

Reachability for Termination*

4th Austria-Japan Summer Workshop **on Term Rewriting**

Akihisa Yamada (University of Innsbruck)

* Supported by Austrian Science Fund (FWF) Y-757

Reachability for Termination of Term Rewriting

Akihisa Yamada (University of Innsbruck)

* Supported by Austrian Science Fund (FWF) Y-757

Reachability in the Dependency Framework for Termination of Term Rewriting

Akihisa Yamada (University of Innsbruck)

* Supported by Austrian Science Fund (FWF) Y-757

Terminology proposal

$s \rightarrow_{\mathcal{R}}^* t$ t is ~~reachable~~ from s
reached

$\exists \theta. s\theta \rightarrow_{\mathcal{R}}^* t\theta$ t is **reachable** from s [Sternagel & Sternagel '16]
 $(s \hookrightarrow_{\mathcal{R}} t)$

Example:

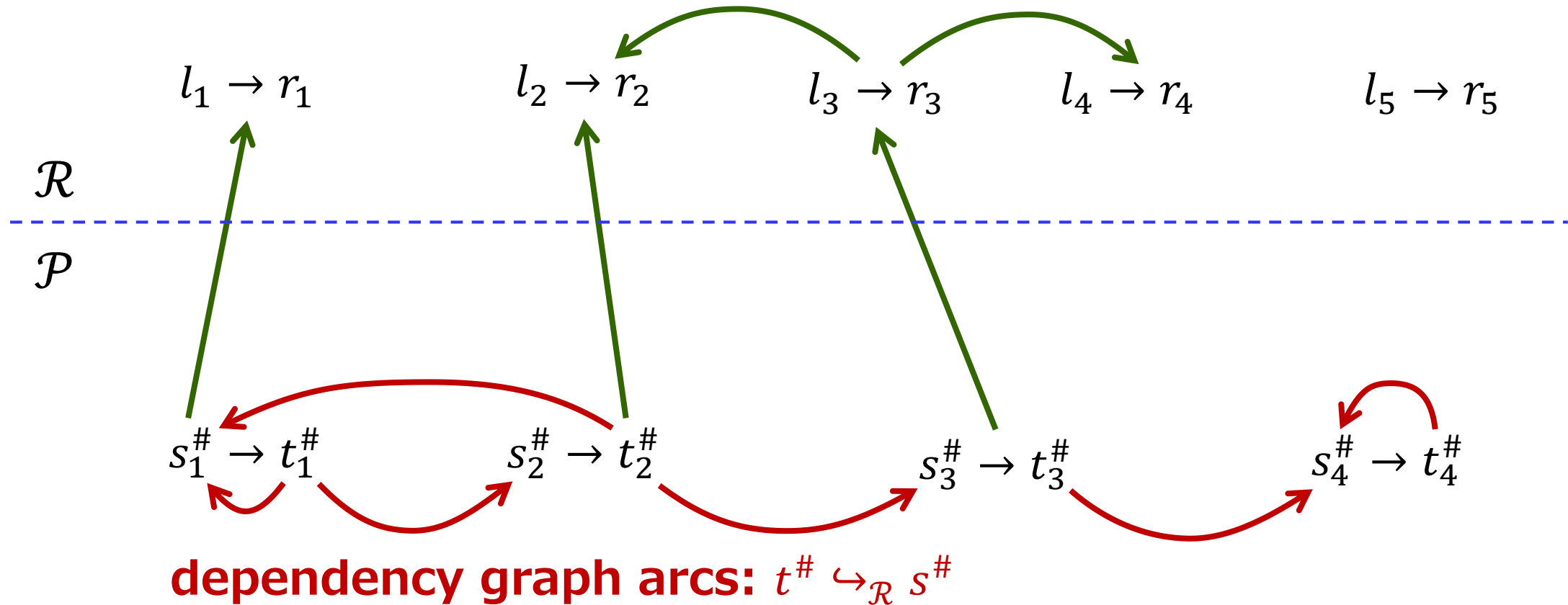
Q: $\text{start}(\textit{some_input}) \hookrightarrow_{\mathcal{R}} \text{error}(\textit{some_code})?$

A: yes, $\text{start}(5) \rightarrow_{\mathcal{R}}^* \text{error}(\text{DIV0})$

Reachability in DP framework

usable: $\exists r' \sqsubseteq r. r' \hookrightarrow_{\mathcal{R}} l$

new



Usable rules (before)

Theorem ([Hirokawa & Middeldorp '04 / Giesl+ '05]):

$$\phi(s) := \bigwedge_{f(s_1, \dots) \trianglelefteq_{\pi} s} \bigwedge_{f(l_1, \dots) \rightarrow r \in \mathcal{R}} f(l_1, \dots) \rightarrow r \in \mathcal{U}$$

If $\phi(\text{rhds } \mathcal{P}) \wedge \phi(\text{rhds } \mathcal{U})$, then one can ignore $\mathcal{R} \setminus \mathcal{U}$

Theorem ([Sternagel & Thiemann '10]): same for

$$\phi(s) := \bigwedge_{f(s_1, \dots) \trianglelefteq_{\pi} s} \bigwedge_{f(l_1, \dots) \rightarrow r \in \mathcal{R}} \text{tcap}(s_1) \sim_{\text{unif}} l_1, \dots \Rightarrow f(l_1, \dots) \rightarrow r \in \mathcal{U}$$

Usable rules via reachability

Theorem (new): Usable rules technique applies for

$$\phi(s) := \bigwedge_{f(s_1, \dots) \triangleq_{\pi} s} \bigwedge_{f(l_1, \dots) \rightarrow r \in \mathcal{R}} s_1 \xrightarrow{\mathcal{R}} l_1, \dots \Rightarrow f(l_1, \dots) \rightarrow r \in \mathcal{U}$$

Proof:

I changed original proofs until Isabelle somehow accepted.
So it must be true.


TODO: Understand why the proof works

Estimating reachability

■ Requirements

- efficiency: can't be as hard as termination proving
- completeness: if t is reachable from s , then it must say so
- soundness (only for nontermination)

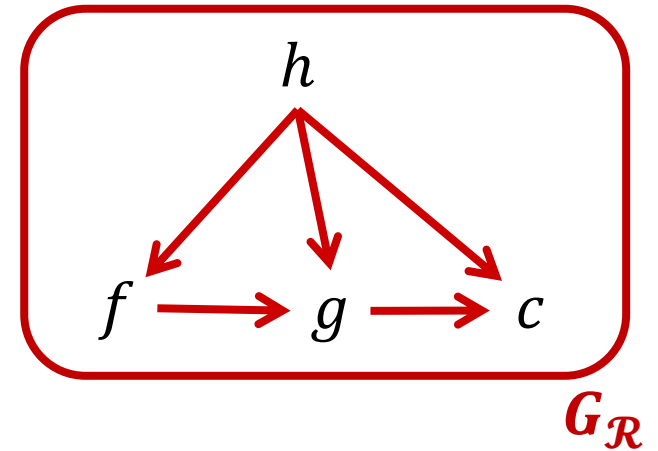
■ Proposed solutions

-  □ symbol transition graph
 - generalized TCAP-unifiability
 - combination
-

Symbol transition graph (in NaTT & TTT2)

$$\mathcal{R} = \begin{cases} f(\dots) \rightarrow g(\dots) \\ g(\dots) \rightarrow c(\dots) \\ h(\dots) \rightarrow x \end{cases}$$

- $c(\dots) \rightarrow_{\mathcal{R}}^* t \Rightarrow t$ must be $c(\dots)$
- $g(\dots) \rightarrow_{\mathcal{R}}^* t \Rightarrow t$ must be $g(\dots)$ or $c(\dots)$
- $f(\dots) \rightarrow_{\mathcal{R}}^* t \Rightarrow t$ must be $f(\dots)$ or $g(\dots)$ or $c(\dots)$
- $h(\dots) \rightarrow_{\mathcal{R}}^* t \Rightarrow$ don't know



Theorem (to be formalized):

Define graph $G_{\mathcal{R}} = \langle \mathcal{F}, \supset \rangle$ s.t. $f \supset g$ whenever $f(\dots) \rightarrow g(\dots) \in \mathcal{R}$ or $f(\dots) \rightarrow x \in \mathcal{R}$.

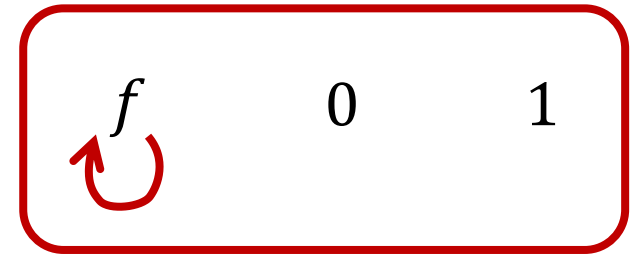
Then $f \supset^* g$ is a complete estimation of $f(\dots) \hookrightarrow_{\mathcal{R}} g(\dots)$

Symbol transition graph' (only in TTT2)

- Example:

$$\mathcal{R} = \{ f(0,1,x) \rightarrow f(x,x,x) \}$$

$$\mathcal{P} = \{ f^\#(0,1,x) \rightarrow f^\#(x,x,x) \}$$



$G_{\mathcal{R}}$

reduced to " $\exists x. x \hookrightarrow_{\mathcal{R}} 0 \wedge x \hookrightarrow_{\mathcal{R}} 1 \wedge x \hookrightarrow_{\mathcal{R}} x'$ "

... UNSAT, since 0 and 1 have no common ancestor in $G_{\mathcal{R}}$


TODO: efficient algorithm for common ancestors (in graph)

Estimating reachability

■ Requirements

- efficiency: can't be as hard as termination proving
- completeness: if t is reachable from s , then it must say so
- soundness (only for nontermination)

■ Proposed solutions

-  □ symbol transition graph
 - generalized TCAP-unifiability
 - combination
-

TCAP-unifiability [Giesl+'05]

- complete estimation of reachability:

$$s \hookrightarrow_{\mathcal{R}} t \implies \text{tcap}_{\mathcal{R}}(s) \sim_{\text{unif}} t$$

Implementation in NaTT: $\text{tcap}(s) \sim_{\text{unif}} t \implies$

- $s \in \mathcal{V}$ or
- $t \in \mathcal{V}$ or
- $s = f(s_1, \dots, s_n)$ and
 - $t = f(t_1, \dots, t_n)$ and $\forall i. \text{tcap}(s_i) \sim_{\text{unif}} t_i$, or
 - $\exists f(l_1, \dots, l_n) \rightarrow r \in \mathcal{R}. \forall i. \text{tcap}(s_i) \sim_{\text{unif}} l_i$

TCAP-unifiability [Giesl+'05]

- complete estimation of reachability:

$$s \hookrightarrow_{\mathcal{R}} t \implies \text{tcap}_{\mathcal{R}}(s) \sim_{\text{unif}} t$$

Implementation in NaTT: $\text{tcap}(s) \sim_{\text{unif}} t \implies$

- $s \in \mathcal{V}$ or
- $t \in \mathcal{V}$ or
- $s = f(s_1, \dots, s_n)$ and
 - $t = f(t_1, \dots, t_n)$ and $\forall i. \text{tcap}(s_i) \sim_{\text{unif}} t_i$, or
 - $\exists f(l_1, \dots, l_n) \rightarrow r \in \mathcal{R}. \forall i. \text{tcap}(s_i) \sim_{\text{unif}} l_i$

TCAP-unifiability reformulated

- complete estimation of reachability:

$$s \hookrightarrow_{\mathcal{R}} t \implies s \hookrightarrow_{\mathcal{R},1} t$$

Definition: $s \hookrightarrow_{\mathcal{R},1} t$ iff

- $s \in \mathcal{V}$ or
- $t \in \mathcal{V}$ or
- $s = f(s_1, \dots, s_n)$ and
 - $t = f(t_1, \dots, t_n)$ and $\forall i. s_i \hookrightarrow_{\mathcal{R},1} t_i$, or
 - $\exists f(l_1, \dots, l_n) \rightarrow r \in \mathcal{R}. \forall i. s_i \hookrightarrow_{\mathcal{R},1} l_i$

if $s \hookrightarrow_{\mathcal{R}} l \rightarrow r \in \mathcal{R}$ then give up

valid only if $r \hookrightarrow_{\mathcal{R}} t$

k -step look-ahead (only in NaTT)

- complete estimation of reachability:

$$s \hookrightarrow_{\mathcal{R}} t \implies s \hookrightarrow_{\mathcal{R},k} t$$

Definition: $s \hookrightarrow_{\mathcal{R},k} t$ iff

- $s \in \mathcal{V}$ or
- $t \in \mathcal{V}$ or
- $s = f(s_1, \dots, s_n)$ and

- $t = f(t_1, \dots, t_n)$ and $\forall i. s_i \hookrightarrow_{\mathcal{R},k} t_i$, or

- $\exists f(l_1, \dots, l_n) \rightarrow r \in \mathcal{R}. \forall i. s_i \hookrightarrow_{\mathcal{R},k} l_i$ and $r \hookrightarrow_{\mathcal{R},k-1} t$

if $s \hookrightarrow_{\mathcal{R}} l \rightarrow r \in \mathcal{R}$, check $r \hookrightarrow_{\mathcal{R}} t$


- Experiments: ($k = 8$, empirically chosen)
+10 YESs (all known, from MNZ_10)

Estimating reachability

■ Requirements

- efficiency: can't be as hard as termination proving
- completeness: if t is reachable from s , then it must say so
- soundness (only for nontermination)

■ Proposed solutions

- symbol transition graph
 -  □ generalized TCAP-unifiability
 - combination
-

Combination (straightforward)

Definition: $s \hookrightarrow_{\mathcal{R},k} t$ iff

- $s \in \mathcal{V}$ or
- $t \in \mathcal{V}$ or
- $s = f(s_1, \dots, s_n)$ and
 - $t = f(t_1, \dots, t_n)$ and $\forall i. s_i \hookrightarrow_{\mathcal{R},k} t_i$, or
 - if $k = 0$ then use $G_{\mathcal{R}}$
 - else $\exists f(l_1, \dots, l_n) \rightarrow r \in \mathcal{R}. \forall i. s_i \hookrightarrow_{\mathcal{R},k} l_i$ and $r \hookrightarrow_{\mathcal{R},k-1} t$

Conclusion

- (Almost) exact usable rules via reachability
 - New reachability estimation
 - symbol transition graph
 - k-step look-ahead (generalizing TCAP-unifiability)
 - TODO:
 - missing formalizations/implementations/evaluations
 - use substitution
 - combine with CTRS techniques [Sternagel & Sternagel '16]?
-