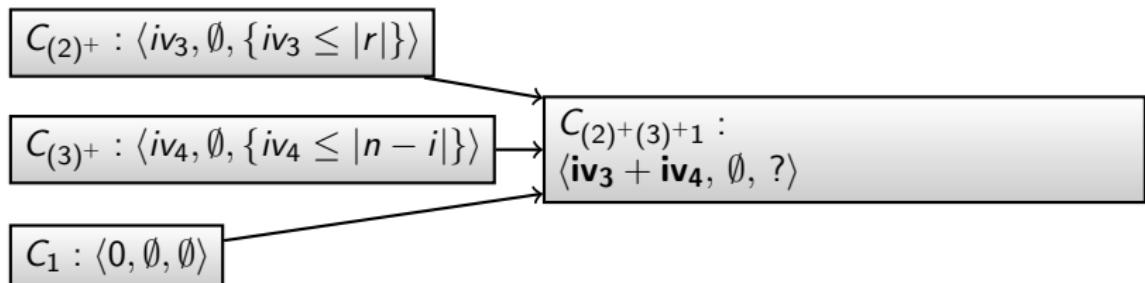
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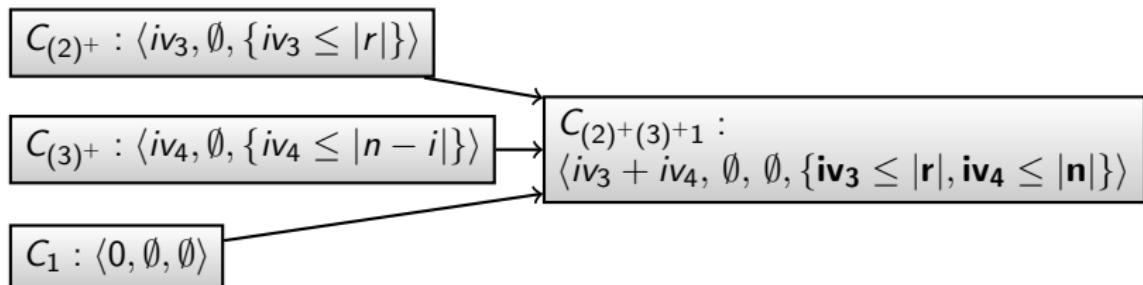
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- ▶ Add cost of the phases in a chain
- ▶ To obtain bounds: express constraints in terms of **initial** variables
 - in phase (2)⁺ variable i is set to arbitrary value between 0 and $n - 1$
 - worst case: expression $n - i$ in phase (3)⁺ has value n



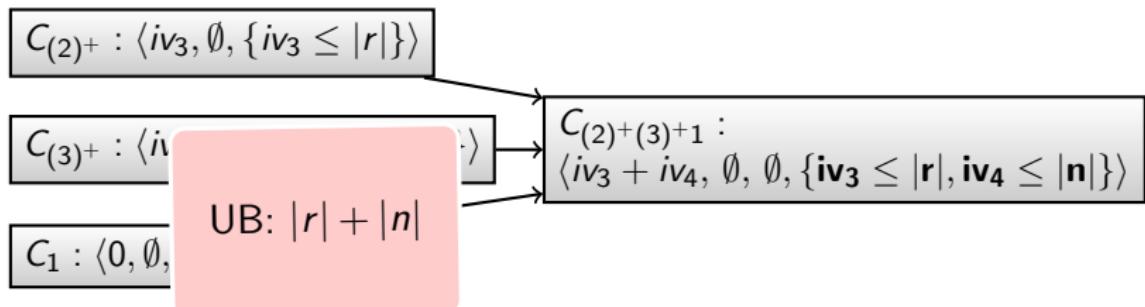
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Amortized cost

```
while (!!=[])
  s=Cons(head(l),s);
  if (*)
    s=popSome(s);
  l=tail(l);
}
popSome(List s) {
  if (s==[] || *)
    return s;
  else
    popSome(tail(s));
}
```

- ▶ While-loop adds elements of list l to list s
 - In worst case loop can iterate $|l|$ times
- ▶ Occasionally, `popSome()` removes elements from s
 - In worst case `popSome()` is called $|l|$ times
- ▶ All elements on s not already present at start come from l :
 - Total cost is $\mathcal{O}(|l|)$ and not $\mathcal{O}(|l|^2)$
- ▶ Example involves **amortized** cost

Cost Relation Abstraction, Return Values

```
while (!==[]) {  
    s=Cons(head(l),s);  
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- ▶ Lists are abstracted to their length

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    if (*)                return s;  
    s=popSome(s);          else  
    l=tail(l);             popSome(tail(s));  
}  
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- ▶ Lists are abstracted to their length
- ▶ Essential to consider the return value of `popSome()`

Recall Control Flow Refinement: popSome()

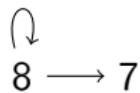
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Phases

$\overline{(8)^+}$

7



8 → 7

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Phases	
$(8)^+$	
7	
Chains	
Non-terminating	Terminating
$(8)^+$	$(8)^+7$
	7

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Phases		Ranking functions
Chains		
Non-terminating	Terminating	
(8) ⁺	s	
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Phases	Ranking functions		Invariants/Summaries
(8) ⁺	s	7	
Chains			
Non-terminating		Terminating	$s \geq 1 \wedge s > so$
(8)⁺		(8) ⁺ 7	$s = so$
		7	

- Now invariants constitute **summaries** (inclusion of return variable)

Refinement Propagation

Propagate control flow refinement from `popSome()` to `whA`

- ▶ Substitute calls to `popSome()` by calls to refined chains of `popSome()`
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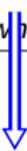
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$$5.1 : whA(l, s) = 1 + popSome[7](s'', s') + whA(l', s') \\ \{l \geq 1, s \geq 0, s'' = s + 1, l' = l - 1, s'' = s'\}$$

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Again refine resulting CEs to obtain chains $(5.1 \vee 5.2 \vee 6)^+ 4$ and 4

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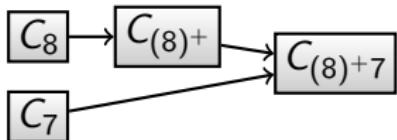
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Again, performed **bottom-up** (C_c denotes chain c)

popSome()



Bound Computation

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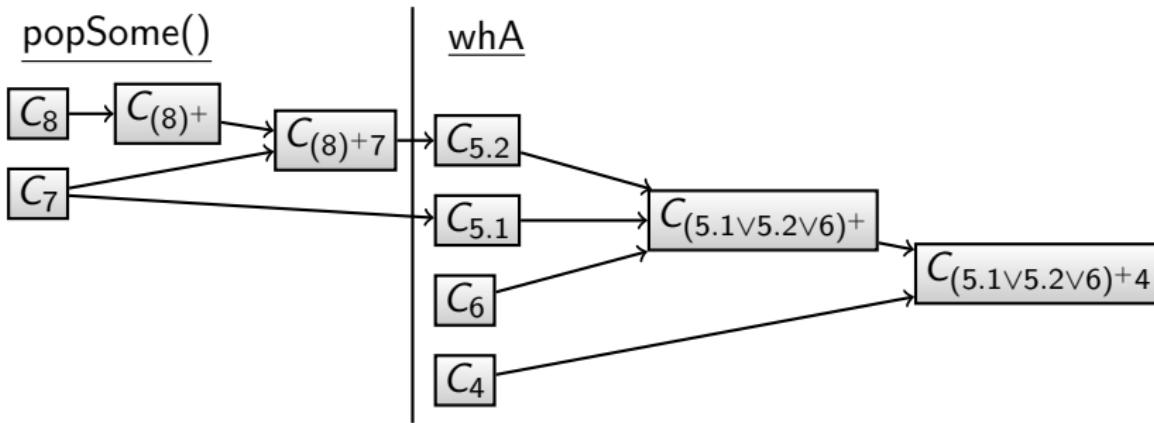
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First Step: Bound Computation of popSome()

- ▶ List s might not be completely consumed in $\text{popSome}()$:
 - to obtain amortized cost, express $C_{(8)^+}$ in terms of s , so and s_f , so_f

$$\begin{array}{c} \text{Chain: } (8)^+ 7 \\ \hline \text{popSome}(s, so) \\ \quad \xrightarrow{\text{CE 8}} 1 + \text{popSome}(s_2, so_2) \\ \quad \quad \quad \xrightarrow{\text{CE 8}} \dots \\ \quad \quad \quad \quad \quad \xrightarrow{\text{CE 8}} 1 + \text{popSome}(s_f, so_f) \\ \quad \quad \quad \quad \quad \quad \xrightarrow{\text{CE 7}} 0 \end{array}$$

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$$C_8 : \langle iv_1, \emptyset, \{iv_1 \leq 1\} \rangle$$

$$C_7 : \langle 0, \emptyset, \emptyset \rangle$$

First Step: Bound Computation of popSome()

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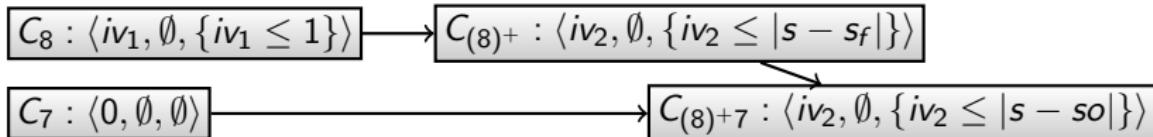


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 - # of iterations of $(8)^+$ bound by difference initial/final value of s
- ▶ Final value of s ($= s_f$) returned and unmodified in $(8)^+$:
 $s_f = so_f = so$

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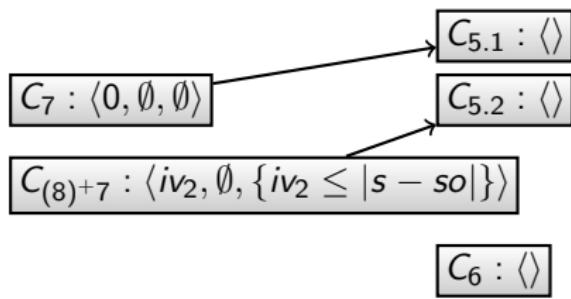


Second Step: (1) Bound Computation of CEs of whA()

$$5.1 : \text{whA}(l, s) = 1 + \text{popSome}[7](s'', s') + \text{whA}(l', s') \\ \{l \geq 1, s \geq 0, s'' = s + 1, l' = l - 1, s'' = s'\}$$

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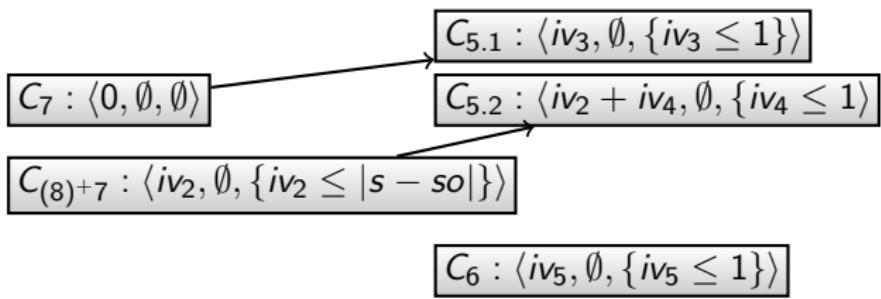
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- Add cost of calls computed in first step to cost relation of caller

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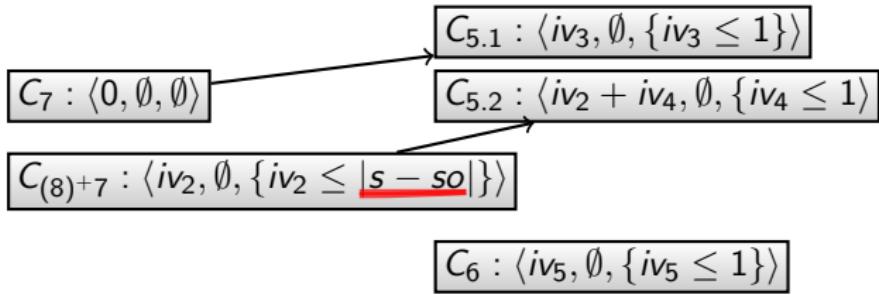
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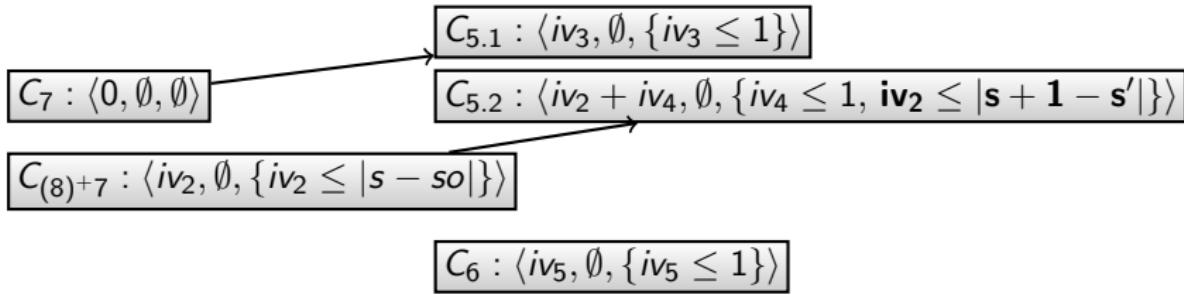
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- ▶ Add cost of calls computed in first step to cost relation of caller
- ▶ $|s - so|$ corresponds to $|s'' - s'|$ in CE 5.2
- ▶ Express bounds in terms of initial variables and variables of recursive call (to obtain amortized cost)

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$$C_{5.2} : \langle iv_2 + iv_4, \emptyset, \{iv_4 \leq 1, iv_2 \leq |s + 1 - s'| \} \rangle$$

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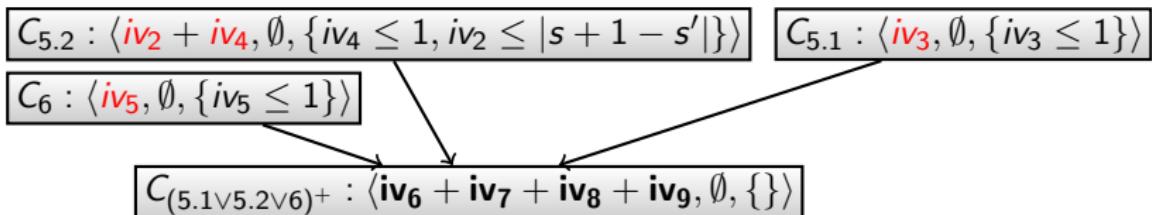
- Define intermediate variables representing the various sums:

$$iv_6 = \sum_{j=1}^{\#c_{5.2}} (iv_{2j}) \quad iv_7 = \sum_{j=1}^{\#c_{5.1}} (iv_{3j}) \quad iv_8 = \sum_{j=1}^{\#c_{5.2}} (iv_{4j}) \quad iv_9 = \sum_{j=1}^{\#c_6} (iv_{5j})$$

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- Use **heuristics** to obtain constraints for these variables:

- **Inductive sum** for iv_6 : obtain symbolic linear expression satisfying:

$$\varphi_{5.2} \Rightarrow L(i, n, r) \geq (\mathbf{s} + \mathbf{1} - \mathbf{s}') \wedge L(i, n, r) \geq (\mathbf{s} + \mathbf{1} - \mathbf{s}') + L(i', n', r')$$

$$5.1 : whA(I, s) = 1 + \text{popSome}[7](s'', s') + whA(I', s') \\ \{I \geq 1, s \geq 0, s'' = s + 1, I' = I - 1, s'' = s'\} = \varphi_{5.1}$$

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Second Step: (2) Bound Computation of Phase of whA()

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- Solution: $\mathbf{l} + \mathbf{s}$ remains unchanged in CEs 5.1 and 6

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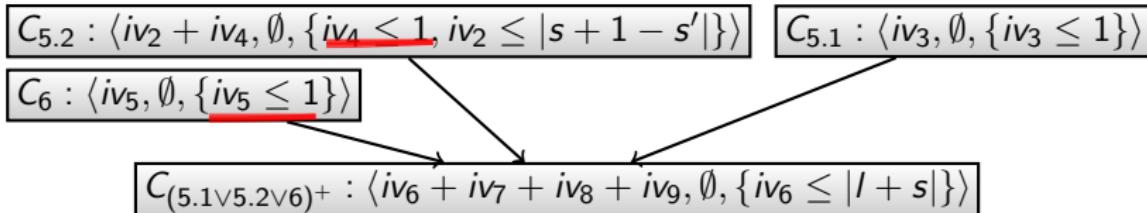
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- Same bound obtained for iv_8, iv_9

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- Same bound obtained for iv_8 , iv_9 and even **sum of all three**

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- Same bound obtained for iv_8 , iv_9 and even **sum of all three**

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UB: $|I + s| + |I|$

$+ 1 - s' | \} \rangle$

$C_{5.1} : \langle iv_3, \emptyset, \{iv_3 \leq 1\} \rangle$

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Implementation and Experiments

- ▶ All techniques implemented in **CoFLoCo** (\Rightarrow complexity competition)
- ▶ Automatically obtained precise bounds for executable, concurrent model (in ABS) of a distributed genetic algorithm
- ▶ **Essential features** to deal with realistic code:
 - Control flow refinement of cost relations
 - Ability to maintain multiple bound candidates in a cost structure
- ▶ In many applications amortized bounds very useful:
code over (functional) data structures
- ▶ **Drawback** of control flow refinement: exponential blow-up possible
 - Employ path/chain merging to mitigate that problem

Control Flow Refinement

- ▶ Separate bounds for computation paths with differing behavior
- ▶ Derive explicit preconditions for these: document, optimize

Propagation of Invariants/Summaries, Bottom-Up Strategy

- ▶ Strengthen application conditions
- ▶ Take return values into account: amortized cost

Separation of Concerns in Cost Structures, Intermediate Variables

- ▶ Maintain multiple candidates for bounds
- ▶ Enable incremental bound inference
- ▶ Plug in induction heuristics to infer closed bounds
- ▶ Represent non-linear bounds
- ▶ Handle loops with resets (see paper)

- ▶ Overcame existing limitations of resource analysis with cost relations:
 - Multi-phase loops
 - Loops with resets
 - Amortized cost
- ▶ Increase precision of derived bounds
- ▶ Presented techniques are language independent:
imperative and functional programs
- ▶ Can also infer (best case) lower bounds
- ▶ Extendable to logarithmic or exponential bounds

References

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